

Analog & Digital Communication Systems

(5th Semester E&TC)



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Communication System

Energy of a signal:

$x(t)$
(fun. of time)

Energy of $x(t)$, $E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt$

Example: $x(t) = \begin{cases} e^{-t}, & t \geq 0 \\ 0, & t < 0 \end{cases} = e^{-t} u(t)$

$$E_x = \int_0^{\infty} e^{-2t} dt = \left. \frac{e^{-2t}}{-2} \right|_0^{\infty} = \frac{1}{2} [1 - 0] = \frac{1}{2}$$

If $E_x < \infty$, then $x(t)$ is termed as an energy signal.

Power of a signal:

Power of $x(t)$, $P_x = \lim_{\tilde{T} \rightarrow \infty} \frac{1}{\tilde{T}} \int_{\tilde{T}} |x(t)|^2 dt$

Energy in a window of size \tilde{T}

$$= \lim_{\tilde{T} \rightarrow \infty} \frac{\text{Energy in a window of size } \tilde{T}}{\tilde{T}}$$

If $P_x < \infty$, then $x(t)$ is termed as a power signal.

If $x(t)$ is an Energy signal.

$$P_x = \lim_{\tilde{T} \rightarrow \infty} \frac{1}{\tilde{T}} \int_{\tilde{T}} |x(t)|^2 dt$$

$$\leq \lim_{\tilde{T} \rightarrow \infty} \frac{1}{\tilde{T}} \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$= \lim_{\tilde{T} \rightarrow \infty} \frac{E_x}{\tilde{T}} = 0$$

$$\Rightarrow P_x \leq 0$$

$$\Rightarrow P_x = 0 \quad (\because P_x \text{ is a +ve qty})$$

Power of an Energy signal is 0.

If $x(t)$ is a power signal, Energy in a window of size \tilde{T}

$$\approx P_x \tilde{T}$$

\Rightarrow Total energy = $\lim_{\tilde{T} \rightarrow \infty}$ Energy in a window of size \tilde{T}

$$= \lim_{\tilde{T} \rightarrow \infty} P_x \tilde{T} = \infty$$

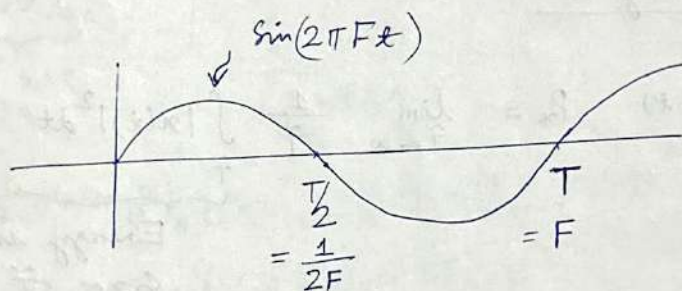
\therefore Energy of a power signal is ∞ .

Periodic signals are power signals.

Periodic signals

$x(t)$ is periodic if

$$x(t) = x(t + kT), \quad \forall t, k \in \mathbb{Z}$$



$F \rightarrow$ frequency

$T = \frac{1}{F}$ (Fundamental Period)

$$\sin(2\pi Ft + kT) = \sin\left(2\pi Ft + 2\pi FkT\right) = \sin(2\pi Ft + 2\pi k)$$

$$= \sin(2\pi Ft)$$

$A \sin(2\pi Ft + \phi)$: Periodic with Period = $\frac{1}{F}$

\downarrow Amplitude \uparrow Phase

Power of a periodic signal:

Let T be the period of periodic signal.

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x(t)|^2 dt$$

Chose $\tilde{T} = mT$

$$m \rightarrow \infty \Rightarrow mT \rightarrow \infty$$

$$\Rightarrow \tilde{T} \rightarrow \infty$$

$$P_x = \lim_{m \rightarrow \infty} \frac{1}{mT} \int_{-\frac{mT}{2}}^{\frac{mT}{2}} |x(t)|^2 dt$$

Energy in m periods = m Energy in a period

$$= \lim_{m \rightarrow \infty} \frac{1}{mT} m \int_{-\frac{T}{2}}^{\frac{T}{2}} |x(t)|^2 dt$$

$$P_x = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} |x(t)|^2 dt$$

= Energy in a window of size T

Example:

$$x(t) = A \cos(2\pi Ft), \quad T = \frac{1}{F}$$

$$\text{Power, } P = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} A^2 \cos^2(2\pi Ft) dt$$

$$\frac{1}{T} \times 2 \int_0^{\frac{T}{2}} A^2 \cos^2(2\pi Ft) dt = \frac{A^2}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \frac{1 + \cos(4\pi Ft)}{2} dt$$

$$= \frac{2A^2}{T} \int_0^{\frac{T}{2}} \frac{1 + \cos(4\pi Ft)}{2} dt$$

$$= \frac{A^2}{T} \int_0^{\frac{T}{2}} 1 + \cos(4\pi Ft) dt$$

$$= \frac{A^2}{T} \left\{ \frac{T}{2} + \frac{\sin(4\pi Ft)}{4\pi F} \Big|_0^{\frac{T}{2}} \right\}$$

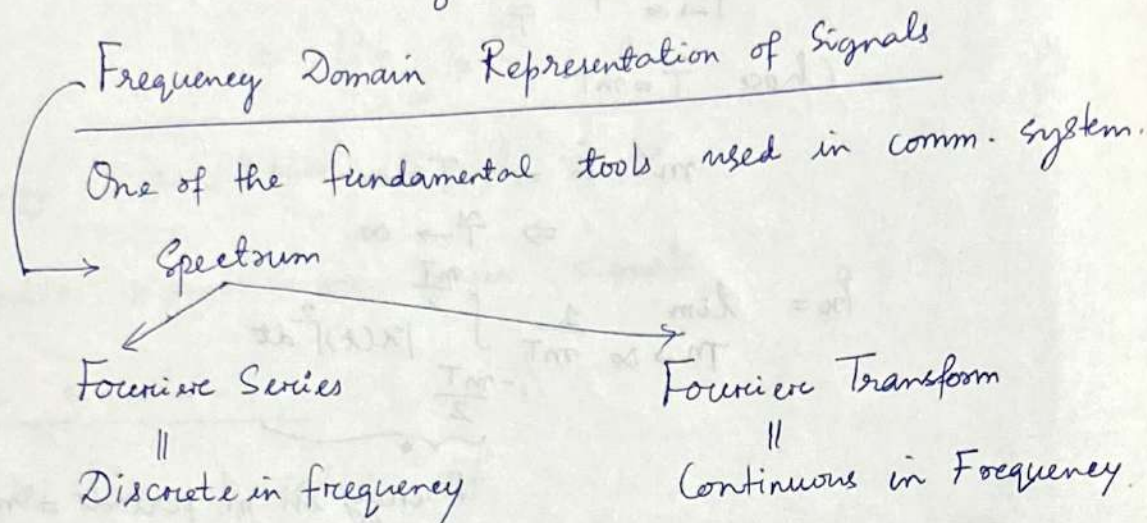
$$= \frac{A^2}{2}$$

$$= \frac{A^2}{2} + \frac{A^2}{2} \frac{1}{8\pi F} \cdot 0$$

$$= \frac{A^2}{2}$$

Power of $A \cos(2\pi Ft + \phi)$ is $\frac{A^2}{2}$.

{ Power depends on Amplitude, independent of Phase }



Fourier Series

Defined for a periodic signal $x(t)$

$x(t)$: Periodic with period T .

$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t}$$

$F_0 = \frac{1}{T}$: Fundamental Frequency of $x(t)$.

C_k : k^{th} F.S. coefficient. (or) Coefficient of k^{th} Harmonic.

$$e^{j2\pi k F_0 t} = \underbrace{\cos(2\pi k F_0 t) + j \sin 2\pi k F_0 t}_{\text{Complex sinusoid}} \rightarrow k^{\text{th}} \text{ Harmonic}$$

Complex sinusoid.

$kF_0 \rightarrow$ Multiple of Fundamental frequency F_0

Linear Combination

$$\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) e^{-j2\pi l F_0 t} dt = C_l$$

$$= \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \left(\sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t} \right) e^{-j2\pi l F_0 t} dt$$

$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} C_k \cdot \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} e^{j2\pi(k-l) F_0 t} dt$$

$$\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} e^{j2\pi(k-l) F_0 t} dt$$

$$= \begin{cases} \frac{1}{T} \cdot T = 1 & k=l \\ \frac{1}{T} \frac{e^{j2\pi(k-l) F_0 t}}{j2\pi(k-l) F_0} \Big|_{-\frac{T}{2}}^{\frac{T}{2}} & k \neq l \end{cases}$$

$$\begin{aligned} & \cos \pi(k-l) + j \sin \pi(k-l) \\ & - \cos \pi(k-l) + j \sin \pi(k-l) \\ & = j2 \sin \pi(k-l) \\ & = 0, (\because k \neq l) \end{aligned}$$

$$= \frac{1}{T} \frac{1}{j2\pi(k-l) F_0} \left\{ e^{j\pi(k-l)} - e^{-j\pi(k-l)} \right\}$$

$$= \frac{1}{T} \frac{1}{2\pi(k-l) F_0} \times 0 \quad \begin{matrix} \Delta\phi = \text{Phase Difference} \\ = 2\pi(k-l) \end{matrix}$$

$$= 0$$

$$e^{j2\pi k F_0 t} \quad e^{j2\pi l F_0 t} \quad [l, k \in \mathbb{Z}]$$

Different Harmonics are orthogonal.

$$\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) \cdot y^*(t) dt = 0$$

$$= \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} e^{j2\pi k F_0 t} \cdot \left(e^{j2\pi l F_0 t} \right)^* dt = 0$$

$$\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) e^{-j2\pi l F_0 t} dt = \sum_{k=-\infty}^{\infty} C_k \underbrace{\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} e^{j2\pi(k-l) F_0 t} dt}_{= \begin{cases} 1, & k=l \\ 0, & k \neq l \end{cases}}$$

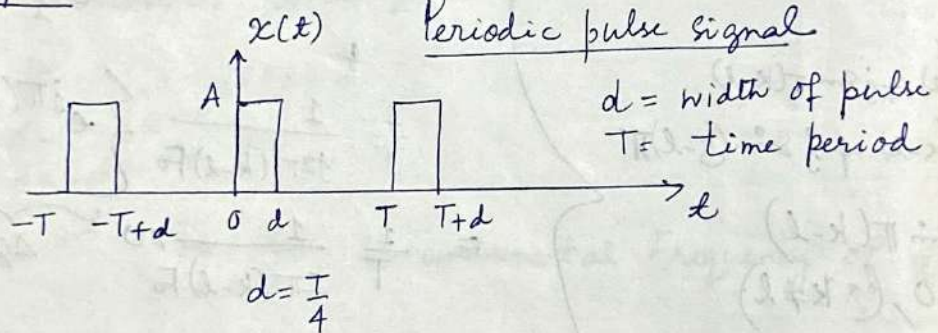
$$= \sum_{k=-\infty}^{\infty} C_k \delta(k-l)$$

$$= C_l$$

$$\frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) \cdot e^{-j2\pi l F_0 t} dt = C_l$$

↑
Coefficient of l^{th} harmonic.

Example



$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t}$$

$$F_0 = \frac{1}{T}$$

$k, l \in \mathbb{Z}$

$$C_l = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) e^{-j2\pi l F_0 t} dt$$

(over a period)
⇒ t to t+T

$$C_l = \frac{1}{T} \int_0^T x(t) e^{-j2\pi l F_0 t} dt$$

$$= \frac{1}{T} \int_0^{T/4} A \cdot e^{-j2\pi l F_0 t} dt$$

$$= \frac{A}{T} \left. \frac{e^{-j2\pi l F_0 t}}{-j2\pi l F_0} \right|_0^{T/4}$$

$$= \frac{A}{2\pi l j} \left[1 - e^{-j2\pi l \frac{T}{4}} \right]$$

$$\Rightarrow C_l = \frac{A}{2\pi l j} e^{-j\frac{\pi l}{4}} \left[e^{+j\frac{\pi l}{4}} - e^{-j\frac{\pi l}{4}} \right]$$

$$\Rightarrow \boxed{C_l = \frac{A}{\pi l} e^{-j\frac{\pi l}{4}} \sin\left[\frac{\pi l}{4}\right]}$$

l^{th} F.S. coefficient ($l \neq 0$)

$$\therefore C_l = \begin{cases} \frac{A}{4}, & l=0 \\ \frac{A}{\pi l} e^{-j\frac{\pi l}{4}} \sin\left(\frac{\pi l}{4}\right), & l \neq 0 \end{cases}$$

$$|C_l| = \left| \frac{A}{\pi l} \cdot e^{-j\frac{\pi l}{4}} \sin\left(\frac{\pi l}{4}\right) \right|$$

$$\Rightarrow |C_l| = \left| \frac{A}{\pi l} \sin\left(\frac{\pi l}{4}\right) \right| : \text{Magnitude Spectrum.}$$

Power of Periodic Signal:

For a periodic signal $x(t)$,

$$P_x = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t}$$

$$x^*(t) = \sum_{m=-\infty}^{\infty} C_m^* e^{-j2\pi m F_0 t}$$

$$\begin{aligned}
 \text{Power} = P_x &= \frac{1}{T} \int_0^T x(t) \cdot x^*(t) dt \\
 &= \frac{1}{T} \int_0^T \left(\sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t} \right) \left(\sum_{m=-\infty}^{\infty} C_m^* e^{-j2\pi m F_0 t} \right) dt \\
 &= \frac{1}{T} \int_0^T \sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} C_k C_m^* e^{+j2\pi(k-m)F_0 t} dt \\
 &= \sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} C_k \cdot C_m^* \underbrace{\frac{1}{T} \int_0^T e^{j2\pi(k-m)F_0 t} dt}_{= \delta(k-m)} \\
 &= \begin{cases} 1, & k=m \\ 0, & k \neq m \end{cases}
 \end{aligned}$$

$$= \sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} C_k C_m^* \delta(k-m)$$

$$P_x = \sum_{k=-\infty}^{\infty} C_k \cdot C_k^* = \sum_{k=-\infty}^{\infty} |C_k|^2$$

$$\frac{1}{T} \int_0^T |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |C_k|^2$$

Parseval's Theorem.

Power in terms of spectrum.

Power of periodic signal

for a periodic signal $x(t)$

$$P = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

$$= \sum_{k=-\infty}^{\infty} |C_k|^2$$

$$= \sum_{k=-\infty}^{\infty} |C_k|^2$$

Fourier Transform (F.T.)

Spectrum of an aperiodic continuous time signal $x(t)$

Consider an aperiodic signal $x(t)$. Its Fourier Transform is,

$$X(F) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j2\pi Ft} dt$$

$F =$ Frequency

Time Domain

$x(t)$

Frequency Domain

$X(F)$

Fourier Transform Pair.

$X(F) \rightarrow$ Complex

$|X(F)| \rightarrow$ Magnitude Spectrum.

$\angle X(F) \rightarrow$ Phase Spectrum.

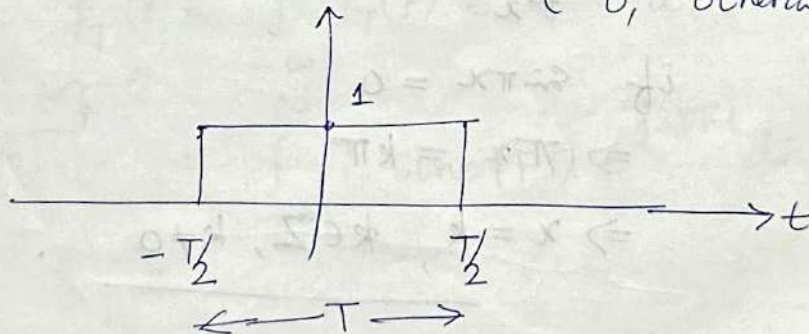
Given $X(F)$,

IFT :

$$x(t) = \int_{-\infty}^{\infty} X(F) \cdot e^{j2\pi Ft} dF$$

Example :-

$$x(t) = p_T(t) = \begin{cases} 1, & |t| \leq T/2 \\ 0, & \text{otherwise} \end{cases}$$



$$X(F) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi Ft} dt$$

$$P_T(F) = \int_{-T/2}^{T/2} 1 \cdot e^{-j2\pi Ft} dt$$

$$= 2 \int_0^{T/2} \cos(2\pi Ft) dt$$

$$= 2 \left. \frac{\sin(2\pi Ft)}{2\pi F} \right|_0^{T/2}$$

$$\boxed{P_T(F) = \frac{\sin(\pi FT)}{\pi F}}$$

$$= T \frac{\sin(\pi FT)}{\pi FT}$$

$$\boxed{P_T(F) = T \operatorname{sinc}(FT)}$$

sinc function

$$\operatorname{sinc} x = \frac{\sin \pi x}{\pi x}$$

$$\lim_{x \rightarrow 0} \operatorname{sinc}(x) = \lim_{x \rightarrow 0} \frac{\sin \pi x}{\pi x} = 1$$

$$\operatorname{sinc} x = \frac{\sin \pi x}{\pi x} = 0$$

$$\text{if } \sin \pi x = 0$$

$$\Rightarrow \pi x = k\pi$$

$$\Rightarrow x = k, \quad k \in \mathbb{Z}, \quad k \neq 0$$

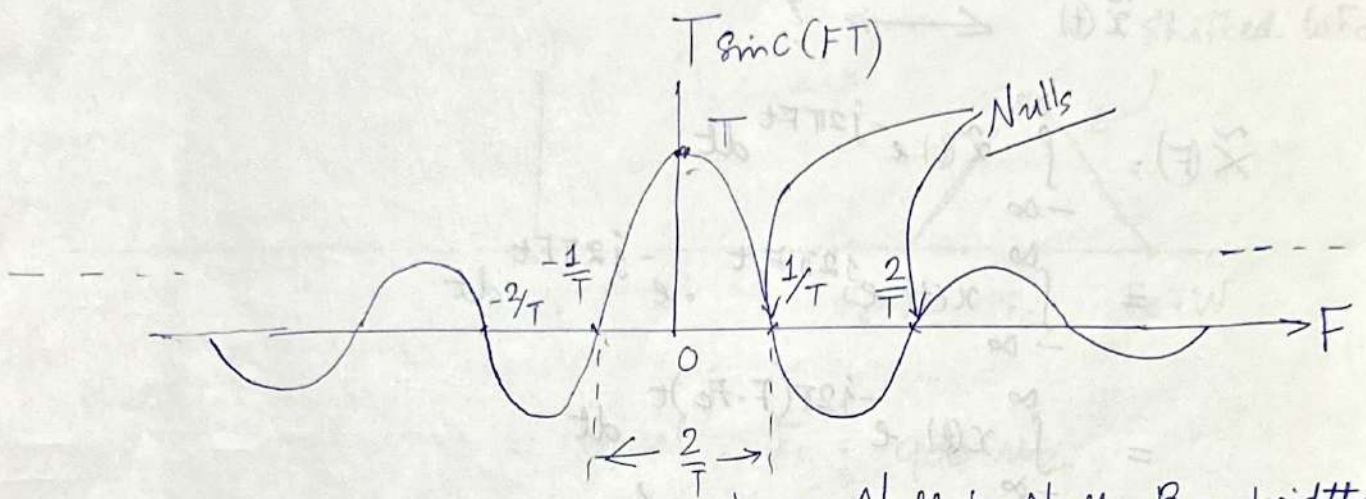
$$P_T(F) = T \operatorname{sinc}(FT)$$

$$\text{At } F=0, T \operatorname{sinc}(0) = T$$

$$\text{At } F = \frac{k}{T}, T \operatorname{sinc}(k) = 0$$

$$T \operatorname{sinc} FT = \frac{T \sin \pi FT}{\pi FT}$$

Looks like $\sin(x)$ except amplitude is decreasing due to $\frac{1}{F}$.



Null to Null Bandwidth.

$$P_T(t) \longleftrightarrow P_T(F)$$

$$T \operatorname{sinc}(FT)$$

$$P_T(t) = \int_{-\infty}^{\infty} P_T(F) e^{j2\pi Ft} dF$$

$$= \int_{-\infty}^{\infty} T \operatorname{sinc}(FT) e^{j2\pi Ft} dF$$

Time Domain
Pulse.

Modulation Property of F.T. :

$$\tilde{x}(t) = x(t) e^{j2\pi F_c t}$$

Modulated Signal. Signal Carrier

complex sinusoid

$F_c = \text{Carrier Frequency}$

$$x(t) \longleftrightarrow X(F)$$

$$\tilde{x}(t) \longleftrightarrow ?$$

$$\begin{aligned}\tilde{X}(F) &= \int_{-\infty}^{\infty} \tilde{x}(t) e^{-j2\pi Ft} dt \\ &= \int_{-\infty}^{\infty} x(t) e^{j2\pi F_c t} \cdot e^{-j2\pi Ft} dt \\ &= \int_{-\infty}^{\infty} x(t) e^{-j2\pi(F-F_c)t} dt \\ &= X(F-F_c)\end{aligned}$$

$$\tilde{X}(F) = X(F-F_c)$$

F.T. of Modulated Signal

Fourier Transform of ~~$x(t)$~~ , i.e. $X(F)$ shifted by F_c .

Modulation in Time = Shift in frequency by F_c

Carrier Frequency

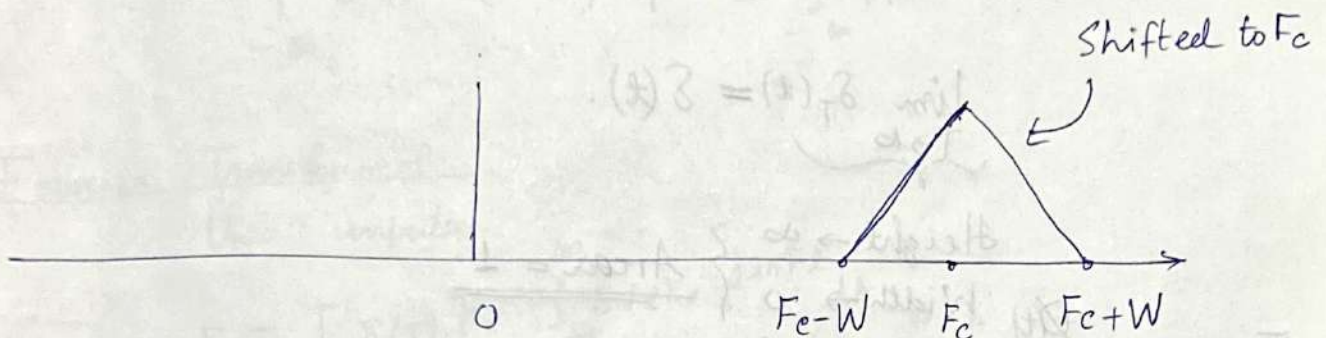
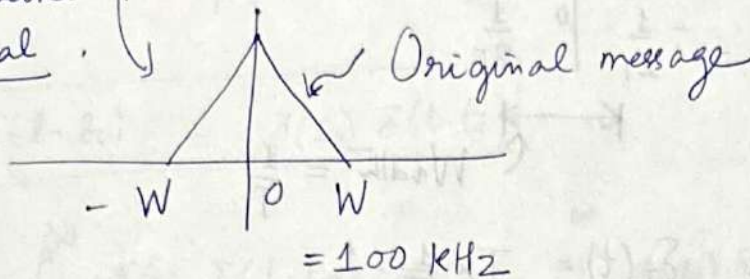
Example :

GSM Comm. System.

Global System
for Mobile

Dominant Wireless
Technology.

Baseband
Signal



Typical, $F_c = 900 \text{ MHz}$
(or) 1800 MHz

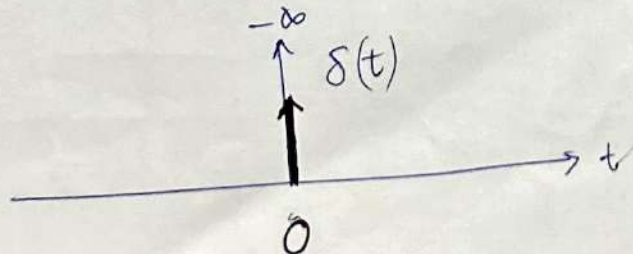
$$F_c \gg \text{Message Bandwidth } (W)$$

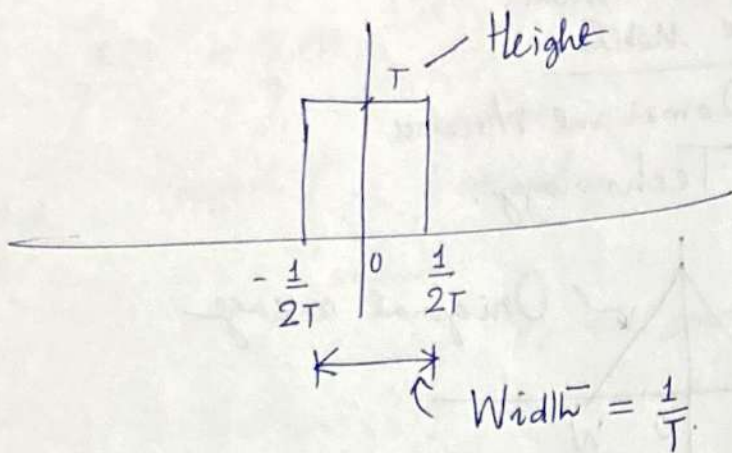
Unit impulse Function :

Dirac Delta Function.

$$\delta(t) = \begin{cases} 0, & t \neq 0 \\ \text{Undefined}, & t = 0 \end{cases}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$





$$\text{Area } \delta_T(t) = T \times \frac{1}{T} = 1$$

$$\lim_{T \rightarrow \infty} \delta_T(t) = \delta(t)$$

$$\left. \begin{array}{l} \text{Height} \rightarrow \infty \\ \text{Width} \rightarrow 0 \end{array} \right\} \underline{\underline{\text{Area} = 1}}$$

For any continuous function $\phi(t)$ at $t=0$,

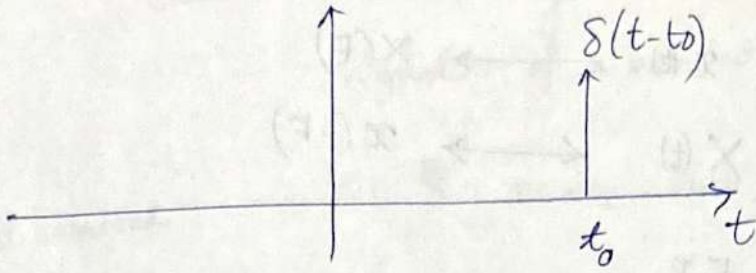
$$\boxed{\phi(t) \delta(t) = \phi(0) \delta(t)}$$

This operation picks value of $\phi(t)$ at $t=0$

Further, $\phi(t) \Big|_{t=0}$

$$\begin{aligned} \int_{-\infty}^{\infty} \phi(t) \delta(t) dt &= \int_{-\infty}^{\infty} \phi(0) \delta(t) dt \\ &= \phi(0) \cdot \int_{-\infty}^{\infty} \delta(t) dt = \phi(0) \end{aligned}$$

$$\delta(t-t_0) = 0, \text{ if } t \neq t_0$$



$$\boxed{\phi(t) \delta(t-t_0) = \phi(t_0) \delta(t-t_0)}$$

$$\int_{-\infty}^{\infty} \phi(t) \delta(t-t_0) dt = \int_{-\infty}^{\infty} \phi(t_0) \delta(t-t_0) dt = \phi(t_0)$$

Fourier Transform of
Unit impulse.

$$\text{F.T. } [\delta(t)] = \int_{-\infty}^{\infty} \delta(t) e^{-j2\pi Ft} dt = 1$$

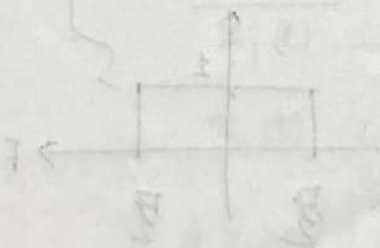
$$\boxed{\delta(t) \longleftrightarrow 1, -\infty < F < \infty}$$

$$\begin{aligned} \text{F.T. } [\delta(t-t_0)] &= \int_{-\infty}^{\infty} \delta(t-t_0) \cdot e^{-j2\pi Ft} dt \\ &= e^{-j2\pi Ft_0} \end{aligned}$$

$$\boxed{\delta(t-t_0) \longleftrightarrow e^{-j2\pi Ft_0}}$$

Shifted impulse

Complex sinusoid.



Duality Property of F.T. :

$$x(t) \longleftrightarrow X(F)$$

$$X(t) \longleftrightarrow x(-F)$$

From Inverse F.T.,

$$x(t) = \int_{-\infty}^{\infty} X(F) e^{j2\pi Ft} dF$$

Interchange t & F

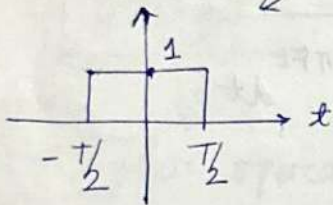
$$x(F) = \int_{-\infty}^{\infty} X(t) \cdot e^{j2\pi Ft} dt$$

$$\Rightarrow x(-F) = \int_{-\infty}^{\infty} X(t) \cdot e^{-j2\pi Ft} dt = FT [X(t)]$$

Example :-

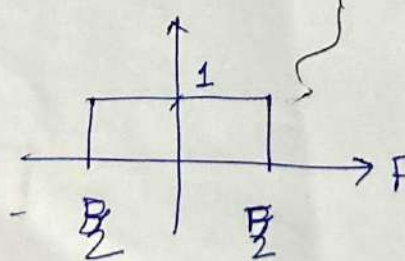
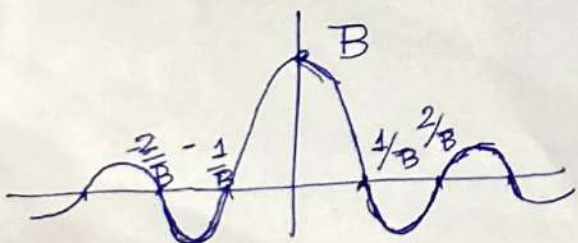
$$p_T(t) \longleftrightarrow T \text{sinc}(FT)$$

$$= T \frac{\sin(\pi FT)}{\pi FT}$$



$$= \begin{cases} 1, & |t| \leq T/2 \\ 0, & \text{otherwise} \end{cases}$$

$$B \text{sinc}(Bt) \longleftrightarrow p_B(-F)$$



Window in frequency

Very important in comm. system

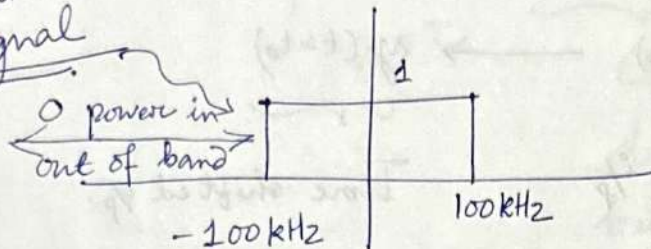
To generate Band Limited Signal.

Example

GSM: Need to generate a band limited signal of bandwidth = 100 kHz

$$W = \frac{B}{2} = 100 \text{ kHz} \Rightarrow B = 200 \text{ kHz}$$

Band Limited Signal



$$B \operatorname{sinc}(Bt) = 200 \text{ kHz} \operatorname{sinc}(200 \text{ kHz } t)$$

GSM \rightarrow Band Limited signal

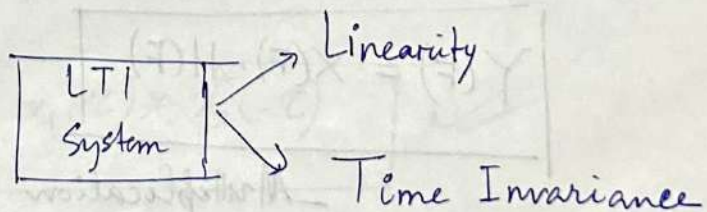
$$B_{\frac{1}{2}} = 100 \text{ kHz}$$

$$200 \text{ kHz} \operatorname{sinc}(200 \text{ kHz } t) \longleftrightarrow \underbrace{P}_{200 \text{ kHz}}(F)$$

Band Limited Signal

TRANSMISSION of a signal through a linear system:

Consider a signal $x(t)$ given as an input to an LTI system.



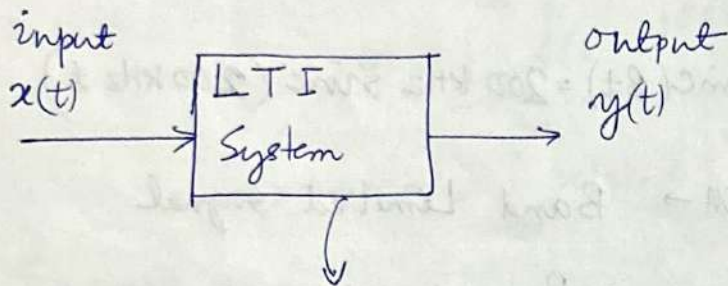
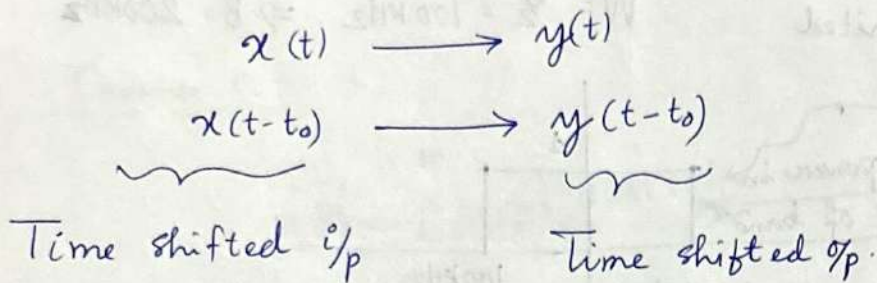
$$\frac{\%p}{x_1(t)} \longrightarrow \frac{\%p}{y_1(t)}$$

$$x_2(t) \longrightarrow y_2(t)$$

$$ax_1(t) + bx_2(t) \longrightarrow ay_1(t) + by_2(t)$$

Linear combination of i/p's produce same linear combination of corresponding o/p's.

TIME INVARIANCE



Impulse Response

$h(t)$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

Convolution Operator

$$= \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau$$

$$Y(F) = X(F) \cdot H(F)$$

Multiplication in Frequency Domain.

CROSS-CORRELATION

Consider $x_1(t)$, ~~$x_1(t)$~~ $x_2(t)$

Cross-correlation function

$$r_{12}(\tau) = \int_{-\infty}^{\infty} x_1(t) x_2^*(t-\tau) dt$$

lag = τ

Characterizes the extent/
degree of similarity
between $x_1(t)$, $x_2(t)$ for a shift
of τ .

$$r_{12}(\tau) = \int_{-\infty}^{\infty} x_1(t) x_2^*[-(\tau-t)] dt$$

$$\tilde{x}_2(t) = x_2(-t)$$

$$\tilde{x}_2(\tau-t) = x_2(t-\tau)$$

$$\Rightarrow \tilde{x}_2^*(\tau-t) = x_2^*(t-\tau)$$

$$= \int_{-\infty}^{\infty} x_1(t) \tilde{x}_2^*(\tau-t) dt$$

$$\begin{aligned} &= x_1(t) * \tilde{x}_2(t) \\ &= x_1(t) * x_2(-t) \end{aligned}$$

$$r_{12}(\tau) = x_1(\tau) * x_2^*(\tau)$$

$$r_{12}(\tau) = x_1(\tau) * x_2^*(-\tau)$$

$$\downarrow$$

$$S_{12}(F) = X_1(F) \cdot X_2^*(F)$$

$$FT[x_2^*(-t)]$$

$$x_2(t) \leftrightarrow X_2(F)$$

$$X_2(F) = \int_{-\infty}^{\infty} x_2(t) e^{-j2\pi Ft} dt$$

$$X_2^*(F) = \int_{-\infty}^{\infty} x_2^*(t) e^{j2\pi Ft} dt$$

$$\tilde{t} = -t$$

$$\Rightarrow dt = -d\tilde{t}$$

$$X_2^*(F) = \int_{\infty}^{-\infty} x_2^*(-\tilde{t}) e^{-j2\pi F\tilde{t}} (-d\tilde{t})$$

$$= \int_{-\infty}^{\infty} x_2^*(-\tilde{t}) e^{-j2\pi F\tilde{t}} d\tilde{t}$$

$x_1(\tau) * x_2^*(-\tau) \leftrightarrow X_1(F) \cdot X_2^*(F)$
$\uparrow \qquad \qquad \qquad \uparrow$
$r_{12}(\tau) \qquad \qquad \qquad S_{12}(F)$

Cross-correlation

AUTO-CORRELATION

$$x_1(\tau) * x_2(-\tau) \longleftrightarrow X_1(F) \cdot X_2^*(F)$$

$$r_{11}(\tau) = x_1(\tau) * x_1^*(-\tau)$$

$$S_{11}(F) = X_1(F) \cdot X_1^*(F)$$

$$S_{11}(F) = |X_1(F)|^2$$

Consider, $x(t)$

$$\begin{aligned} \text{Autocorrelation, } R_{xx}(\tau) &= \int_{-\infty}^{\infty} x(t) \cdot x^*(t-\tau) dt \\ &= x(\tau) * x^*(-\tau) \end{aligned}$$

$$S_{xx}(F) = X(F) X^*(F) = |X(F)|^2$$

F.T. of Auto-correlation.

$$R_{xx}(\tau) \longleftrightarrow S_{xx}(F)$$

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} S_{xx}(F) e^{j2\pi F\tau} dF$$

$$R_{xx}(0) = \int_{-\infty}^{\infty} S_{xx}(F) \cdot dF$$

$$R_{xx}(0) = \int_{-\infty}^{\infty} |X(F)|^2 dF$$

$$\text{Also, } R_{xx}(0) = \int_{-\infty}^{\infty} x(t) x^*(t) dt$$

$$= \int_{-\infty}^{\infty} |x(t)|^2 dt$$

Energy of $x(t)$.

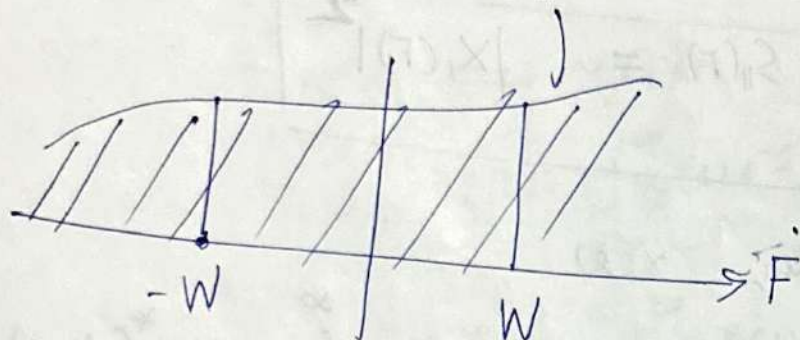
$$R_{xx}(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} |X(F)|^2 dF$$

$$S_{xx}(F) = |X(F)|^2$$

Parseval's Relation.

Total Energy of the signal $x(t)$

$$|X(F)|^2 = S_{xx}(F)$$



Energy in the band $[-W, W]$

$$= \int_{-W}^W S_{xx}(F) dF = \int_{-W}^W |X(F)|^2 dF$$

$S_{xx}(F)$: Energy spread or

$$= |X(F)|^2$$

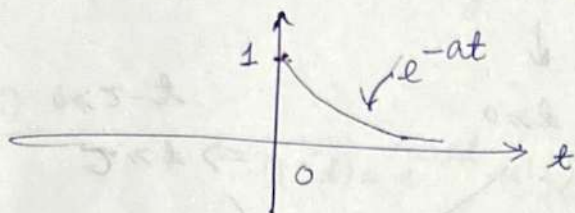
Distribution of energy of $x(t)$
in frequency Domain.

Energy Spectral Density (ESD) of $x(t)$.

Example:
(Auto-correlation)

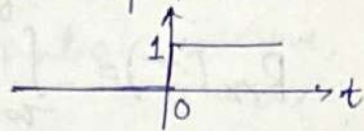
$$x(t) = e^{-at} u(t)$$

$$= \begin{cases} e^{-at}, & t \geq 0 \\ 0, & t < 0 \end{cases}$$



$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

unit step function



Auto-correlation of $e^{-at} u(t)$

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} x(t) \cdot x^*(t-\tau) dt$$

$$= \int_{-\infty}^{\infty} x(t) \cdot x(t-\tau) dt \quad [\text{For real } x(t)]$$

$$= \int_{-\infty}^{\infty} e^{-at} u(t) \cdot e^{-a(t-\tau)} u(t-\tau) dt$$

\downarrow $t \geq 0$ \downarrow $t \geq \tau$
 \searrow \swarrow
 $t \geq \tau$

$$= \int_{\tau}^{\infty} e^{-at} \cdot e^{-a(t-\tau)} dt$$

$$= \int_{\tau}^{\infty} e^{-2at} e^{a\tau} dt$$

$$= e^{a\tau} \left. \frac{e^{-2at}}{-2a} \right|_{\tau}^{\infty}$$

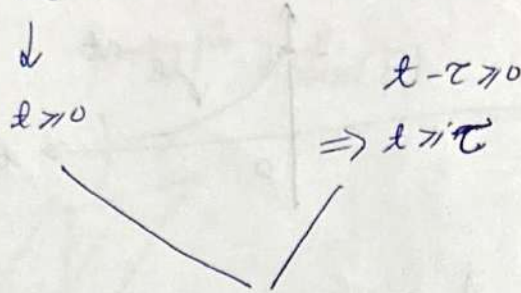
$$= \frac{e^{a\tau}}{2a} [e^{-2a\tau} - 0] = \frac{e^{-a\tau}}{2a}$$

Auto-correlation of $e^{-at} u(t)$

$$R_{xx}(\tau) = \frac{e^{-a\tau}}{2a} \quad [\tau \geq 0]$$

of $\tau \leq 0$

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} e^{-at} u(t) \cdot e^{-a(t-\tau)} u(t-\tau) dt$$



$t \geq 0$ ($\because \tau$ is $-ve$)

$$R_{xx}(\tau) = \int_0^{\infty} e^{-at} \cdot e^{-a(t-\tau)} dt$$

$$= \int_0^{\infty} e^{-2at} e^{a\tau} dt$$

$$= e^{a\tau} \left. \frac{e^{-2at}}{-2a} \right|_0^{\infty}$$

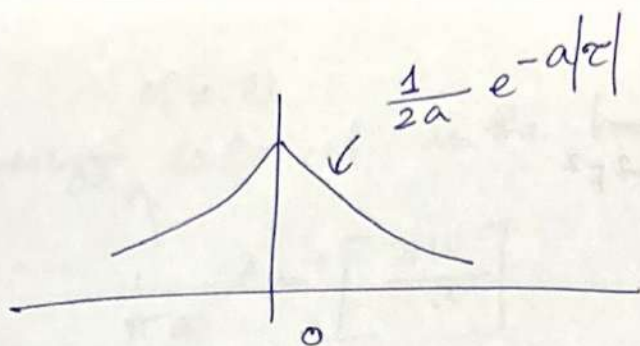
$$= \frac{e^{a\tau}}{2a} [1 - 0]$$

$$= \frac{e^{a\tau}}{2a}$$

$$R_{xx}(\tau) = \begin{cases} \frac{e^{-a\tau}}{2a}, & \tau \geq 0 \\ \frac{e^{a\tau}}{2a}, & \tau < 0 \end{cases}$$

$$R_{xx}(\tau) = \frac{1}{2a} e^{-a|\tau|}$$

Auto-correlation fun. of $e^{-at} u(t)$



Decaying exponential in +ve, -ve axis.

ESD:

$$x(t) = e^{-at} u(t)$$

$$X(F) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi Ft} dt$$

$$= \int_{-\infty}^{\infty} e^{-at} u(t) e^{-j2\pi Ft} dt$$

$$= \int_0^{\infty} e^{-(a+j2\pi F)t} dt$$

$$= \frac{e^{-(a+j2\pi F)t}}{-(a+j2\pi F)} \Big|_0^{\infty}$$

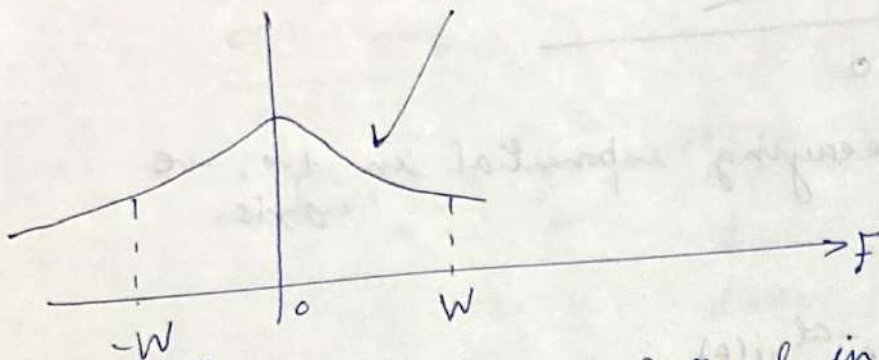
$$X(F) = \frac{1}{a+j2\pi F}$$

$$S_{xx}(F) = |X(F)|^2 = \left| \frac{1}{a+j2\pi F} \right|^2$$

$$R_{xx}(\tau) \xleftrightarrow{\text{F.T.}} \boxed{S_{xx}(F) = \frac{1}{a^2 + 4\pi^2 F^2}}$$

↓
ESD.

$$S_{xx}(F) = \frac{1}{a^2 + 4\pi^2 F^2}$$



Spread of Energy of signal in Frequency Domain.

Energy contained in the band $[-W, W]$

$$= \int_{-W}^W \frac{dF}{a^2 + 4\pi^2 F^2}$$

$$= \int_{-W}^W \frac{dF}{a^2 + (2\pi F)^2} \quad \begin{matrix} 2\pi F = \tilde{F} \\ 2\pi W \Rightarrow 2\pi dF = d\tilde{F} \end{matrix}$$

$$= \frac{1}{2\pi a} \left[\tan^{-1} \left(\frac{2\pi \tilde{F}}{a} \right) \right]_{-2\pi W}^{2\pi W}$$

$$= \frac{1 \times 2}{2\pi a} \left[\tan^{-1} \left(\frac{2\pi W}{a} \right) \right]$$

$$= \frac{1}{\pi a} \left[\tan^{-1} \left(\frac{2\pi W}{a} \right) \right]$$

Energy of $x(t)$ contained in the band $[-W, W]$ is :-

$$\frac{1}{\pi a} \tan^{-1} \left[\frac{2\pi W}{a} \right]$$

Say $W \rightarrow \infty$

$$\frac{1}{\pi a} \tan^{-1} \left[\frac{2\pi W}{a} \right] \Bigg|_{W \rightarrow \infty} = \frac{1}{\pi a} \times \frac{\pi}{2} \Bigg|_{W \rightarrow \infty} = \frac{1}{2a}$$

Total Energy

$$x(t) = e^{-at} u(t)$$

$$E_x = \int_0^{\infty} e^{-2at} dt = \frac{e^{-2at}}{-2a} \Bigg|_0^{\infty} = \frac{1}{2a}$$

$R_{xx}(\tau) \leftarrow$ Set $\tau = 0$

$$\int_{-\infty}^{\infty} x(t) x^*(t-\tau) dt$$

Set $\tau = 0$

$$= \int_{-\infty}^{\infty} x(t) \cdot x^*(t) dt$$

$$\Rightarrow R_{xx}(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} S_{xx}(f) df$$

$$= \int_{-\infty}^{\infty} |X(f)|^2 df$$

(Parseval's Relation / Theorem)

Auto-correlation

$$x_1(t)$$

$$R_{11}(\tau) = \int_{-\infty}^{\infty} x_1(t) x_1^*(t-\tau) dt$$

or

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} x(t) x^*(t-\tau) dt = x(t) * x^*(-t)$$

$$S_{xx}(F) = \int_{-\infty}^{\infty} R_{xx}(\tau) e^{-j2\pi F\tau} d\tau = X(F) \cdot \text{FT}[x^*(-\tau)]$$
$$= X(F) \cdot X^*(F) = |X(F)|^2$$

$$\boxed{S_{xx}(F) = |X(F)|^2}$$

Fourier Transform of auto-correlation.

$$X(F) : \text{FT}[x(t)]$$

$$R_{xx}(\tau) \longleftrightarrow S_{xx}(F)$$

$R_{xx}(\tau)$ is IFT of $S_{xx}(F)$

$$\Rightarrow R_{xx}(\tau) = \int_{-\infty}^{\infty} S_{xx}(F) e^{j2\pi F\tau} dF$$

$$\Rightarrow \boxed{R_{xx}(0) = \int_{-\infty}^{\infty} S_{xx}(F) dF = \int_{-\infty}^{\infty} |X(F)|^2 dF}$$

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} x(t) \cdot x^*(t-\tau) dt$$

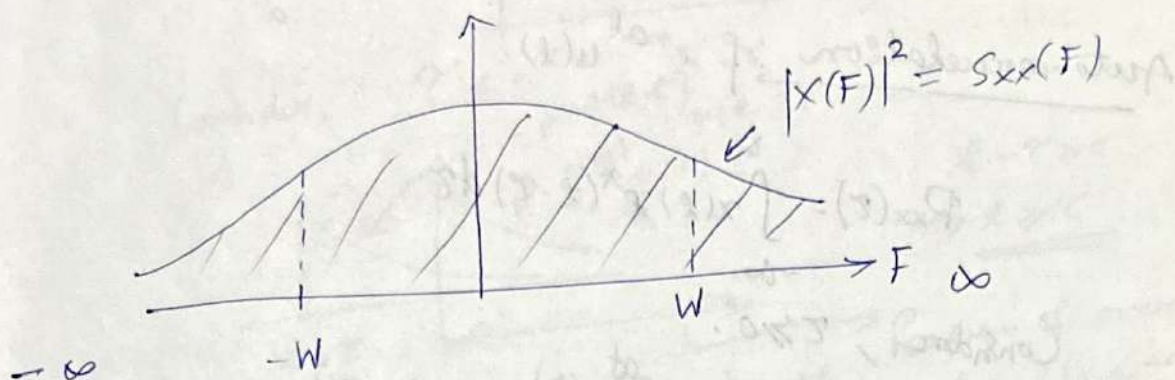
$$R_{xx}(0) = \int_{-\infty}^{\infty} x(t) \cdot x^*(t) dt = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$\therefore \boxed{R_{xx}(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} S_{xx}(F) dF = \int_{-\infty}^{\infty} |X(F)|^2 dF}$$

Energy of $x(t)$

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} |X(F)|^2 dF$$

Parseval's relation for a continuous time signal



Total Energy,
$$= \int_{-\infty}^{\infty} |X(F)|^2 dF = \int_{-\infty}^{\infty} S_{xx}(F) dF$$

Total Energy of the signal contained in the band $[-W, W]$

$$\int_{-W}^W S_{xx}(F) dF =$$

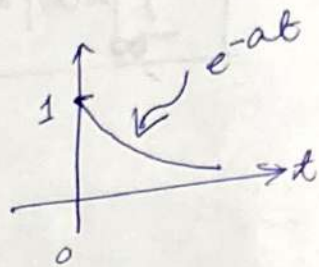
Energy Distribution of $x(t)$
in Frequency Domain.

$$S_{xx}(F) = |X(F)|^2$$
 : Energy Spectral Density
(ESD)

$$S_{xx}(F) \geq 0$$
 for all F \rightarrow Non-negative.

Example of Auto-correlation

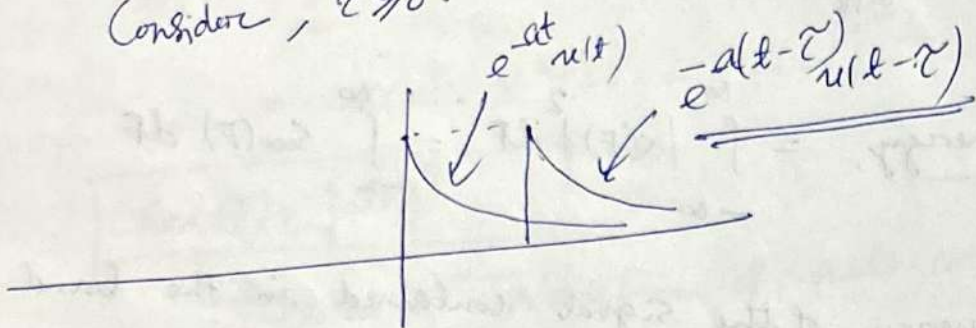
$$x(t) = e^{-at}u(t) = \begin{cases} e^{-at} & t \geq 0 \\ 0 & \text{otherwise} \end{cases}$$



Auto-correlation of $e^{-at}u(t)$

$$R_{xx}(\tau) = \int_{-\infty}^{\infty} x(t) x^*(t-\tau) dt$$

Consider, $\tau \geq 0$.



$$R_{xx}(\tau) = \int_{-\infty}^{\infty} e^{-at}u(t) \cdot e^{-a(t-\tau)}u(t-\tau) dt$$

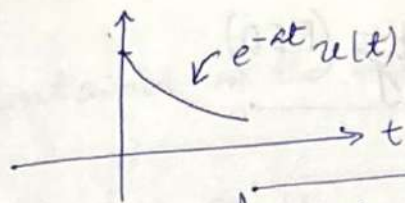
non-zero only for $t \geq \tau$

$$= \int_{\tau}^{\infty} e^{-at} \cdot e^{-a(t-\tau)} dt$$

$$= e^{+a\tau} \int_{\tau}^{\infty} e^{-2at} dt = e^{-a\tau} \left. \frac{e^{-2at}}{-2a} \right|_{\tau}^{\infty}$$

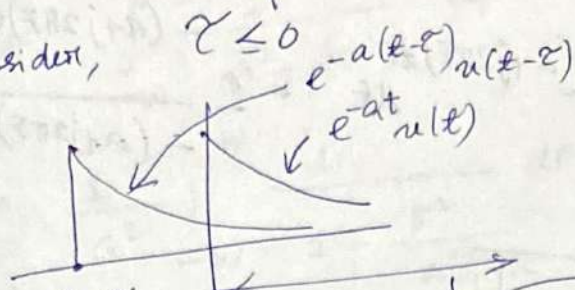
$$= \frac{1}{2a} e^{-a\tau}$$

$$R_{xx}(\tau) = \frac{e^{-a\tau}}{2a} \quad \text{iff } \tau \geq 0$$



if $\tau \geq 0$, $R_{11}(\tau) = \frac{e^{-a\tau}}{2a}$

Consider,



$t - \tau \geq 0$
 $\Rightarrow t \geq \tau$

Time shift τ is $-\tau$.
 Portion of overlap of $e^{-at}u(t)$ & $e^{-a(t-\tau)}u(t-\tau)$ for $t \geq 0$

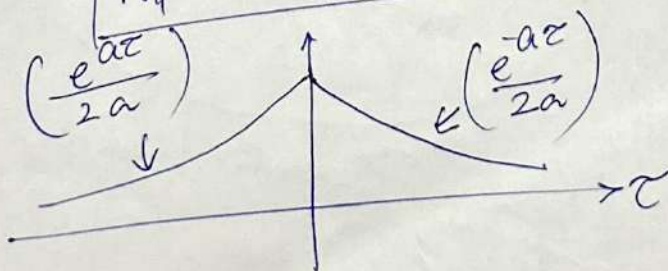
$$R_{11}(\tau) = \int_0^{\infty} e^{-at} e^{-a(t-\tau)} dt$$

$$= e^{a\tau} \int_0^{\infty} e^{-2at} dt = e^{a\tau} \left[\frac{e^{-2at}}{-2a} \right]_0^{\infty}$$

$$R_{11}(\tau) = \frac{e^{a\tau}}{2a}, \text{ for } \tau \leq 0$$

$$R_{11}(\tau) = \begin{cases} \frac{1}{2a} e^{-a\tau}, & \tau \geq 0 \\ \frac{1}{2a} e^{a\tau}, & \tau < 0 \end{cases} = \frac{1}{2a} [e^{-a|\tau|}]$$

$$R_{11}(\tau) = \frac{1}{2a} e^{-a|\tau|} \leftarrow \text{ACF of } \underline{e^{-at}u(t)}$$



Energy Spectral Density (ESD)

$$x(t) = e^{-at} u(t)$$

$$X(F) = \int_0^{\infty} e^{-at} e^{-j2\pi Ft} dt$$

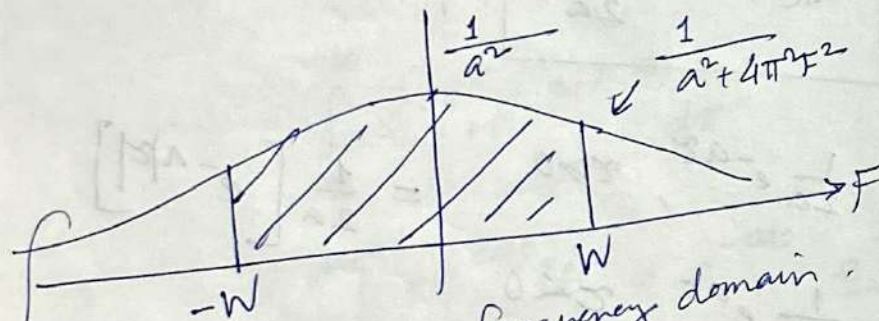
$$= \int_0^{\infty} e^{-(a+j2\pi F)t} dt = \frac{e^{-(a+j2\pi F)t}}{-(a+j2\pi F)} \Big|_0^{\infty}$$

$$\Rightarrow \boxed{X(F) = \frac{1}{a+j2\pi F}}$$

$$\text{ESD, } S_{11}(F) = |X(F)|^2 = \left| \frac{1}{a+j2\pi F} \right|^2 = \left(\frac{1}{\sqrt{a^2 + 4\pi^2 F^2}} \right)^2$$

$$\Rightarrow \boxed{S_{11}(F) = \frac{1}{a^2 + 4\pi^2 F^2}}$$

F.T.
↓
 $R_{xx}(\tau)$



Spread of energy in frequency domain.

Energy contained in the band $[-W, W]$

$$\int_{-W}^W S_{xx}(F) dF$$
$$= \int_{-W}^W \frac{1}{a^2 + 4\pi^2 F^2} dF$$
$$= \frac{1}{a^2} \int_{-W}^W \frac{1}{1 + \frac{F^2}{a^2/4\pi^2}} dF$$

$$\tilde{F} = \frac{F}{a/2\pi} \Rightarrow d\tilde{F} = \frac{2\pi}{a} dF$$
$$= \frac{1}{a^2} \cdot \frac{a}{2\pi} \int_{-\frac{2\pi W}{a}}^{\frac{2\pi W}{a}} \frac{1}{1 + (\tilde{F})^2} d\tilde{F}$$

$$= \frac{1}{2\pi a} \int_{-\frac{2\pi W}{a}}^{\frac{2\pi W}{a}} \frac{d\tilde{F}}{1 + \tilde{F}^2} = \frac{1}{2\pi a} \tan^{-1}(\tilde{F}) \Big|_{-\frac{2\pi W}{a}}^{\frac{2\pi W}{a}}$$

$$= \frac{1}{2\pi a} \times 2 \tan^{-1}\left(\frac{2\pi W}{a}\right)$$

$$= \frac{1}{\pi a} \tan^{-1}\left(\frac{2\pi W}{a}\right)$$

Energy of $x(t) = e^{-at} u(t)$

in the band $[-W, W]$

Set $W \rightarrow \infty$

$$E_x = \frac{1}{\pi a} \tan^{-1}\left(\frac{2\pi W}{a}\right)$$

$W \rightarrow \infty$

$$= \frac{1}{\pi a} \times \frac{\pi}{2}$$

$$= \frac{1}{2a}$$

$$x(t) = e^{-at} u(t)$$

$$\int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$= \int_0^{\infty} e^{-2at} dt$$

$$= \left. \frac{e^{-2at}}{-2a} \right|_0^{\infty}$$

$$= \frac{1}{2a}$$

ACF

$$R_{xx}(\tau) \xrightarrow{\text{Set } \tau=0} \int_{-\infty}^{\infty} x(t) x^*(t-\tau) dt$$

$$= \int_{-\infty}^{\infty} x(t) \cdot x^*(t) dt$$

$$\therefore R_{xx}(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

Total Energy of signal

$$x(t) = e^{-at} u(t)$$

$$R_{xx}(\tau) = \frac{1}{2a} e^{-a|\tau|}$$

$$R_{xx}(0) = \frac{1}{2a}$$

$$R_{xx}(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} S_{xx}(F) dF = \int_{-\infty}^{\infty} |X(F)|^2 dF$$

Parseval's Relation.

AMPLITUDE MODULATION (AM)

$$e(t) = A_c \cos(2\pi F_c t)$$

Carrier
Amplitude of Carrier
Carrier frequency

AM: Message modulates the amplitude of carrier.

$$x(t) = (1 + k_a m(t)) A_c \cos(2\pi F_c t)$$

$$\Rightarrow \boxed{x(t) = A_c [1 + k_a m(t)] \cos(2\pi F_c t)}$$

Amplitude Modulated Signal

$k_a \rightarrow$ Sensitivity of

$m(t) \rightarrow$ Message Signal

Amplitude of carrier is modulated according to message $m(t)$.

Example :-

$$A_c = 1$$

$$k_a = \frac{1}{2}$$

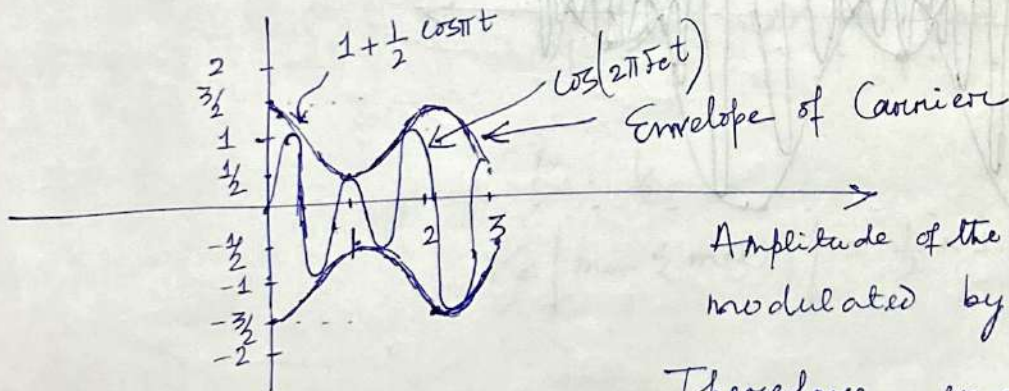
$$F_m = \frac{1}{2}$$

$$m(t) = \cos(2\pi F_m t)$$

$$= \cos(\pi t)$$

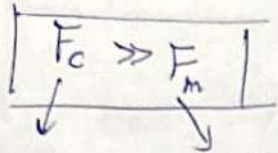
$$\text{AM: } x(t) = A_c (1 + k_a m(t)) \cos(2\pi F_c t)$$

$$\Rightarrow x(t) = \left(1 + \frac{1}{2} \cos \pi t\right) \cos(2\pi F_c t)$$



Amplitude of the carrier is modulated by message.

Therefore envelope of carrier contains information about message.



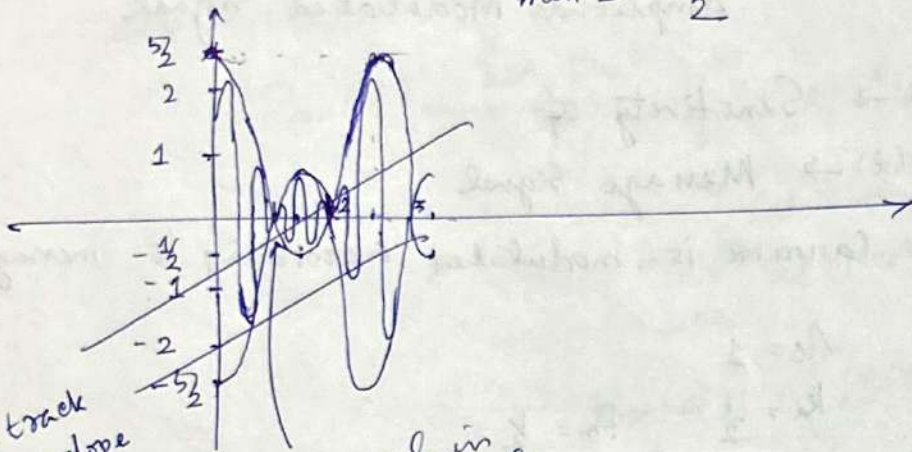
Carrier Frequency maximum frequency
 Component of the message.

$$k_a = \frac{3}{2}$$

$$1 + k_a m(t) = 1 + \frac{3}{2} \cos(\pi t)$$

$$\text{max} = \frac{5}{2}$$

$$\text{min} = -\frac{1}{2}$$

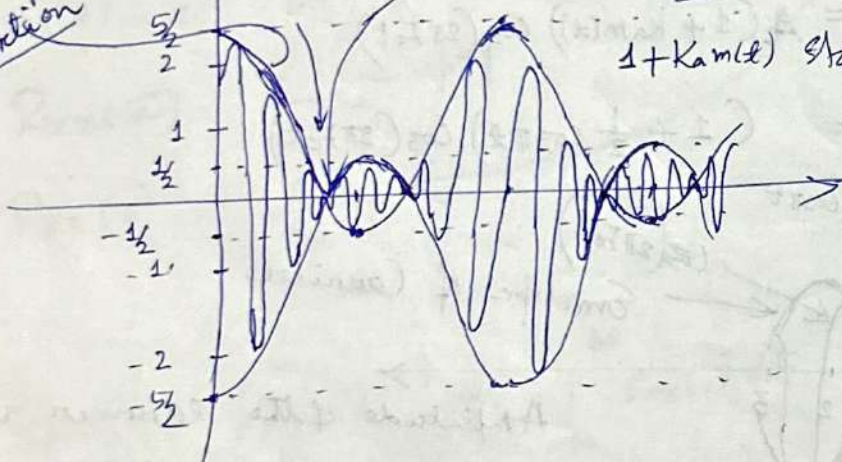


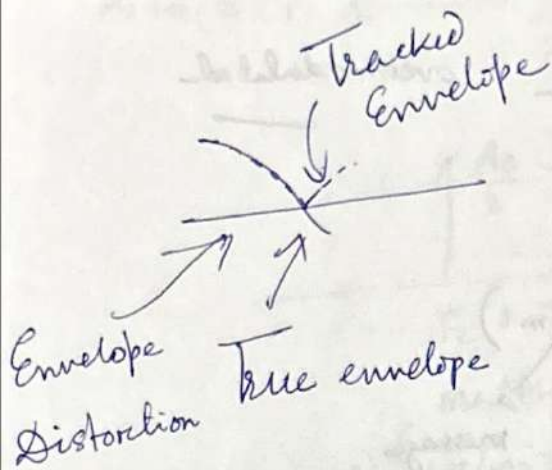
As we track the envelope
 envelope distortion

Phase reversal in modulating signal

$$1 + k_a m(t) = 1 + \frac{3}{2} \cos(\pi t) = 0$$

$1 + k_a m(t)$ starts becoming -ve





To avoid envelope distortion
Choose k_a appropriately

$$1 + k_a m(t) \geq 0$$

For No distortion

$$\Rightarrow k_a m(t) \geq -1$$

$$\Rightarrow \boxed{k_a \left| \min \{m(t)\} \right| \leq 1}$$

$$\mu = k_a \left| m(t) \right|_{\min}$$

$$= k_a \left| \min \{m(t)\} \right|$$

$$\mu \leq 1$$

↓
Modulation Index

For no envelope distortion $\mu \leq 1$

if $\mu > 1 \rightarrow$ Carrier is overmodulated.

↓
Envelope Distortion.

$$m(t) = \cos \pi t$$

$$\left| \min \{m(t)\} \right| = \left| \min \{ \cos \pi t \} \right| = |-1| = 1$$

$$k_a = \frac{1}{2}$$

$$k_a \left| \min \{m(t)\} \right| = \frac{1}{2} \times 1 = \frac{1}{2} < 1$$

$$K_a = \frac{3}{2}$$

$$K_a |\min\{m(t)\}| = \frac{3}{2} \times 1 = \frac{3}{2} > 1 \quad ; \quad \text{overmodulated}$$

For a sinusoidal message signal

$$m(t) = A_m \cos(2\pi F_m t)$$

Amplitude of message
message frequency

$$|\min\{m(t)\}| = |-A_m| = A_m$$

$$\mu = K_a A_m$$

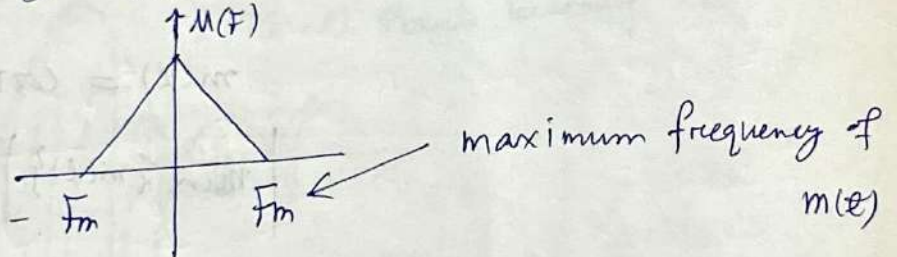
Modulation Index = Sensitivity Factor \times Amplitude of message

For a sinusoidal message, $m(t) = A_m \cos(2\pi F_m t)$

Spectrum of an AM signal :

message : $m(t)$

$$m(t) \longleftrightarrow M(F)$$



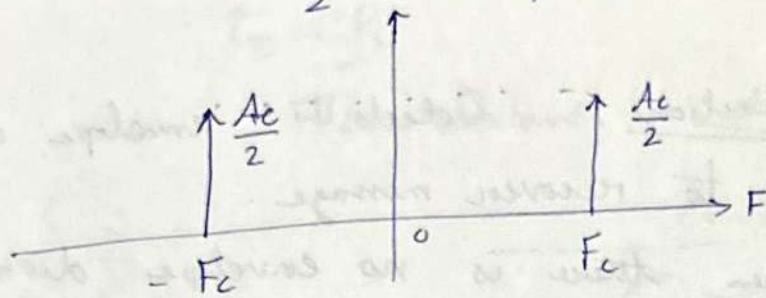
$$x(t) = A_c (1 + K_a m(t)) \cos(2\pi F_c t)$$

$$= A_c \cos(2\pi F_c t) + K_a A_c m(t) \cdot \cos(2\pi F_c t)$$

$$\cos 2\pi F_c t = \frac{e^{j2\pi F_c t} + e^{-j2\pi F_c t}}{2} \longleftrightarrow \frac{1}{2} [\delta(F - F_c) + \delta(F + F_c)]$$

$$e^{j2\pi F_c t} \longleftrightarrow \delta(F - F_c), \quad e^{-j2\pi F_c t} \longleftrightarrow \delta(F + F_c)$$

$$A_c \cos(2\pi F_c t) \longleftrightarrow \frac{A_c}{2} \delta(F - F_c) + \frac{A_c}{2} \delta(F + F_c)$$



Multiplication in time domain

$$A_c K_a m(t) \cdot \cos(2\pi F_c t)$$

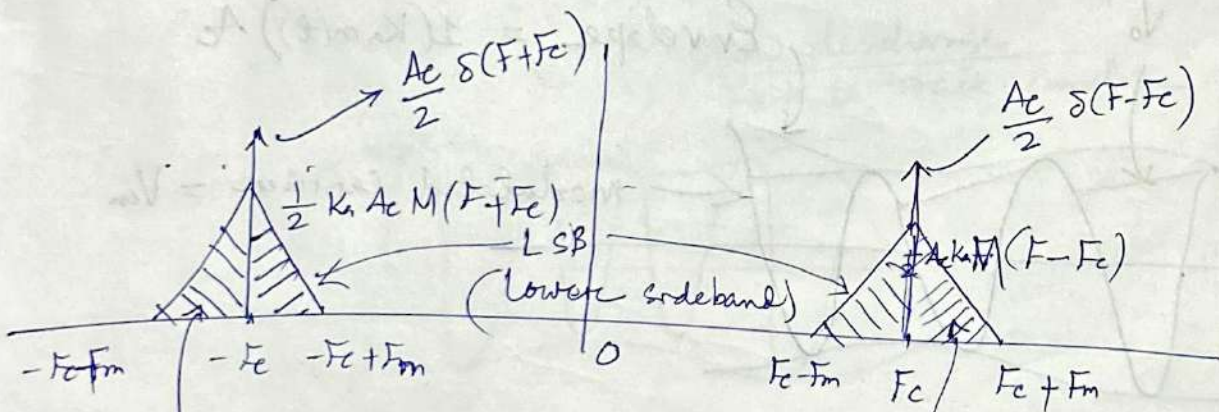
$$\updownarrow \quad \updownarrow$$

$$A_c K_a M(F) * \frac{1}{2} [\delta(F - F_c) + \delta(F + F_c)]$$

Convolution in Frequency Domain

$$= \frac{A_c K_a}{2} M(F) * \delta(F - F_c) + \frac{A_c K_a}{2} M(F) * \delta(F + F_c)$$

$$= \frac{A_c K_a}{2} M(F - F_c) + \frac{A_c K_a}{2} M(F + F_c)$$



Spectrum of AM signal : $A_c(1 + k_a m(t)) \cos(2\pi F_c t)$

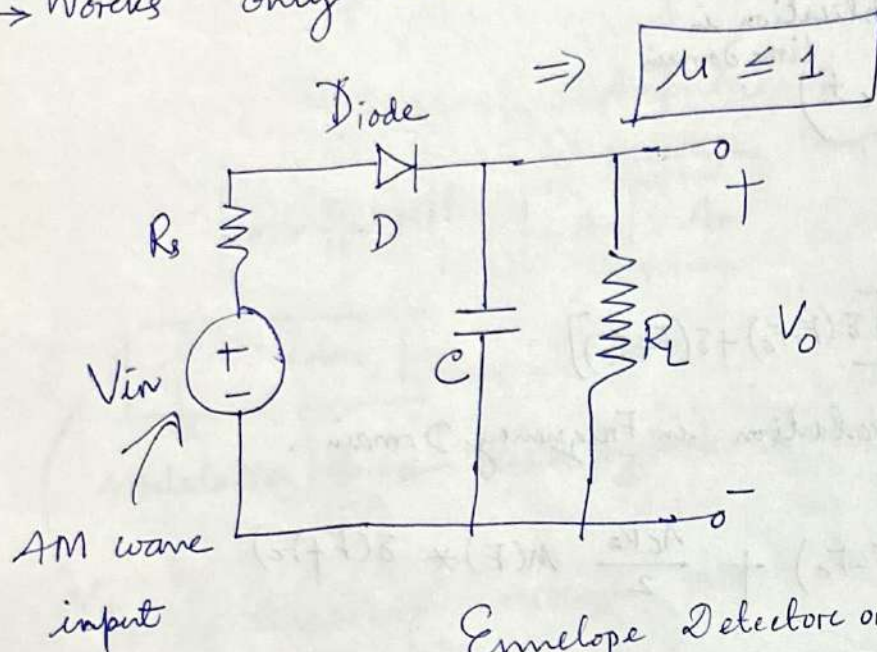
USB
(upper sideband)

Detection of AM

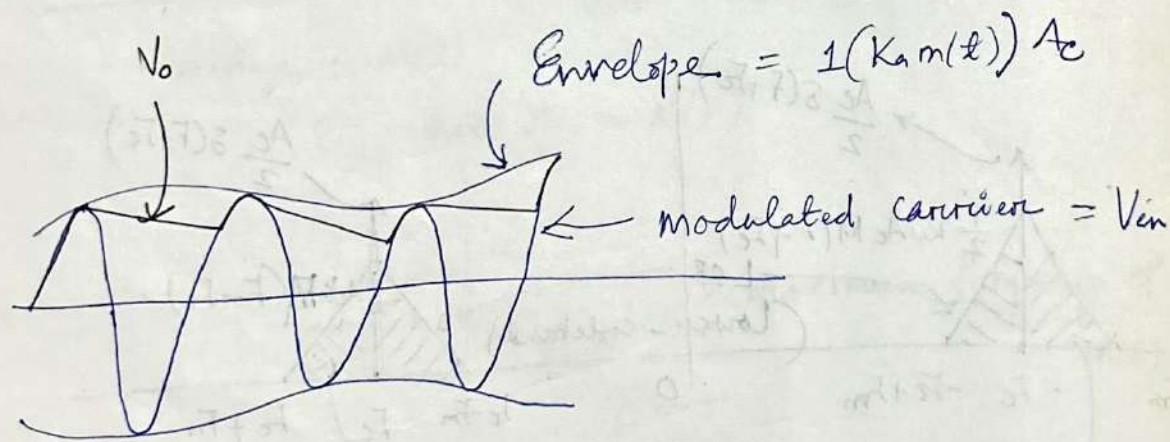
Envelope Detection: Detects the envelope of

transmitted signal to recover message.

→ Works only when there is no envelope distortion



Envelope Detector or Peak Detector



$V_o =$ output of envelope detector

Principle:

When $V_{in} > V_o$

⇒ Diode is F.B. ⇒ Capacitor charges to peak of V_{in}

$V_{in} < V_o$

⇒ D is R.B. ⇒ Capacitor discharges through R_L

Capacitor discharges slowly

$$\tau_D = RC$$

Time constant for discharging.

Envelope Detector

- Low cost receiver
- Less complex
 - Low cost
 - Easy to implement
 - Long distance capability

Broadcast application

Ex:- Radio, TV

→ Between Aircraft & air traffic control.

over a long distance

$$V_{in} = A_c [1 + k_a m(t)] \cos(2\pi F_c t)$$

→ Maritime communication
ship-to-ship & ship-to-shore

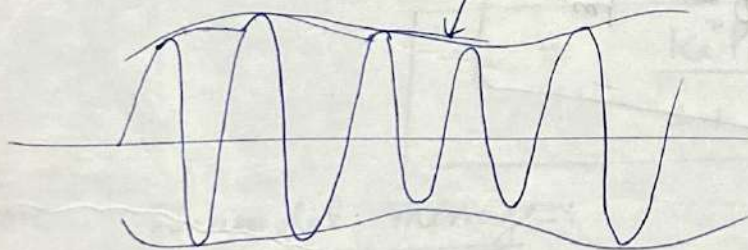
(MF) & (HF) bands

→ Military Radio

$$\tau_D = RC$$

$V_{in} < V_0$: Diode is R.B.

slow discharge
Fails to track envelope



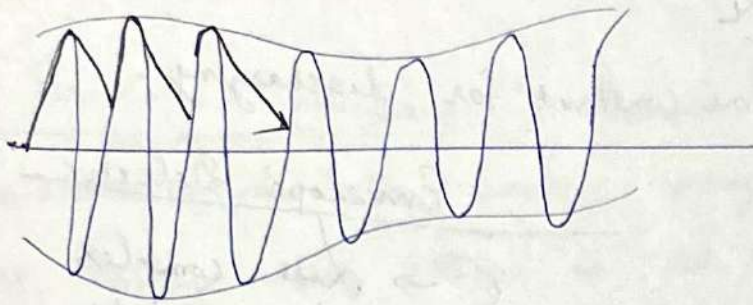
$\tau_D = RC$, very large
⇒ Fails to track envelope

$$\tau_D \ll \frac{1}{F_m}$$

Discharge is faster than the rate of change of envelope

$A_c [1 + k_a m(t)]$
Determined by message $m(t)$

(MF) 300kHz - 3MHz | (HF) 3-30MHz



If τ_D is too small

\Rightarrow Capacitor discharges very rapidly.

Output of the capacitor tracks the carrier & not the envelope.

$$\tau_D = RC \gg \frac{1}{f_c}$$

\downarrow so that q_p does not

tracks envelope rather than carrier

$$\frac{1}{f_c} \ll \tau_D \ll \frac{1}{f_m}$$

Power of an AM Signal

$$x(t) = A_c [1 + k_a m(t)] \cos(2\pi f_c t)$$

$$= A_c \cos(2\pi f_c t) + A_c k_a m(t) \cos(2\pi f_c t)$$

$$\text{Avg Power} = \frac{A_c^2}{2}$$

$$\text{Inst. power} : \frac{k_a^2 A_c^2 m^2(t)}{2}$$

$$\text{Avg Power} : E \left\langle \frac{1}{2} k_a^2 A_c^2 m^2(t) \right\rangle$$

$$= \frac{1}{2} k_a^2 A_c^2 E \langle m^2(t) \rangle$$

$$= \frac{1}{2} k_a^2 A_c^2 P_m$$

$\left. \begin{array}{l} P_m \rightarrow \text{Avg power of message} \\ \text{signal} \end{array} \right\}$

$$P_T = \frac{A_c^2}{2} + \frac{k_a^2 A_c^2 P_m}{2}$$

$\eta = \text{efficiency of AM} = \frac{\text{Power in carrier modulated by message}}{\text{Total Power}}$

Total Power

$$\frac{1}{2} A_c^2 k_a^2 P_m$$

$$\frac{1}{2} A_c^2 + \frac{1}{2} A_c^2 k_a^2 P_m$$

$$\eta = \frac{k_a^2 P_m}{1 + k_a^2 P_m}$$

For a sinusoidal message:

$$m(t) = A_m \cos(2\pi F_m t)$$

$$P_m = \frac{A_m^2}{2}$$

$$\eta = \frac{k_a^2 \frac{A_m^2}{2}}{1 + k_a^2 \frac{A_m^2}{2}}$$

$$= \frac{(k_a A_m)^2}{2 + (k_a A_m)^2}$$

$$\Rightarrow \eta = \frac{\mu^2}{2 + \mu^2}$$

$$\eta = \frac{\mu^2}{2 + \mu^2} = 1 - \frac{2}{2 + \mu^2}$$

decreases with μ

η increases with μ

For envelope detection, $\max(\mu) = 1$

$$\eta_{\max} = \frac{\mu^2}{\mu^2 + 2} \Big|_{\mu=1} = \frac{1}{2+1} = \frac{1}{3}$$

$$\boxed{\% \eta_{\max} = 33\%}$$

↳ maximum efficiency with no ED

OR

$$\begin{aligned} s(t) &= A_c [1 + \mu \cos(2\pi F_m t)] \cos(2\pi F_c t) \\ &= A_c \cos(2\pi F_c t) + \mu A_c \cos(2\pi F_c t) \cos(2\pi F_m t) \\ &= A_c \cos(2\pi F_c t) + \frac{\mu A_c}{2} \cos 2\pi (F_c + F_m)t + \end{aligned}$$

$$\begin{aligned} P_C &= \frac{A_c^2}{2} \\ P_{USB} &= \frac{\frac{\mu^2 A_c^2}{2^2}}{2} = \frac{\mu^2 A_c^2}{8} \\ P_{LSB} &= \frac{\frac{\mu^2 A_c^2}{2^2}}{2} = \frac{\mu^2 A_c^2}{8} \end{aligned}$$

$$\eta = \frac{P_{LSB} + P_{USB}}{P_C + P_{LSB} + P_{USB}} = \frac{\frac{\mu^2 A_c^2}{8} + \frac{\mu^2 A_c^2}{8}}{\frac{A_c^2}{2} + \frac{\mu^2 A_c^2}{8} + \frac{\mu^2 A_c^2}{8}}$$

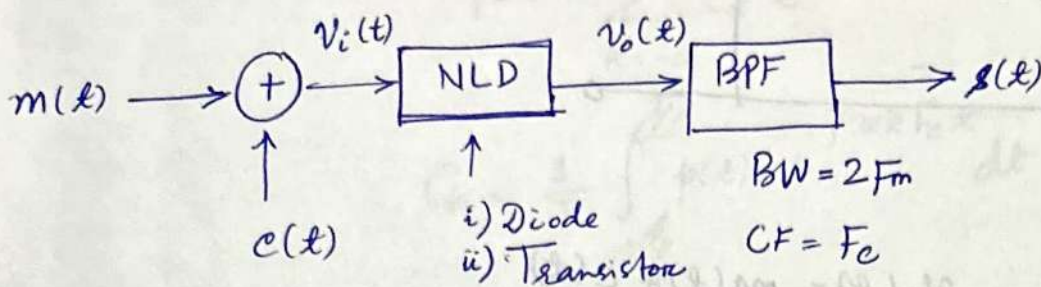
$$\Rightarrow \eta = \frac{\frac{\mu^2 A_c^2}{4}}{\frac{A_c^2}{2} + \frac{\mu^2 A_c^2}{4}} = \frac{\mu^2}{2 + \mu^2}$$

AM Modulation

2 methods:

- Square Law Modulation
- Switching Modulation.

a) Square Law Modulation



$$v_i(t) = m(t) + c(t) = m(t) + A_c \cos(2\pi F_c t)$$

$$v_o(t) = a_1 v_i(t) + a_2 v_i^2(t)$$

$$= a_1 [m(t) + A_c \cos(2\pi F_c t)] + a_2 [m(t) + A_c \cos(2\pi F_c t)]^2$$

$$\Rightarrow v_o(t) = a_1 m(t) + a_1 A_c \cos(2\pi F_c t) + a_2 m^2(t) + a_2 A_c^2 \cos^2(2\pi F_c t) + 2 a_2 m(t) \cdot A_c \cos(2\pi F_c t)$$

OP of BPF:

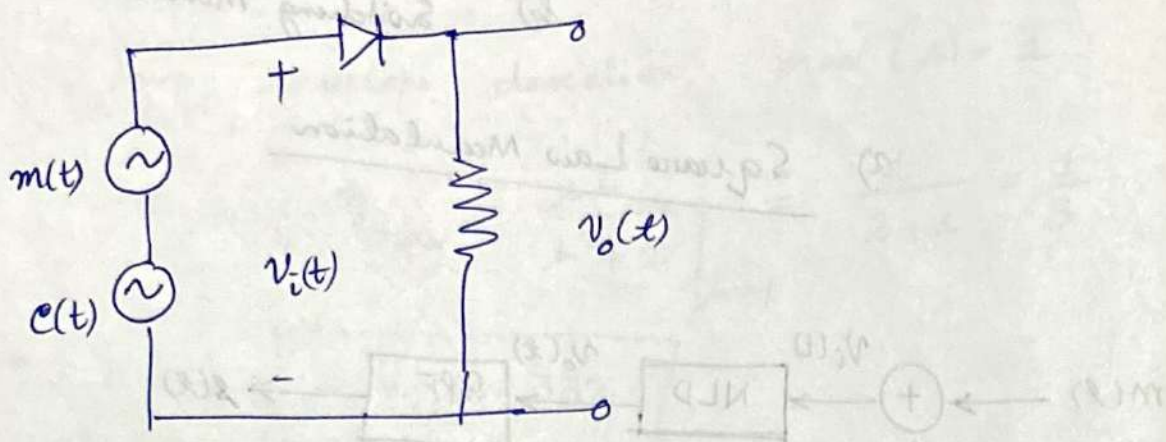
$$s(t) = a_1 A_c \cos(2\pi F_c t) + 2 a_2 m(t) \cdot A_c \cos(2\pi F_c t)$$

$$= a_1 A_c \left[1 + \frac{2 a_2 A_c}{a_1 A_c} m(t) \right] \cos(2\pi F_c t)$$

$$= a_1 A_c \left[1 + \frac{2 a_2}{a_1} m(t) \right] \cos(2\pi F_c t)$$

$$\therefore s(t) = A_c [1 + k_a m(t)] \cos(2\pi F_c t) \quad \begin{cases} A_c = a_1 A_c' \\ k_a = \frac{2 a_2}{a_1} \end{cases}$$

b) Switching Modulator



$$v_i(t) = m(t) + c(t)$$

$$= m(t) + A_c \cos(2\pi F_c t)$$

Since $A_c \gg$ amplitude $\{m(t)\}$

Carrier $c(t)$ decides the states of diode. (ON or OFF)

$$\text{So, } v_i(t) \geq 0 \Rightarrow v_o(t) = v_i(t)$$

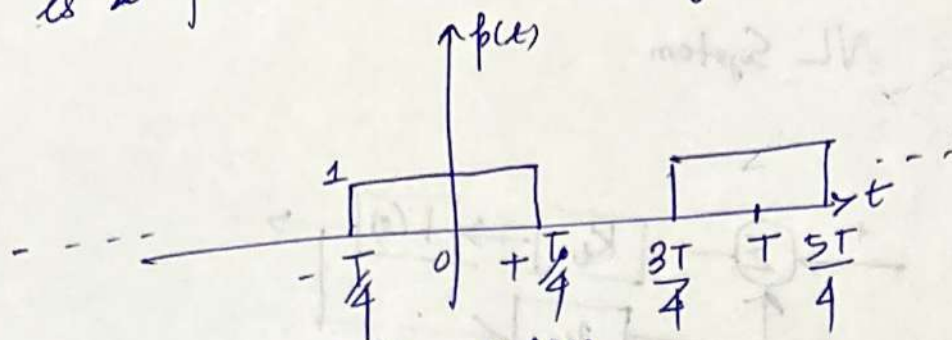
$$\& \text{ if } v_i(t) < 0 \Rightarrow v_o(t) = 0$$

So $v_o(t)$ varies between $v_i(t)$ & 0 at a rate equal to carrier frequency F_c .

$$\text{So, } v_o(t) = v_i(t) \cdot p(t)$$

$$= [m(t) + A_c \cos(2\pi F_c t)] p(t)$$

$p(t)$ is a pulse train with duty cycle = 50%.



$$T = \frac{1}{F_0}$$

F.S. representation of $p(t)$

$$p(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_0 t}$$

$$C_k = \frac{1}{T} \int_{-T/4}^{T/4} p(t) \cdot e^{-j2\pi k F_0 t} dt$$

$$C_0 = \frac{1}{T} \int_{-T/4}^{T/4} 1 dt = \frac{1}{T} \times \frac{T}{2}$$

$$\frac{T \text{ sinc}(F T)}{T} = \frac{1}{2}$$

$$= \frac{1}{T} \int_{-T/4}^{T/4} e^{-j2\pi k F_0 t} dt$$

$$= \frac{1}{T} \left. \frac{e^{-j2\pi k F_0 t}}{-j2\pi k F_0} \right|_{-T/4}^{T/4}$$

$$= \frac{1}{T} \times \frac{1}{j2\pi k F_0} \left\{ e^{j\pi k F_0 T/2} - e^{-j\pi k F_0 T/2} \right\}$$

$$= \frac{1}{j2\pi k} \left\{ e^{j\pi k/2} - e^{-j\pi k/2} \right\}$$

$$= \frac{1 \times \sin(\frac{\pi k}{2})}{\pi k}$$

$$p(t) = \frac{1}{2} + \frac{1}{\pi}$$

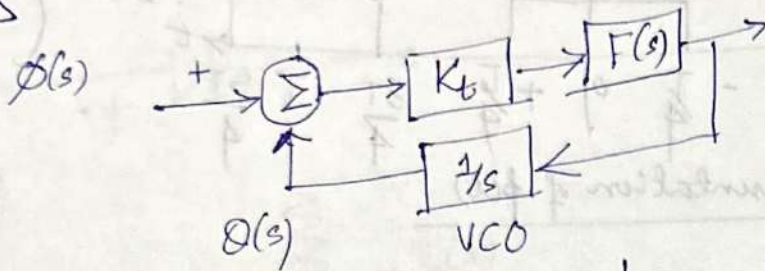
~~$p(t)$~~

$$C_k = \begin{cases} \frac{1}{2}, & k=0 \\ 0, & k \rightarrow \text{even} \\ \neq 0, & k \rightarrow \text{odd} \end{cases}$$

Phase Locked Loop

Linear Model

NL System.



$$H(s) = \frac{\theta(s)}{\phi(s)}$$

$$\begin{aligned} \theta(s) &= \frac{K_t F(s)}{s} [\phi(s) - \theta(s)] \\ \Rightarrow \frac{\theta(s)}{\phi(s)} &= \frac{K_t F(s)}{1 + \frac{K_t F(s)}{s}} \\ &= \frac{K_t F(s)}{1 + K_t F(s)} \end{aligned}$$

$$\frac{1}{s} \times \frac{1}{s} = \frac{1}{s^2}$$

$$\frac{1}{s} \times \frac{1}{s} = \frac{1}{s^2}$$

Double Sideband Modulation (DSB)

$$x(t) = A_c m(t) \cos(2\pi F_c t)$$

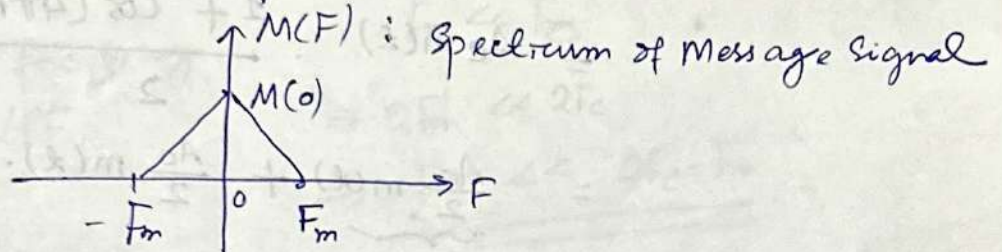
No pure carrier component is present

$m(t) \rightarrow$ Message Signal

$F_c \rightarrow$ Carrier Frequency

DSB-SC

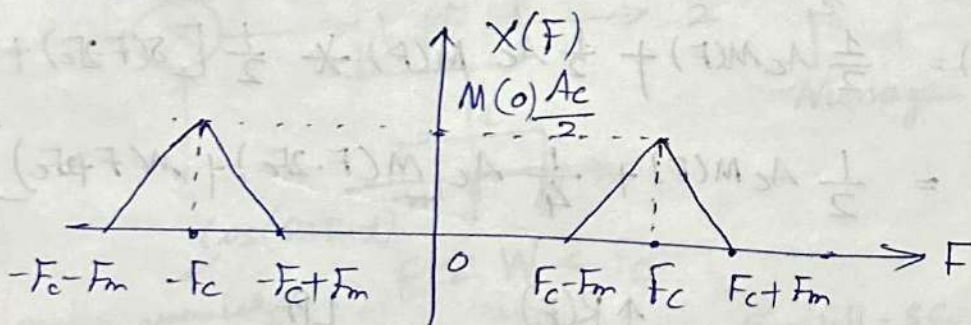
Double Sideband - Suppressed Carrier



$$x(t) = A_c m(t) \cos(2\pi F_c t) = m(t) \cdot A_c \cos(2\pi F_c t)$$

$$\Rightarrow X(F) = M(F) * \frac{A_c}{2} [\delta(F - F_c) + \delta(F + F_c)]$$

$$\Rightarrow X(F) = \frac{A_c}{2} [M(F - F_c) + M(F + F_c)]$$



$$\boxed{B.W = 2F_m}$$

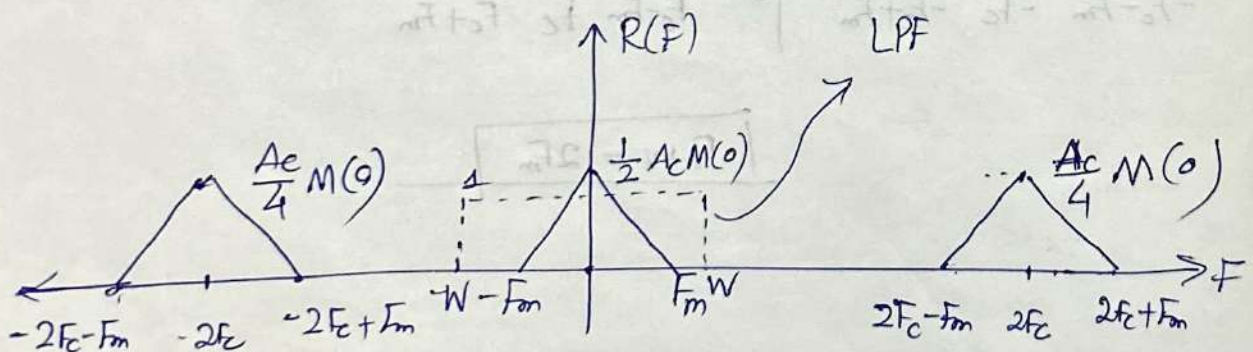
Demodulation of DSB-SC

Demodulation can be carried out by multiplying with a coherently generated carrier at the receiver.

$$\begin{aligned}
 r(t) &= x(t) \cdot \cos(2\pi F_c t) \\
 &= A_c m(t) \cdot \cos(2\pi F_c t) \cdot \cos(2\pi F_c t) \\
 &= A_c m(t) \cdot \cos^2(2\pi F_c t) \\
 &= A_c m(t) \cdot \frac{1 + \cos(4\pi F_c t)}{2} \\
 &= \underbrace{\frac{A_c}{2} m(t)}_{\text{Baseband}} + \underbrace{\frac{A_c}{2} m(t) \cdot \cos(4\pi F_c t)}_{\substack{\text{Freq} = 2f_c \\ \text{Centered at } 2f_c}}
 \end{aligned}$$

$$r(t) = x(t) \cos(2\pi F_c t) = \frac{1}{2} A_c m(t) + \frac{1}{2} A_c m(t) \cos(4\pi F_c t)$$

$$\begin{aligned}
 R(F) &= \frac{1}{2} A_c M(F) + \frac{1}{2} A_c M(F) * \frac{1}{2} [\delta(F-2F_c) + \delta(F+2F_c)] \\
 &= \frac{1}{2} A_c M(F) + \frac{1}{4} A_c [M(F-2F_c) + M(F+2F_c)]
 \end{aligned}$$



Choosing an LPF of suitable bandwidth W

$\frac{A_c m(t)}{2}$ can be separated from $\frac{A_c \cos(4\pi f_c t)}{2}$
 ↓
 Base-band
 Sidebands at $\pm 2f_c$.

Choose LPF, such that cut off frequency,

$$f_m \leq W \leq 2f_c - f_m$$

This is possible because, we have

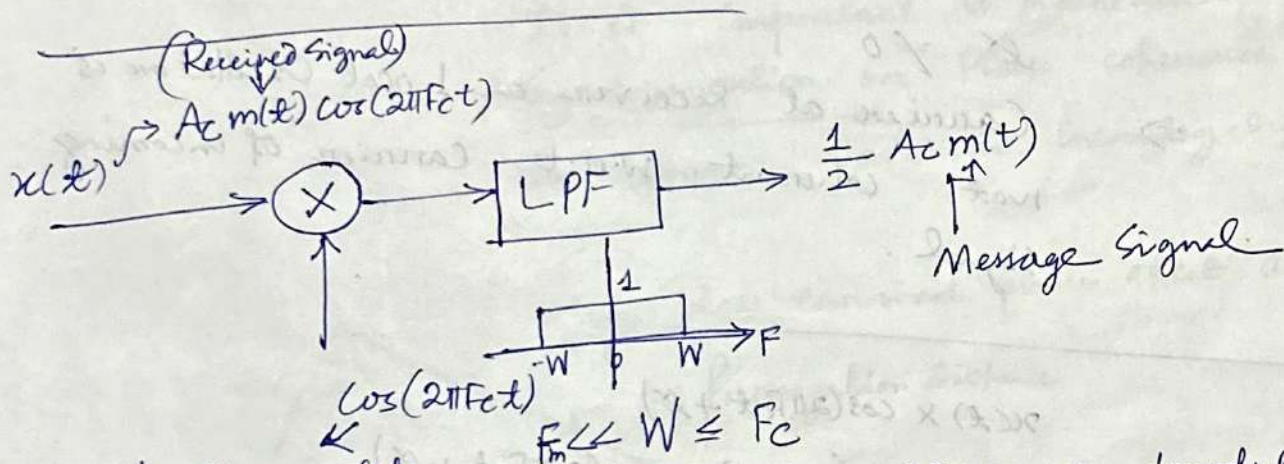
$$f_m \ll f_c$$

$$\Rightarrow 2f_m \ll 2f_c$$

$$\Rightarrow f_m \ll 2f_c - f_m$$

Cut off frequency of LPF

LPF blocks the component $\frac{A_c m(t) \cos(4\pi f_c t)}{2}$.



Schematic Diagram of DSB-SC demodulation process

* Phase of incoming signal & locally generated carrier at receiver are same.
No phase offset

↓
 Coherent Demodulation.

$$x(t) = A_c m(t) \cos(2\pi F_c t) \quad \text{:- Received Signal}$$

$$x \cos(2\pi F_c t) \quad \left\{ \begin{array}{l} \text{Locally generated carrier at receiver} \\ \text{No Phase offset between these 2} \end{array} \right. \rightarrow \text{Coherent Demodulation}$$

or Synchronous Demodulation

But in general,

$$x(t) = A_c m(t) \cos(2\pi F_c t) \quad \cos(2\pi F_c t + \phi)$$

$\phi \rightarrow$ Carrier Phase offset

$\Rightarrow \phi \neq 0$
Carrier at Receiver or Local Oscillator is not coherent w.r.t carrier of incoming signal.

$$\begin{aligned} & x(t) \times \cos(2\pi F_c t + \phi) \\ = & A_c m(t) \cos(2\pi F_c t) \cdot \cos(2\pi F_c t + \phi) \\ = & \frac{A_c m(t)}{2} \left[\cos(4\pi F_c t + \phi) + \cos(\phi) \right] \\ = & \underbrace{\frac{A_c m(t)}{2} \cdot \cos \phi}_{\text{Baseband}} + \underbrace{\frac{A_c m(t)}{2} \cos(4\pi F_c t + \phi)}_{\pm 2F_c} \end{aligned}$$

LPF,

Cut off

$$F_m < W < F_c - F_m$$

% of LPF : $\frac{1}{2} A_c m(t) \cos \phi$

Additional factor ϕ .

Previously absent in coherent demodulation.

Power of demodulated signal,

$$= \frac{1}{4} A_c^2 P_m \cos^2 \phi$$

% power decreases by a factor of $\cos^2 \phi$ [≤ 1], for

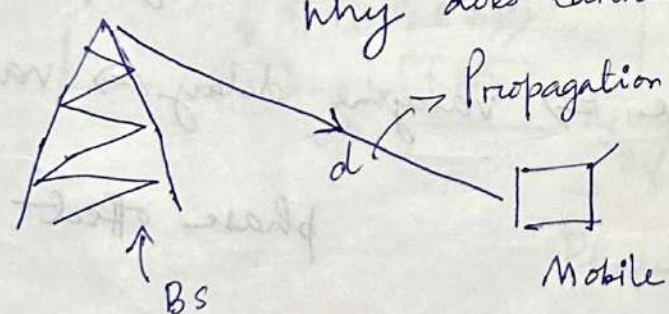
$$\phi = \frac{\pi}{2}, \text{ Power} = 0$$

Locally generated carrier is orthogonal to carrier wave in incoming signal.

$\phi \uparrow \Rightarrow P \downarrow \Rightarrow$ Performance of Rx worsens.

It is important to maintain Phase Synchronisation or Phase coherence with respect to carrier wave in incoming signal.

Why does carrier phase offset arises?



(Base Station)

Tx: Transmits

$$x(t) = A_c m(t) \cdot \cos(2\pi f_c t)$$

$$\text{Propagation delay} = \frac{d}{c}$$

Signal received at the mobile user

$$\downarrow \quad \downarrow \text{Delayed version of } x(t)$$
$$r_y(t) = x(t - \tau)$$

$$= A_c m(t - \tau) \cos [2\pi F_c (t - \tau)]$$

$$= A_c m(t - \tau) \cos [2\pi F_c t - 2\pi F_c \tau]$$

$$= A_c m(t - \tau) \cos \left(2\pi F_c t - \underbrace{2\pi F_c \frac{d}{c}}_{\phi} \right)$$

$\phi = \text{Phase offset}$

$$m(t - \tau) \approx m(t)$$

(Since $F_m \ll F_m$ maximum message freq.)

$$\approx A_c m(t) \cos [2\pi F_c t - \phi(d)]$$

$$\boxed{\phi(d) = 2\pi F_c \left(\frac{d}{c} \right)}$$

: Phase offset.

(Varying)

depends on distance, d

$$\frac{\partial \phi(d)}{\partial t} = \frac{\partial}{\partial t}$$

$$\frac{\partial \phi(d)}{\partial t} = \frac{\partial}{\partial t} \frac{2\pi F_c d/c}{dt} = \frac{2\pi F_c}{c} \frac{\partial d}{\partial t}$$

Rate of change of Phase offset \propto velocity of user

Varying distance \Rightarrow varying delay \Rightarrow varying phase offset

Hence, to avoid performance deterioration, one has to frequently synchronize phase of local oscillator with that of incoming signal.

This process is termed as Phase Synchronization.

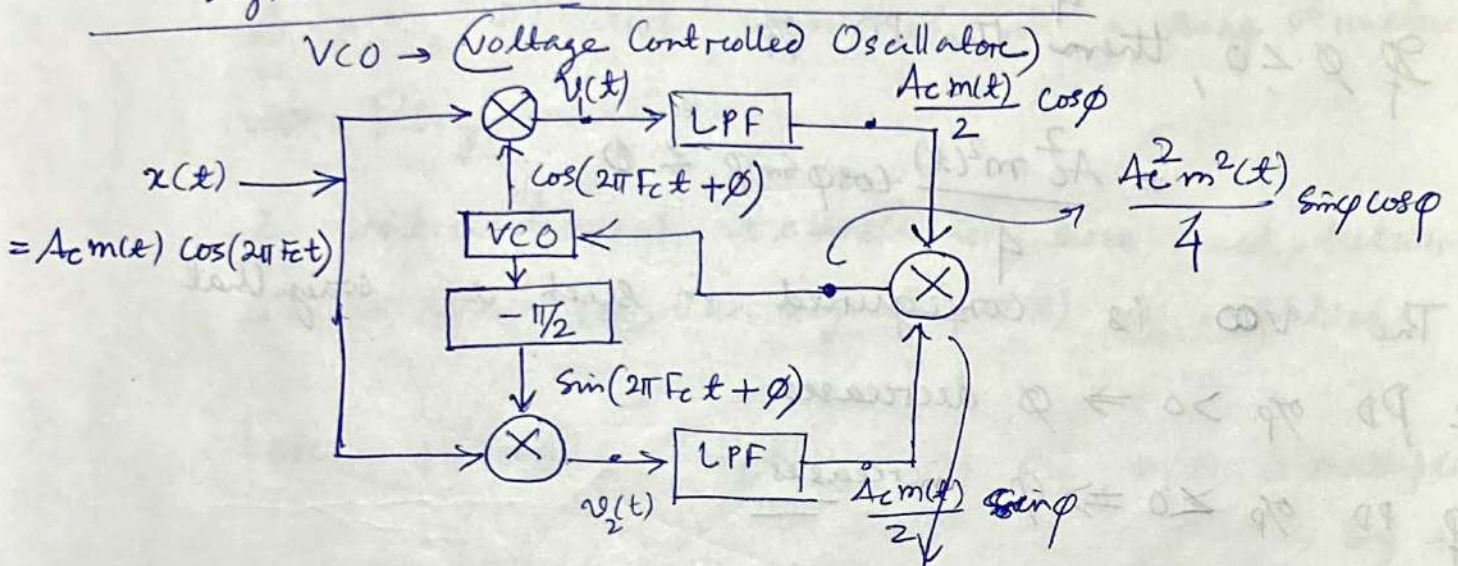
To perform phase synchronization,

one can employ Costas Receiver / Costas loop.

Costas Receiver enables coherent Demodulation by synchronizing phase of locally generated carrier with that of the incoming ~~sig~~ signal.

COSTAS LOOP (OR RECEIVER)

To synchronize Phase of ~~incoming~~ signal to locally generated carrier with that of incoming signal.



Phase Discriminator

Upper

$$v_1(t) = A_c m(t) \cos(2\pi F_c t) \times \cos(2\pi F_c t + \phi) = \frac{A_c m(t)}{2} \left\{ \cos(4\pi F_c t + \phi) + \cos \phi \right\}$$

% of LPF: $\frac{A_c m(t)}{2} \cos \phi$

% of 2nd demodulator

$$v_2(t) = A_c m(t) \cos(2\pi F_c t) \cdot \sin(2\pi F_c t + \phi)$$

$$= \frac{A_c m(t)}{2} \left[\sin(4\pi F_c t + \phi) + \sin(\phi) \right]$$

Output of LPF :-

$$\frac{A_c m(t)}{2} \sin \phi$$

% of Phase Discriminator

$$\frac{A_c^2 m^2(t)}{4} \sin \phi \cdot \cos \phi$$

Assume, ϕ to be small.

$$-\frac{\pi}{2} \leq \phi \leq \frac{\pi}{2}$$

If $\phi > 0$, then we have Phase Discriminator (PD) output is

$$\frac{A_c^2 m^2(t)}{4} \cos \phi \cdot \sin \phi \geq 0$$

If $\phi < 0$, then the PD %

$$= \frac{A_c^2 m^2(t)}{4} \cos \phi \sin \phi < 0$$

The VCO is configured in such a way that

If PD % $> 0 \Rightarrow \phi$ decreases

If PD % $< 0 \Rightarrow \phi$ increases.

Hence +ve ϕ ~~decreases~~ \Rightarrow Decrease in ϕ

-ve $\phi \Rightarrow$ increase in ϕ

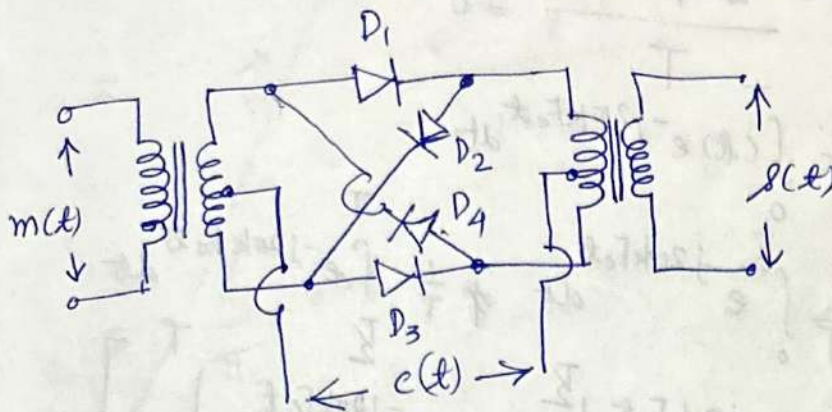
\Rightarrow Phase offset ϕ is eventually driven to zero

$$\phi = 0$$

\Rightarrow ~~Carrier~~ Synchronization is achieved between locally generated carrier & the incoming signal.

Quadrature Carrier Multiplexing

RING-MODULATOR

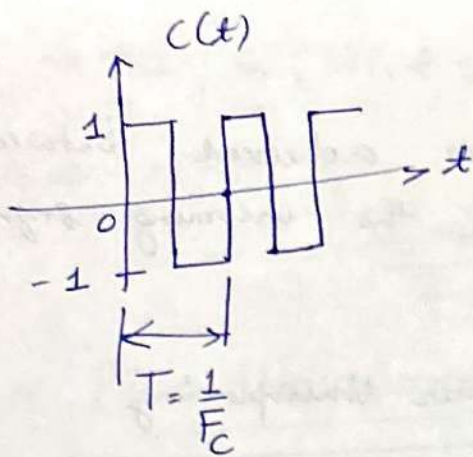


D_1, D_2, D_3, D_4 are connected in a ring structure
 \Rightarrow Ring modulator.

2 centre tapped transformers are used, between which the carrier signal $c(t)$ is applied.

For $c(t) > 0$, D_1 & D_3 are ON, $m(t)$ is multiplied by +1

For $c(t) < 0$, D_2 & D_4 are ON, $m(t)$ is multiplied by -1



$$C_0 = \frac{(1 \times \frac{T}{2}) + (-1 \times \frac{T}{2})}{T} = 0$$

$$C_k = \frac{1}{T} \int_0^T c(t) e^{-j2\pi k F_c t} dt$$

$$= \frac{1}{T} \int_0^{\frac{T}{2}} e^{-j2\pi k F_c t} dt - \frac{1}{T} \int_{\frac{T}{2}}^T e^{-j2\pi k F_c t} dt$$

$$= \frac{1}{T} \left[\frac{e^{-j2\pi k F_c t}}{-j2\pi k F_c} \Big|_0^{\frac{T}{2}} - \frac{e^{-j2\pi k F_c t}}{-j2\pi k F_c} \Big|_{\frac{T}{2}}^T \right]$$

$$= \frac{1}{T} \left[\frac{1}{\pi k F_c} \frac{(1 - e^{-j\pi k})}{j2} - \frac{1}{\pi k F_c} \frac{(e^{-j\pi k} - e^{-j2\pi k})}{j2} \right]$$

$$= \frac{1}{\pi k F_c} \times \frac{1}{T} \left[e^{-j\frac{\pi k}{2}} \sin\left(\frac{\pi k}{2}\right) - e^{-j\frac{3\pi k}{2}} \sin\left(\frac{\pi k}{2}\right) \right]$$

$$= \frac{1}{\pi k} \sin\left(\frac{\pi k}{2}\right) \left[e^{-j\frac{\pi k}{2}} - e^{-j\frac{3\pi k}{2}} \right]$$

$$= \frac{1}{\pi k} \sin\left(\frac{\pi k}{2}\right) e^{-j\pi k} \left(\frac{e^{+j\frac{\pi k}{2}} - e^{-j\frac{\pi k}{2}}}{j2} \right) \times j2$$

$$= \frac{1}{\pi k} \times j2 \times \sin^2\left(\frac{\pi k}{2}\right) e^{-j\pi k} = \begin{cases} 0, & k \rightarrow \text{Even} \\ \neq 0, & k \rightarrow \text{Odd} \end{cases}$$

$$= \frac{j2}{\pi k} e^{-j\pi k}$$

$$= \frac{-j2}{\pi k} = \frac{2}{j\pi k}$$

for k (even), $C_k = 0$

$$C_1 = \frac{1}{\pi} \times j2 \sin^2\left(\frac{\pi}{2}\right) e^{-j\pi}$$

$$C_{-1} = \frac{1}{-\pi} \times j2 \sin^2\left(\frac{\pi}{2}\right) e^{j\pi}$$

$$C_1 + C_{-1} = \frac{1}{\pi} \left(e^{-j\pi} - e^{j\pi} \right) \times j2$$

$$= \frac{1}{\pi} \frac{e^{-j\pi} - e^{j\pi}}{j2}$$

$$= \frac{4}{\pi} \sin \pi$$

$$\cos \pi + j \sin \pi$$

$$c(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_c t}$$

Odd k

$$= \left(C_1 e^{j2\pi F_c t} + C_{-1} e^{-j2\pi F_c t} \right) + \dots$$

$$= \left(\frac{1}{\pi} j2 \cdot \sin^2\left(\frac{\pi}{2}\right) e^{-j\pi} \times e^{j2\pi F_c t} \right) + \left(\frac{1}{-\pi} j2 \times \sin^2\left(\frac{\pi}{2}\right) e^{j\pi} \times e^{-j2\pi F_c t} \right)$$

$$= -\frac{j2}{\pi} e^{j2\pi F_c t} + \frac{j2}{\pi} e^{-j2\pi F_c t}$$

$$= \frac{2 \times 2}{\pi} \left\{ \frac{e^{j2\pi F_c t} - e^{-j2\pi F_c t}}{j \times 2} \right\} = \frac{4}{\pi} \sin(2\pi F_c t)$$

$$\begin{aligned}
& C_3 e^{j2\pi(3F_c)t} + C_{-3} e^{-j2\pi(3F_c)t} \\
&= \frac{2}{j\pi(3)} e^{j2\pi(3F_c)t} + \frac{2}{j\pi(-3)} e^{-j2\pi(3F_c)t} \\
&= \frac{2 \times 2}{3\pi} \frac{e^{j2\pi(3F_c)t} - e^{-j2\pi(3F_c)t}}{j \times 2} \\
&= \underline{\underline{\frac{4}{3\pi} \sin(2\pi(3F_c)t)}}
\end{aligned}$$

$$\begin{aligned}
& \frac{4}{\pi} \sin(2\pi F_c t) + \frac{4}{3\pi} \sin[2\pi(3F_c)t] + \dots \\
&= \frac{4}{1}
\end{aligned}$$

$$\begin{aligned}
C_k &= \frac{1}{T} \left\{ \int_0^{\frac{T}{2}} e^{j2\pi k F_c t} dt - \int_{\frac{T}{2}}^T e^{-j2\pi k F_c t} dt \right\} \\
&= \frac{1}{T} \left\{ \frac{e^{-j2\pi k F_c t}}{-j2\pi k F_c} \Big|_0^{\frac{T}{2}} - \frac{e^{-j2\pi k F_c t}}{-j2\pi k F_c} \Big|_{\frac{T}{2}}^T \right\}
\end{aligned}$$

$$= \frac{1}{-j2\pi k F_c T} \left\{ \left(e^{-j2\pi k F_c \frac{T}{2}} - e^0 \right) - \left(e^{-j2\pi k F_c T} - e^{-j2\pi k F_c \frac{T}{2}} \right) \right\}$$

$$= \frac{1}{-j2\pi k F_c T} \left\{ \left(e^{-j\pi k} - 1 \right) - \left(e^{-j2\pi k} - e^{-j\pi k} \right) \right\}$$

$$= \frac{1}{j2\pi k F_c T} \left\{ 1 - 2e^{-j\pi k} + e^{-j2\pi k} \right\}$$

$$= \frac{1}{j2\pi k F_c T} (1 - e^{-j\pi k})^2 = \begin{cases} 0, & k: \text{Even} \\ \frac{2}{j\pi k}, & k: \text{Odd} \end{cases}$$

$$C_k = \begin{cases} 0 & k: \text{even} \\ \frac{2}{j\pi k} & k: \text{odd} \end{cases}$$

$$C_0 = 0$$

$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{+j\pi k F_c t}$$

$$= \sum_{k=-\infty}^{\infty} \frac{2}{j\pi k} e^{j2\pi k F_c t}$$

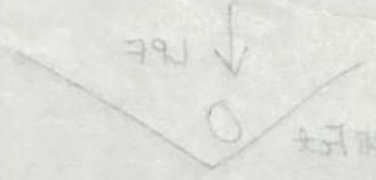
$$= \frac{2}{j\pi} e^{j2\pi F_c t} - \frac{2}{j\pi} e^{-j2\pi F_c t}$$

$$= \frac{2 \times 2}{j\pi} \frac{e^{j2\pi F_c t} - e^{-j2\pi F_c t}}{2}$$

$$= \frac{4}{\pi} \sin(2\pi F_c t)$$

⇒ 2 messages are multiplexed on a common carrier, hence this scheme is termed as Double Sideband (DSB)

$$\cos(2\pi F_c t) = \sin(2\pi F_c t) = \frac{1}{2} \sin(4\pi F_c t)$$



Therefore $\cos(2\pi F_c t)$ & $\sin(2\pi F_c t)$ are orthogonal carriers

Q. 1. This Orthogonality can be used to recover $m_1(t)$ & $m_2(t)$ at Receiver

QCM (Quadrature Carrier Multiplexing)

Consider 2 Carrier signals (Phase Difference = $\frac{\pi}{2}$)
 \Rightarrow Carriers are in quadrature.

$$\cos(2\pi F_c t) \quad \sin(2\pi F_c t)$$

$$\sin(2\pi F_c t + \frac{\pi}{2}) = \cos(2\pi F_c t)$$

$$x(t) = A_c \underbrace{m_I(t)} \cos(2\pi F_c t) - A_c \underbrace{m_Q(t)} \sin(2\pi F_c t)$$

2 message signals: $m_I(t)$, $m_Q(t)$

$m_I(t)$ is the message, modulated by $\cos(2\pi F_c t)$
or Inphase carrier

$m_Q(t)$ is the message, modulated by $\sin(2\pi F_c t)$
or Quadrature carrier.

\Rightarrow 2 messages are multiplexed on Quadrature carriers, hence this scheme is termed as Quadrature Carrier Multiplexing (QCM)

$$\cos(2\pi F_c t) \cdot \sin(2\pi F_c t) = \frac{1}{2} \sin(4\pi F_c t)$$

Therefore $\cos(2\pi F_c t)$ & $\sin(2\pi F_c t)$ are orthogonal carriers

\downarrow LPF
0

This Orthogonality can be used to recover $m_I(t)$, $m_Q(t)$ at Receiver

Demodulation with $\cos(2\pi F_c t)$

$$x(t) \cdot \cos(2\pi F_c t) = \left(A_c m_I(t) \cos(2\pi F_c t) - A_c m_Q(t) \sin(2\pi F_c t) \right) \cos(2\pi F_c t)$$

$$= A_c m_I(t) \cos^2(2\pi F_c t) - A_c m_Q(t) \sin(2\pi F_c t) \cdot \cos(2\pi F_c t)$$

$$= \frac{A_c m_I(t)}{2} (1 + \cos(4\pi F_c t)) - \frac{A_c m_Q(t)}{2} \sin(4\pi F_c t)$$

$$= \underbrace{\frac{A_c m_I(t)}{2}}_{\text{Baseband Component}} + \underbrace{\frac{A_c m_I(t)}{2} \cos(4\pi F_c t)}_{\pm 2F_c} - \underbrace{\frac{A_c m_Q(t)}{2} \sin(4\pi F_c t)}_{+2F_c}$$

Baseband
Component

↓ LPF

$$\frac{A_c m_I(t)}{2}$$

Inphase signal is received.

Demodulate $m_Q(t)$ with $\sin(2\pi F_c t)$

$$x(t) \cdot \sin(2\pi F_c t) = A_c m_I(t) \cos(2\pi F_c t) \sin(2\pi F_c t) - A_c m_Q(t) \sin^2(2\pi F_c t)$$

$$= \frac{A_c m_I(t)}{2} \sin(4\pi F_c t) - \frac{A_c m_Q(t)}{2} (1 - \cos(4\pi F_c t))$$

$$= \frac{A_c m_I(t)}{2} \sin(4\pi F_c t) - \frac{A_c m_Q(t)}{2} + \frac{A_c m_Q(t)}{2} \cos(4\pi F_c t)$$

↓ LPF

$$-\frac{A_c m_Q(t)}{2}$$

Inverted
message signal is recovered

$$\cos 2\theta = 1 - 2\sin^2 \theta$$

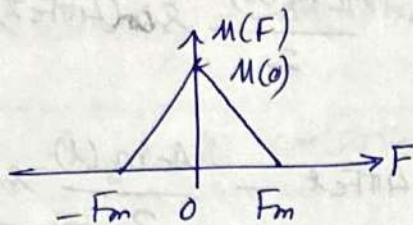
$$\Rightarrow \sin^2 \theta = \frac{1 - \cos 2\theta}{2}$$

SINGLE SIDEBAND MODULATION (SSB)

Consider a message signal $m(t)$

$$m(t) \xleftrightarrow{F.T.} M(F)$$

One sided bandwidth



$$\boxed{BW = F_m}$$

 of $m(t)$

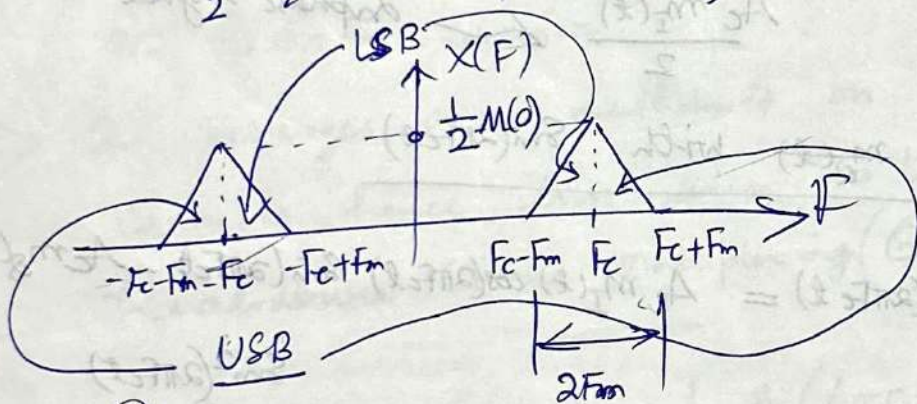
Consider the modulated signal

$$x(t) = m(t) \cdot \cos(2\pi F_c t)$$

$F_c \rightarrow$ Carrier Frequency

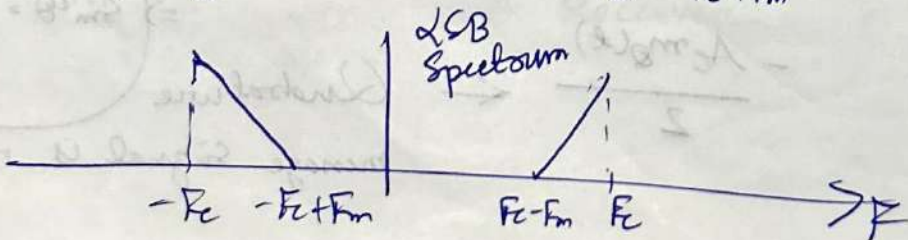
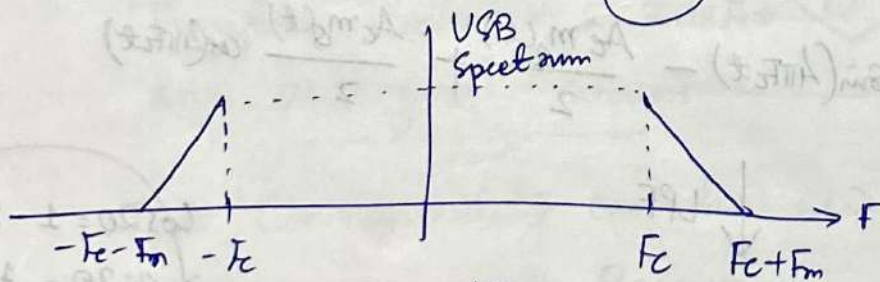
$$X(F) = M(F) * \frac{1}{2} \{ \delta(F - F_c) + \delta(F + F_c) \}$$

$$= \frac{1}{2} \{ M(F - F_c) + M(F + F_c) \}$$



Passband bandwidth of the modulated signal

$$= (2F_m)$$



Advantage of single band

USB, USB; Pass-band bandwidth = F_m

Passband bandwidth of LSB/USB = F_m

$\Rightarrow \frac{1}{2} \times$ Bandwidth of DSB-SC

\Rightarrow Spectral efficiency increases.

$\approx \frac{\text{Information given}}{\text{Bandwidth}}$

Since information of SSB is same as DSB

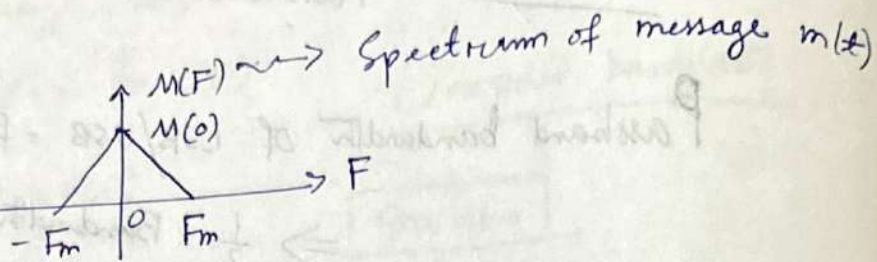
Bandwidth of SSB = ~~$\frac{1}{2}$~~ ~~Bandwidth~~ of $\frac{1}{2}$ BW of DSB.

Spectral efficiency of SSB = $2 \times$ Spectral efficiency of DSB

4/10/2023

Generation of SSB Modulated Signals

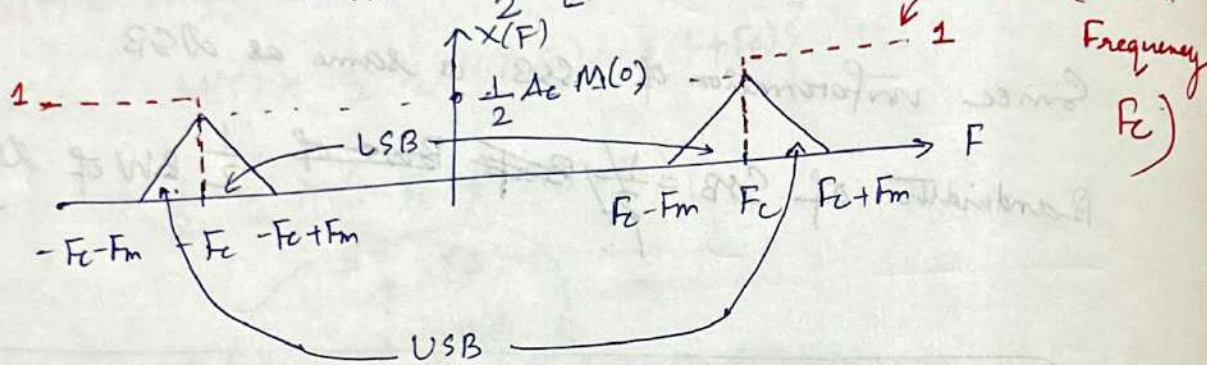
Frequency Discrimination



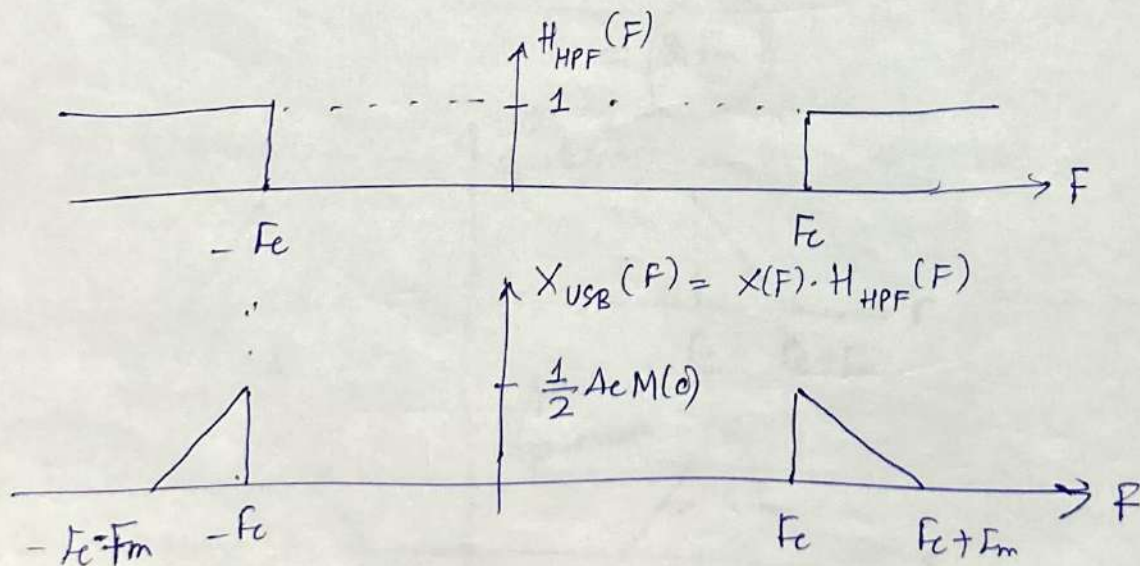
$$x(t) = A_c m(t) \cdot \cos(2\pi F_c t)$$

DSB-SC signal

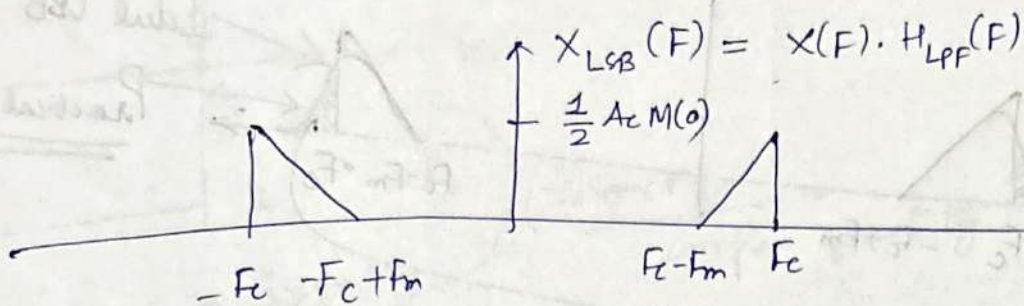
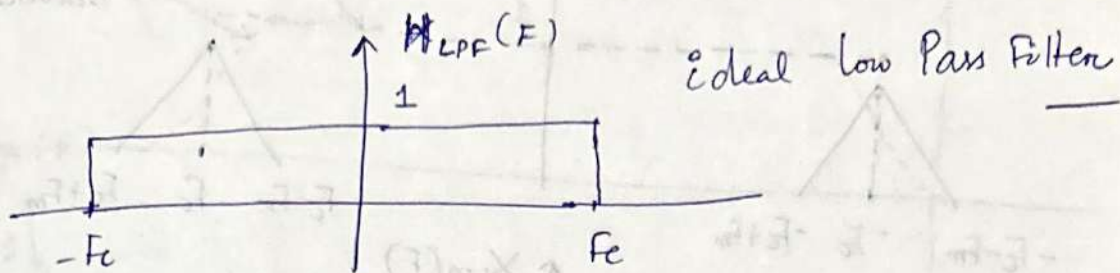
$$X(F) = \frac{A_c}{2} [M(F-F_c) + M(F+F_c)]$$



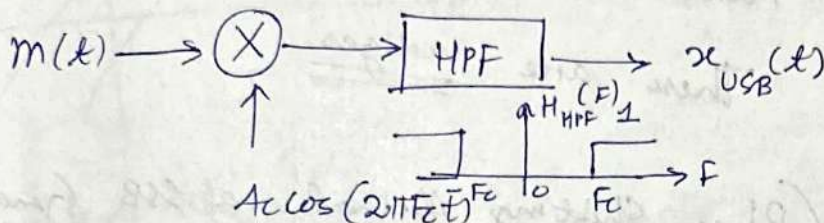
Since LSB & USB are separated in the frequency domain \Rightarrow Frequency Discrimination or filtering can be employed to extract either LSB or USB.



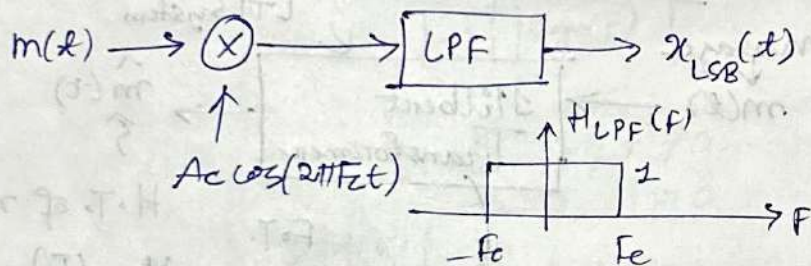
LSB Generation



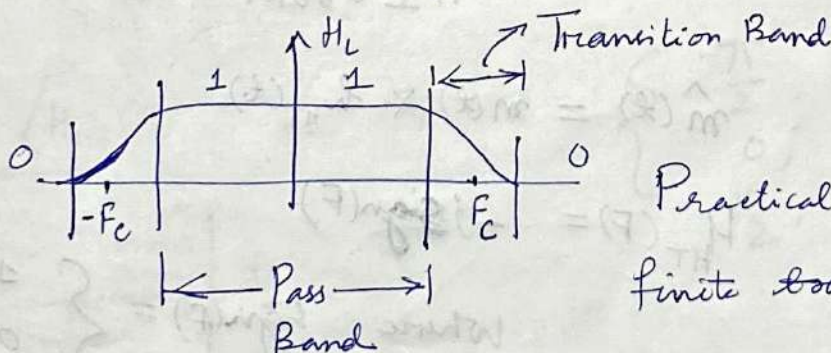
USB Generation



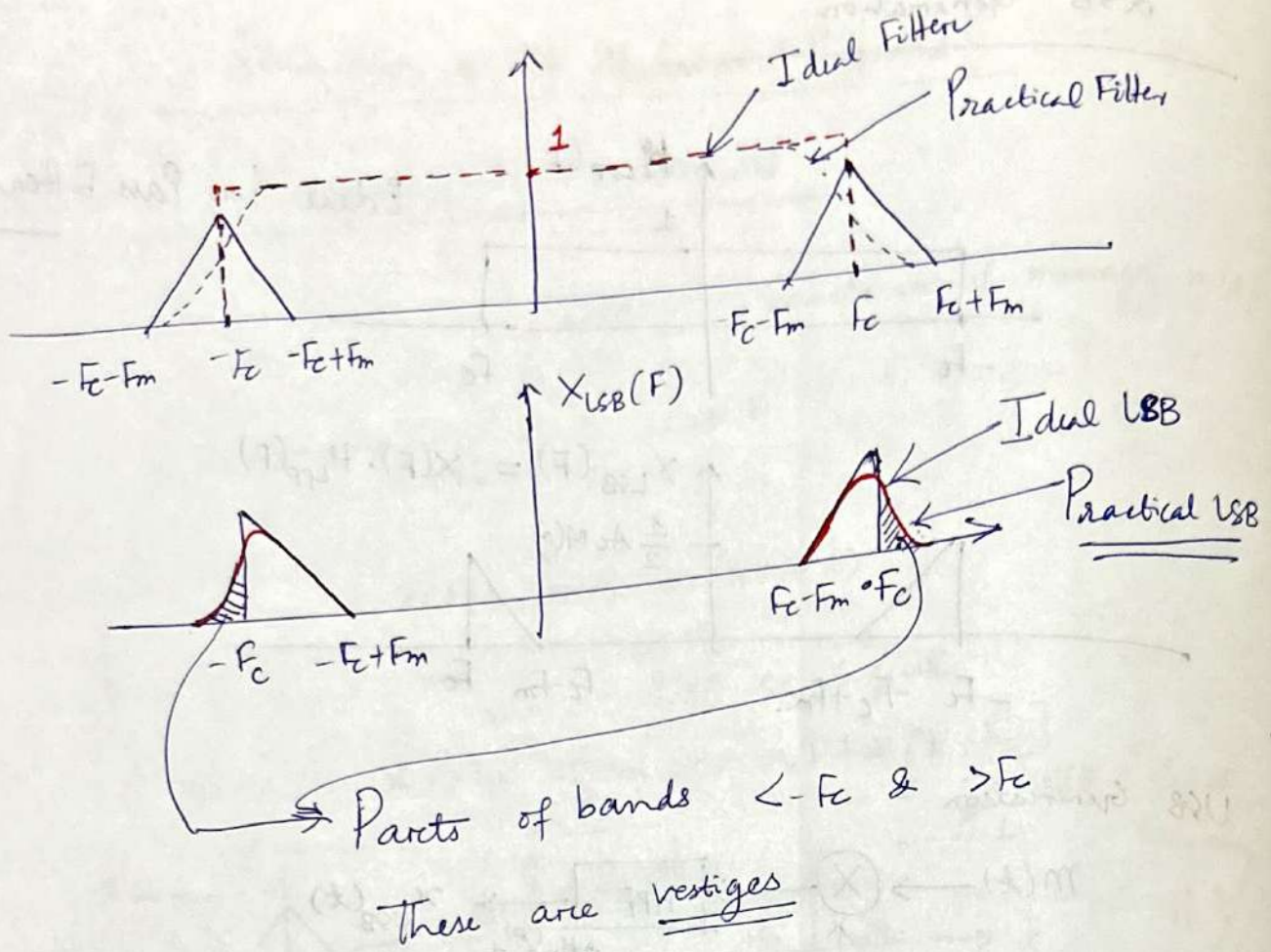
LSB Generation



In practice, it is very difficult to design filters with such sharp cut off.

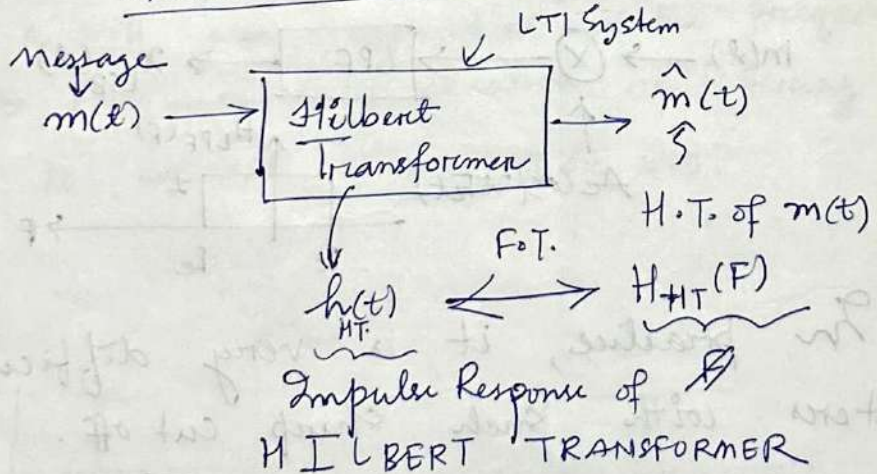


Practical Filters have finite transition bands.



(Phase Shifting Method of SSB Generation)

Hilbert Transform (Time Domain Transform)

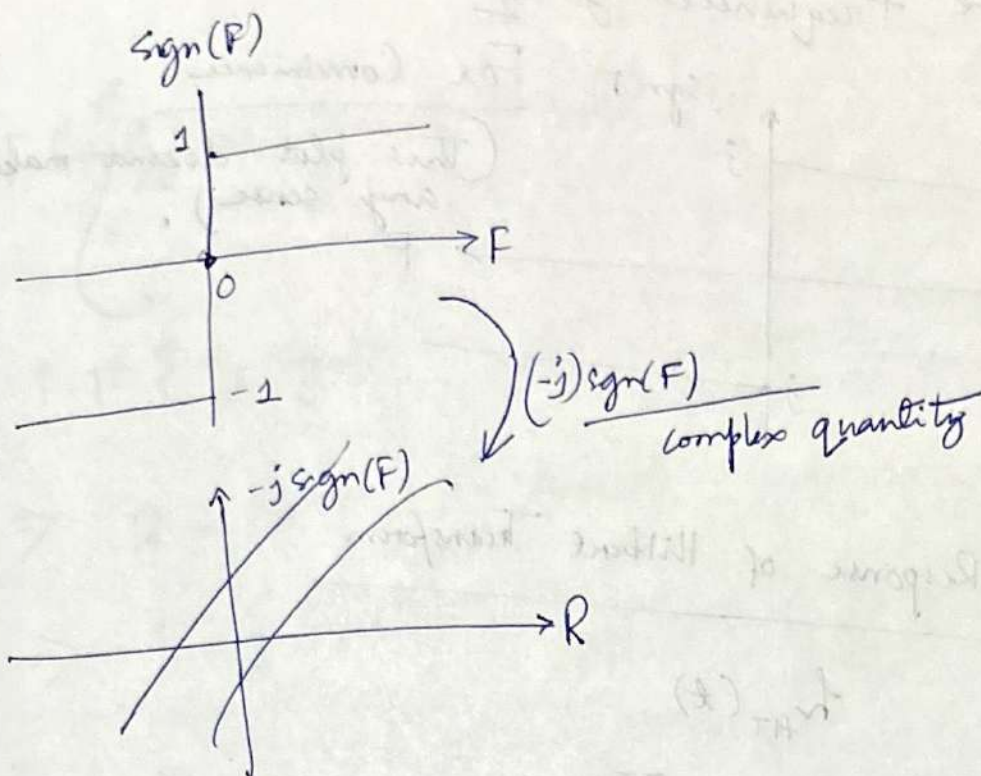


$$\hat{m}(t) = m(t) * h_{HT}(t)$$

$$H_{HT}(F) = -j \text{sign}(F)$$

Where $\text{sign}(F) = \begin{cases} 1, & F > 0 \\ 0, & F = 0 \\ -1, & F < 0 \end{cases}$

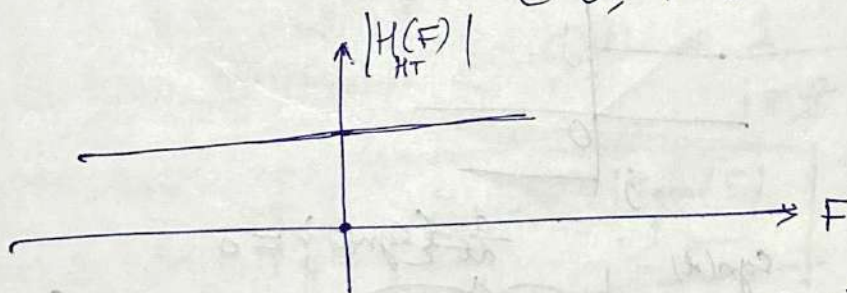
$$H_{HT}(F) = \begin{cases} -j, & F > 0 \\ 0, & F = 0 \\ j, & F < 0 \end{cases}$$



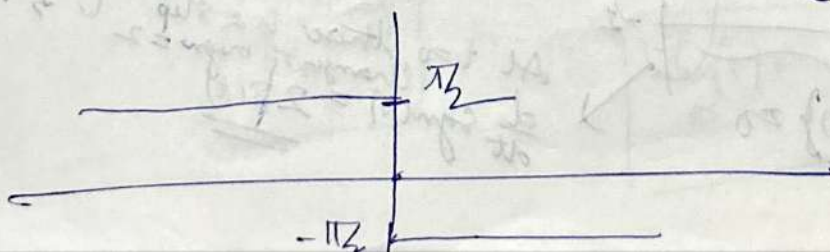
Magnitude Response :

$$\begin{aligned} |H_{HT}(F)| &= |-j\text{sgn}(F)| \\ &= |-j| |\text{sgn}(F)| \end{aligned}$$

$$= \begin{cases} 1, & F \neq 0 \\ 0, & F = 0 \end{cases}$$



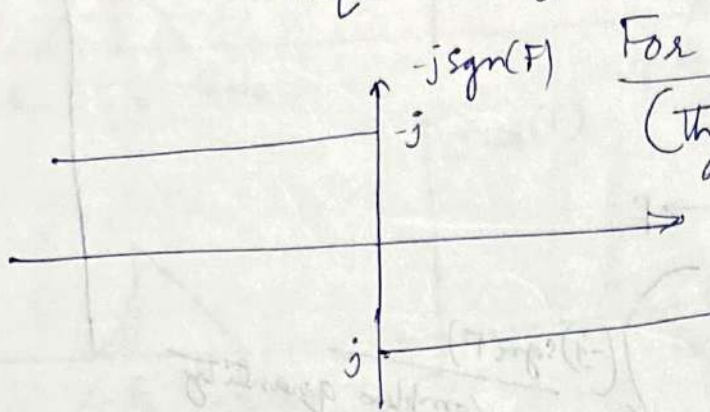
$$\angle H_{HT}(F) = \angle -j\text{sgn}(F) = \begin{cases} -\frac{\pi}{2}, & F > 0 \\ 0, & F = 0 \\ \frac{\pi}{2}, & F < 0 \end{cases}$$



HT is shifting the Phase

All +ve frequencies by $-\frac{\pi}{2}$

All -ve frequencies by $\frac{\pi}{2}$



For Conviniene

(This plot doesnot make any sense).

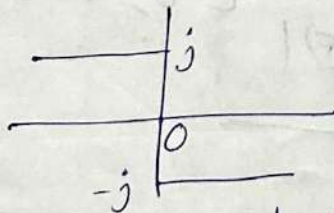
Impulse Response of Hilbert Transform

$$h_{HT}(t)$$

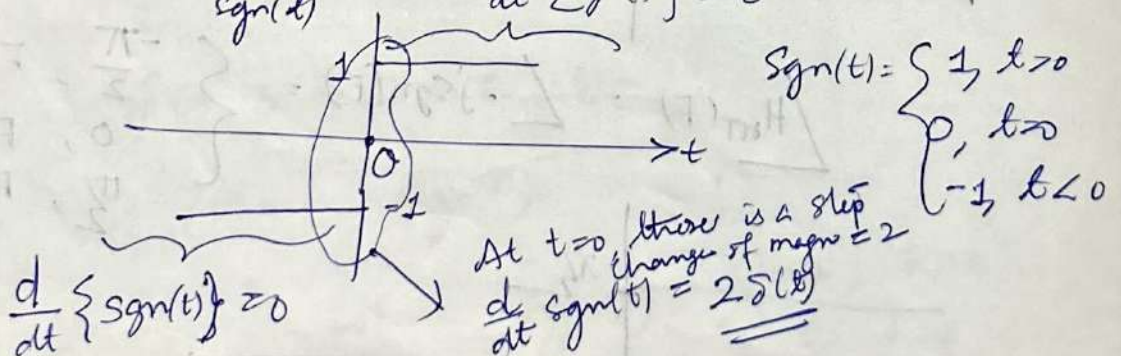
Derivative Property of FT.

$$\begin{aligned} x(t) &\longleftrightarrow X(F) \\ \frac{dx(t)}{dt} &\longleftrightarrow j2\pi F X(F) \end{aligned}$$

$$H_{HT}(F) = -j \operatorname{sgn}(F)$$



$$\operatorname{sgn}(t) \quad \frac{d}{dt} \{ \operatorname{sgn}(t) \} = 0$$



$$\frac{d}{dt} \{ \text{sgn}(t) \} = 2\delta(t)$$

$$\text{F.T. of } \frac{d}{dt} \{ \text{sgn}(t) \} = \text{FT} \{ 2\delta(t) \} = 2$$

$$\text{FT} \left\{ \frac{d}{dt} x(t) \right\} = j2\pi f X(f)$$

$$\text{F.T.} \left\{ \frac{d}{dt} \text{sgn}(t) \right\} = j2\pi f \text{FT} \{ \text{sgn}(t) \}$$

$$\Rightarrow 2 = j2\pi f \text{FT} \{ \text{sgn}(t) \}$$

$$\Rightarrow \text{FT} \{ \text{sgn}(t) \} = \frac{1}{j\pi f}$$

$$\text{sgn}(t) \leftrightarrow \frac{1}{j\pi f}$$

Duality: $x(t) \leftrightarrow X(f)$

$$\Rightarrow X(t) \leftrightarrow x(f)$$

$$\Rightarrow \frac{1}{j\pi t} \leftrightarrow \text{sgn}(-f)$$

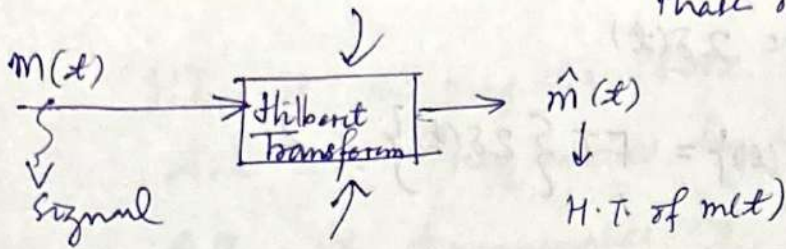
$$\Rightarrow -\text{sgn}(f) \leftrightarrow \frac{1}{j\pi t}$$

$$\Rightarrow \boxed{\frac{1}{\pi t} \leftrightarrow \underbrace{-j \text{sgn}(f)}_{H_{HT}(f)}}$$

$$\boxed{h_{HT}(t)}$$

$$\boxed{h_{HT}(t) = \frac{1}{\pi t}}$$

Phase shifter → Phase of +ve freq, by $-\pi/2$
 Phase of -ve freq, by $\pi/2$



$$H_{HT}(F) = -j \operatorname{sgn}(F)$$

$$h_{HT}(t) = \frac{1}{\pi t}$$

$$\hat{m}(t) = m(t) * \frac{1}{\pi t}$$

$$\hat{M}(F) = M(F) \cdot \left[-j \operatorname{sgn}(F) \right]$$

Product

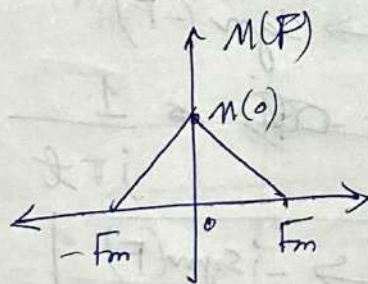
$$= -j \operatorname{sgn}(F) M(F)$$

SSB Generation Based on Phase shifting method



Employs the Hilbert Transform.

Consider message signal $m(t)$ with spectrum $M(F)$



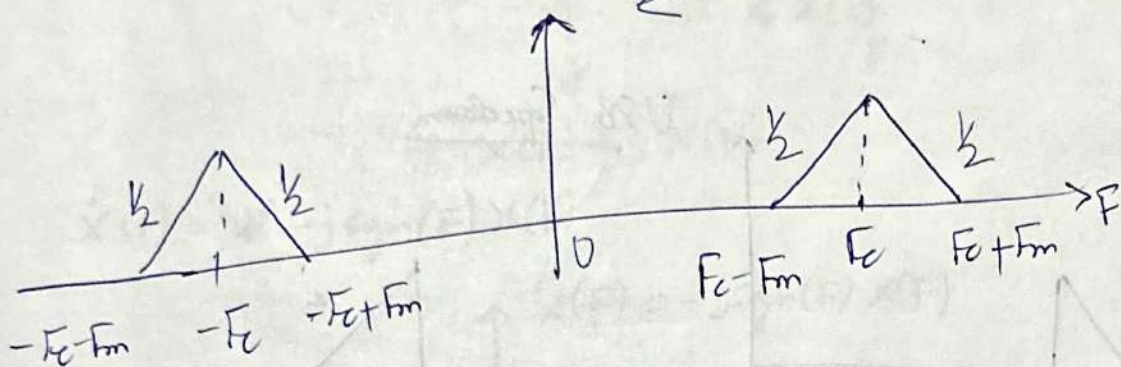
Consider the modulated signal $s(t) = m(t) \cdot \cos(2\pi F_c t) -$

$$\hat{m}(t) \sin(2\pi F_c t)$$

where $\hat{m}(t) \leftrightarrow \text{HT} \{ m(t) \}$

Since we are using $m(t)$ & the phase shifted signal $\hat{m}(t)$, this is known as Phase shifting method of generation of SSB.

$$m(t) \cos(2\pi F_c t) \leftrightarrow \frac{1}{2} [M(F-F_c) + M(F+F_c)]$$



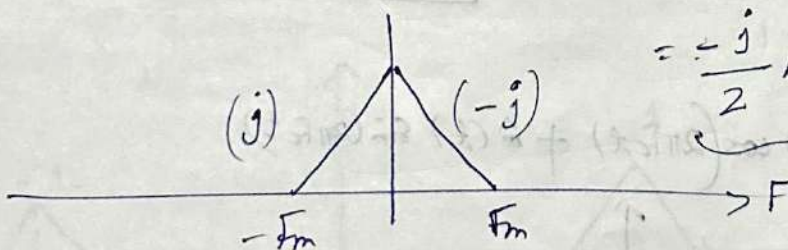
$$\hat{m}(t) \sin(2\pi F_c t) = \hat{m}(t) \left\{ \frac{e^{j2\pi F_c t} - e^{-j2\pi F_c t}}{j2} \right\}$$

$$\hat{m}(t) \leftrightarrow \hat{M}(F)$$

$$\hat{M}(F) = M(F) \{ -j \sin(F) \}$$

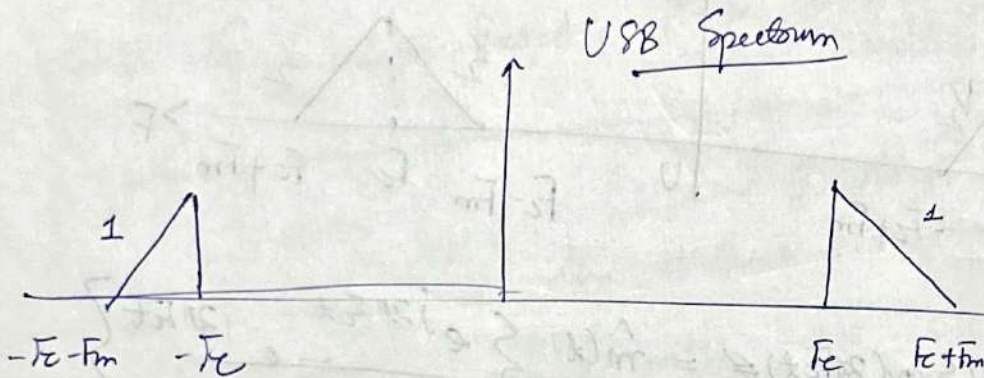
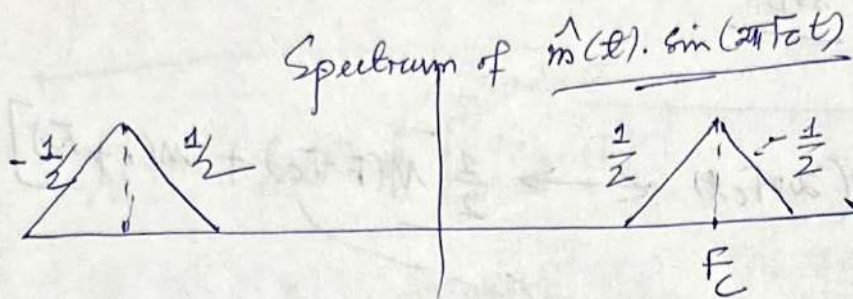
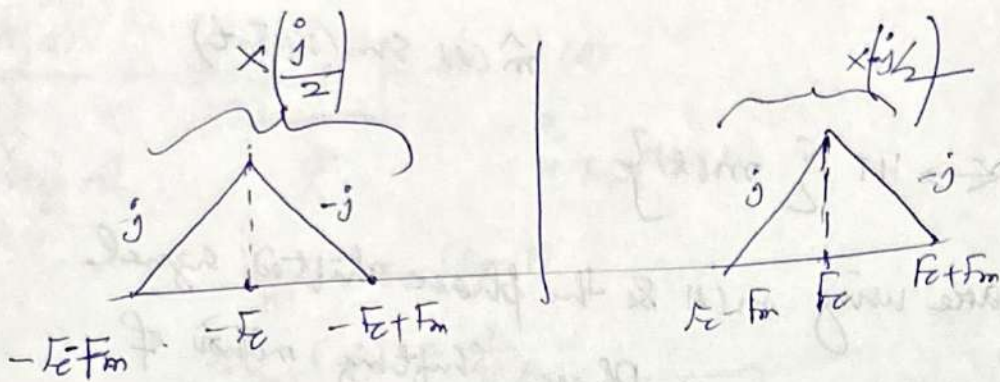
$$\hat{M}(F) * \left\{ \frac{\delta(F-F_c)}{2j} - \frac{\delta(F+F_c)}{2} \right\}$$

$$= \frac{-j}{2} \hat{M}(F-F_c) + \frac{j}{2} \hat{M}(F+F_c)$$



$$\hat{m}(t) =$$

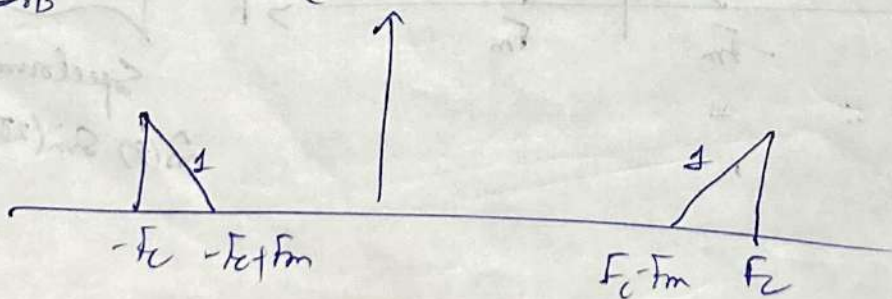
Spectrum of $\hat{m}(t) \sin(2\pi F_c t)$



$$x(t) = m(t) \cos(2\pi F_c t) - \hat{m}(t) \sin(2\pi F_c t)$$

USB
Upper Sideband Modulated Signal

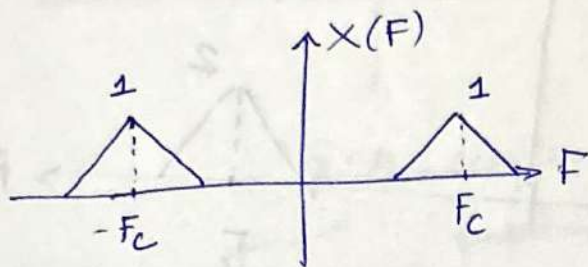
$$x(t) = m(t) \cos(2\pi F_c t) + \hat{m}(t) \sin(2\pi F_c t)$$



Complex Envelope

Consider a passband signal $x(t)$

$$x(t) \leftrightarrow X(F)$$



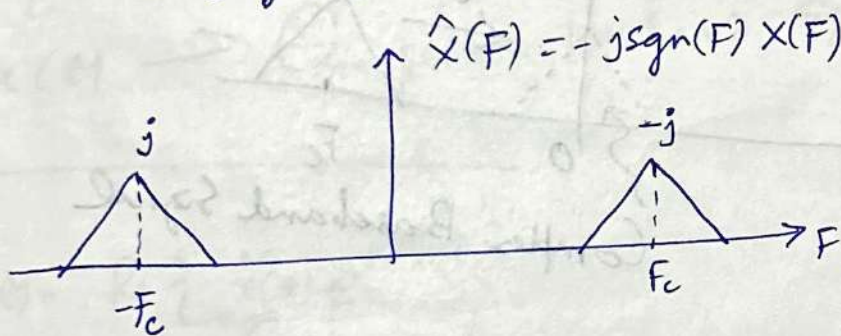
Consider a new signal,

$$x(t) + j \hat{x}(t)$$

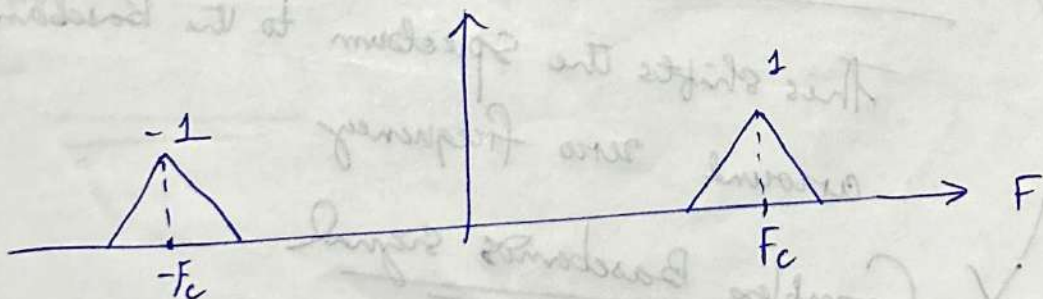
HT. of $x(t)$

$$X(F) + j \hat{X}(F)$$

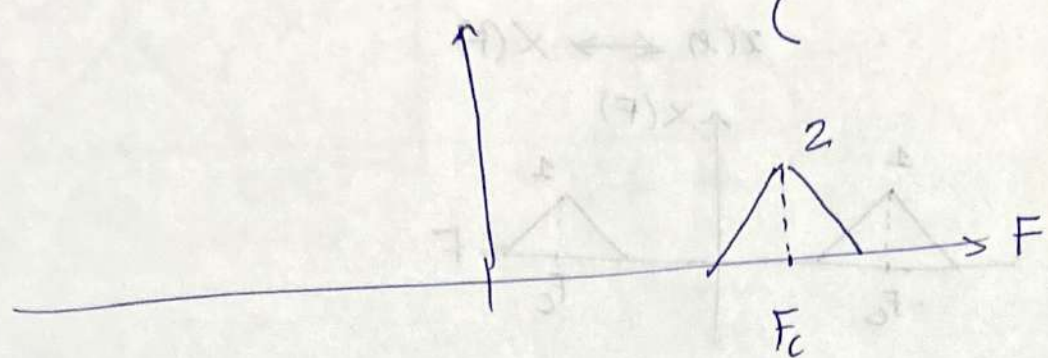
$$\hat{X}(F) = -j \operatorname{sgn}(F) X(F)$$



$$j \hat{X}(F)$$

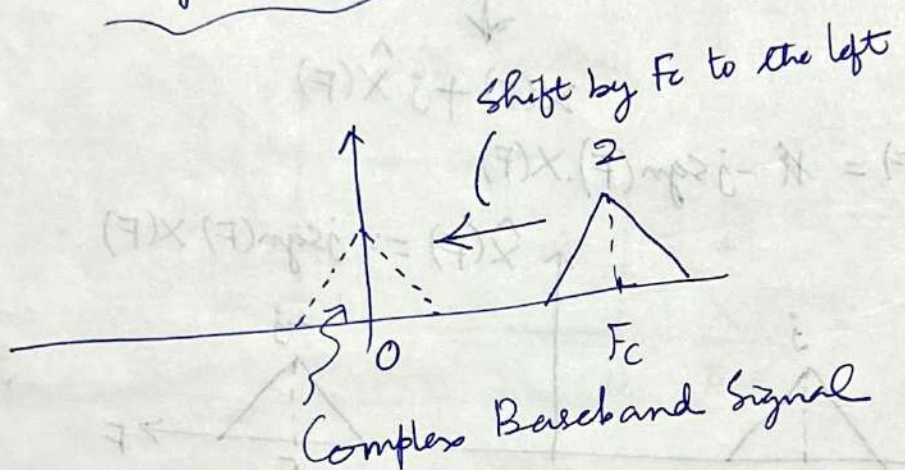


$$x(f) + j\hat{x}(f) = \begin{cases} 2x(f), & f > 0 \\ 0, & f < 0 \end{cases}$$



$$x(t) + j\hat{x}(t) \leftrightarrow \begin{cases} 2x(f), & f > 0 \\ 0, & f < 0 \end{cases}$$

Complex Pre-envelope of $x(t)$



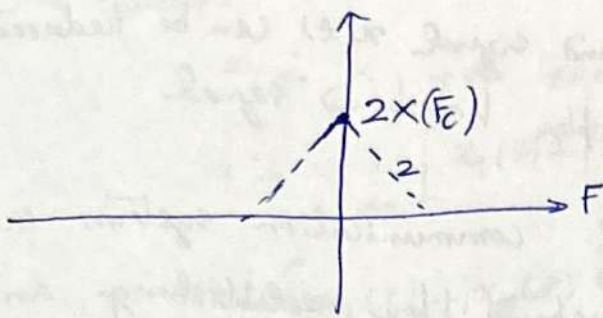
$$[x(t) + j\hat{x}(t)] \cdot e^{-j2\pi f_c t}$$

This shifts the spectrum to the Baseband; i.e., around zero frequency

Complex Baseband Signal

Complex baseband equivalent signal of passband signal $x(t)$

$\tilde{X}(F) = \text{Spectrum of } \tilde{x}(t)$



$\tilde{x}(t) = \text{complex baseband equivalent of passband signal } x(t).$

Complex Envelope of $x(t)$

$$\begin{aligned} & \text{Re} \{ \tilde{x}(t) e^{j2\pi F_c t} \} \\ &= \text{Re} \{ (x(t) + j\hat{x}(t)) e^{-j2\pi F_c t} \cdot e^{j2\pi F_c t} \} \\ &= \text{Re} \{ x(t) + j\hat{x}(t) \} \\ &= x(t) \rightarrow \text{Original passband signal} \end{aligned}$$

$$x(t) = \text{Re} \{ \tilde{x}(t) e^{j2\pi F_c t} \}$$

Passband Signal

Complex Envelope of $\tilde{x}(t) e^{j2\pi F_c t}$

So,

⇒ Every passband signal $x(t)$ can be reduced to an equivalent complex baseband signal

⇒ All the analysis of communication systems can be carried out in baseband by establishing an equivalence between ~~baseband~~ passband & complex baseband signal.

⇒ An unified framework can be developed for analysis of communication systems.

QCM Signal

↳ (Quadrature Carrier Modulation)

$$x(t) = x_I(t) \cos(2\pi F_c t) - x_Q(t) \sin(2\pi F_c t)$$

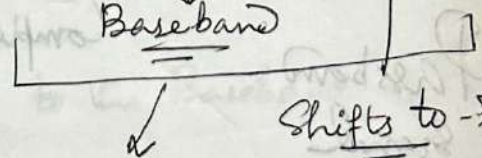
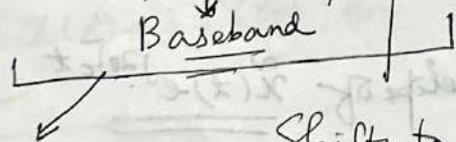


In phase Signal Quadrature Signal

$x_I(t), x_Q(t)$ ← Baseband Signals.

$$x(t) = x_I(t) \left[\frac{e^{j2\pi F_c t} + e^{-j2\pi F_c t}}{2} \right] - x_Q(t) \left[\frac{e^{j2\pi F_c t} - e^{-j2\pi F_c t}}{2j} \right]$$

$$= \frac{1}{2} \left\{ x_I(t) + j x_Q(t) \right\} e^{j2\pi F_c t} + \frac{1}{2} \left\{ x_I(t) - j x_Q(t) \right\} e^{-j2\pi F_c t}$$



Corresponds to the frequency Band

Corresponds to -ve frequency band.

Complex Pre-envelope:

$$= 2 \times \text{+ve Frequency Band Signal}$$

$$= 2 \times \frac{1}{2} [x_I(t) + jx_Q(t)] e^{j2\pi f_c t}$$

$$= \{x_I(t) + jx_Q(t)\} e^{j2\pi f_c t}$$

↓
Complex Pre-envelope of QCM signal $x(t)$.

Complex envelope $\tilde{x}(t)$ is,

$$\tilde{x}(t) = x_p(t) e^{-j2\pi f_c t}$$

$$= \{x_I(t) + jx_Q(t)\} e^{j2\pi f_c t} \cdot e^{-j2\pi f_c t}$$

$$\boxed{\tilde{x}(t) = x_I(t) + jx_Q(t)}$$

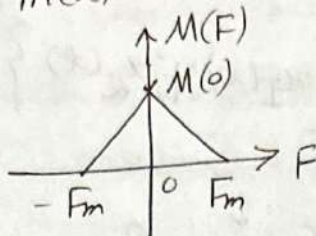
Complex Envelope or Complex Baseband equivalent of QCM signal.

VESTIGIAL SIDEBAND MODULATION

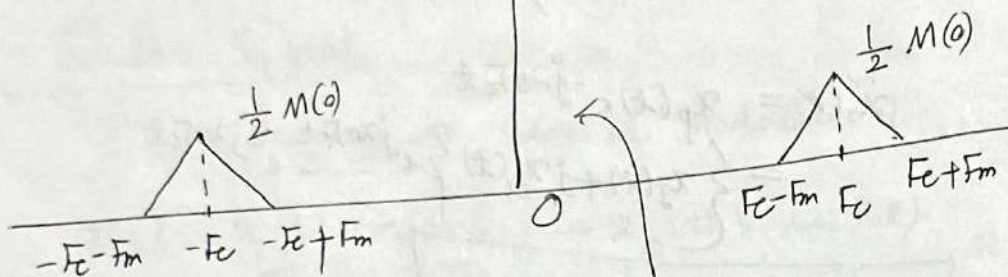
(VSB)

Why?

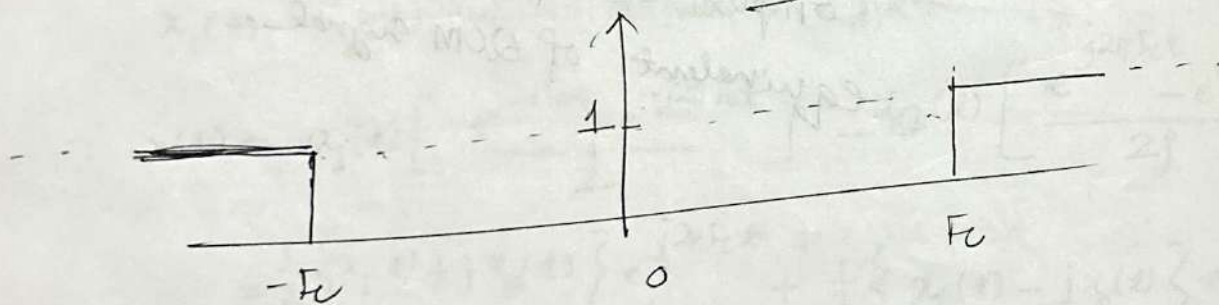
$m(t)$ ← message.



$$m(t) \cdot \cos(2\pi F_c t) \longleftrightarrow \frac{1}{2} [M(F - F_c) + M(F + F_c)]$$

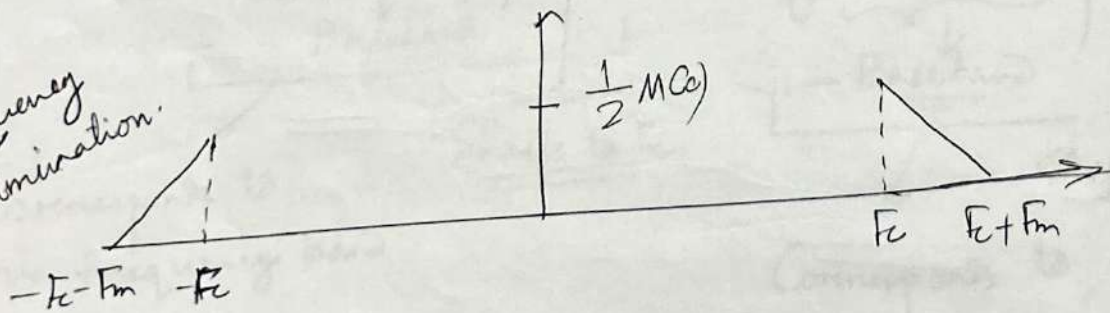


Spectrum of $m(t) \cdot \cos(2\pi F_c t)$

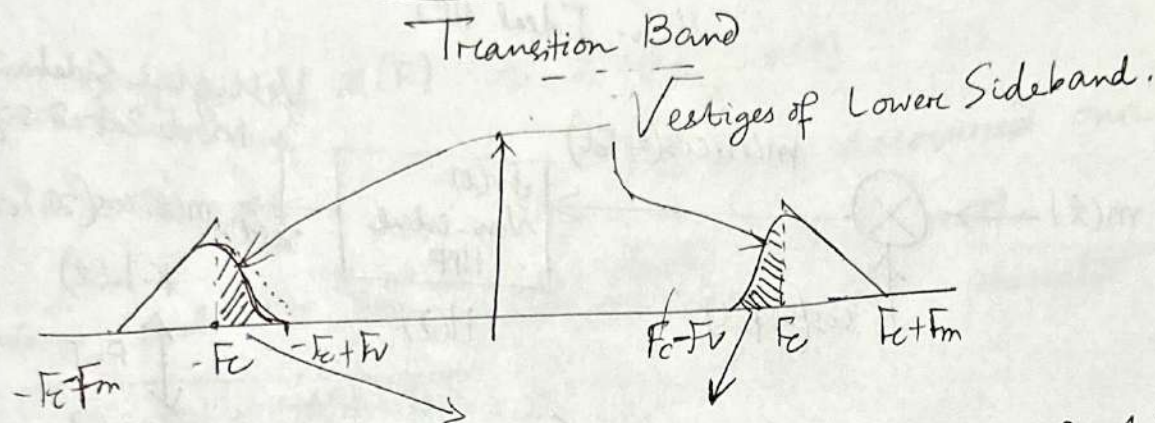
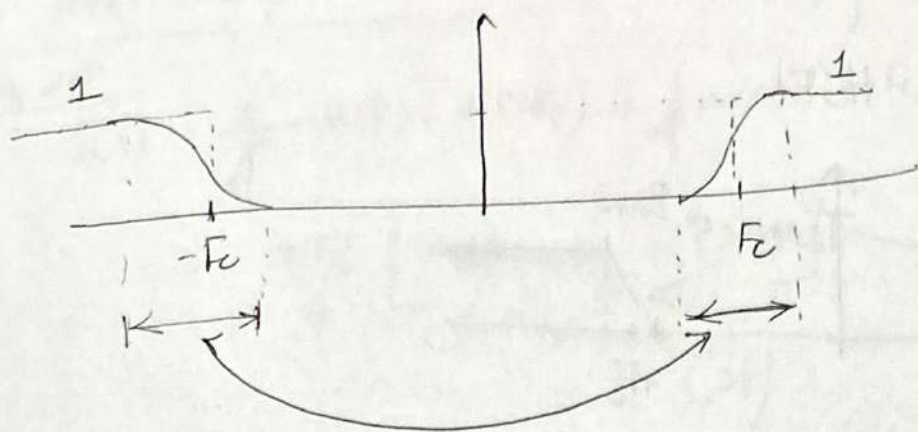


Frequency Discrimination.

for SSB Generation



To design an HPF with such sharp cut off frequency

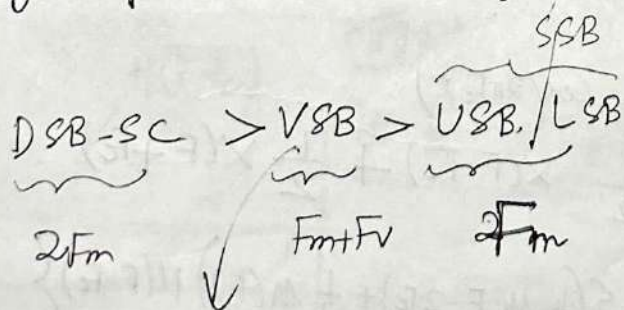


Because of Vestige requires a small portion of USB.

F_v :- Bandwidth of vestige.

Net bandwidth of the signal = $F_m + F_v$

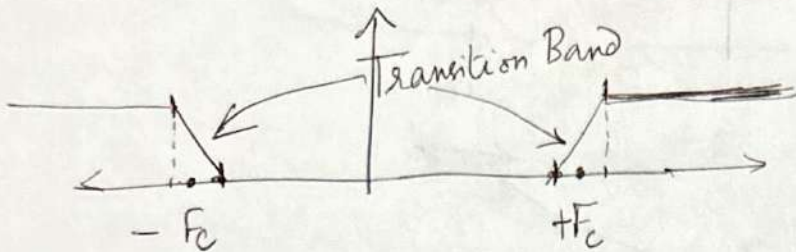
Increasing Spectral efficiency of Vestige \rightarrow



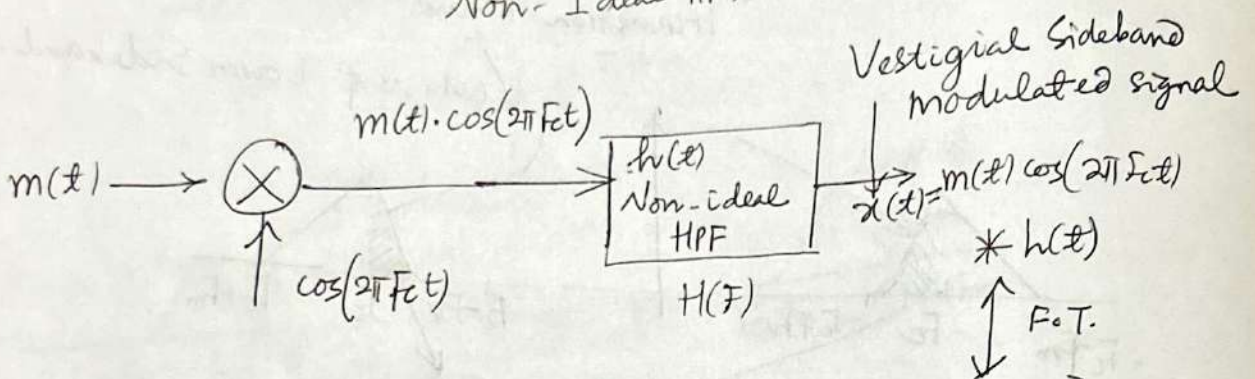
USB has lower complexity of implementation in comparison to VSB since it doesn't require ideal HPF
 (USB + Vestige of LSB)

Properties of VSB Filter

$H(f)$

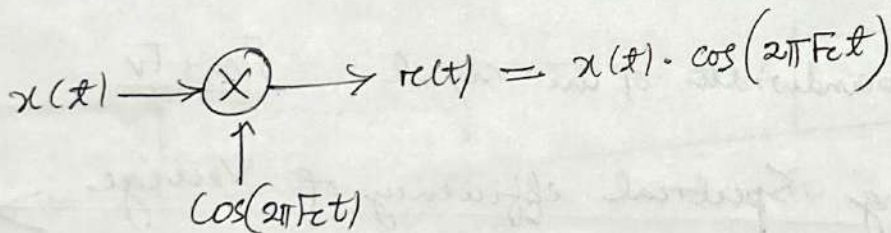


Non-Ideal HPF



$$X(f) = \left\{ \frac{1}{2} M(f-f_c) + \frac{1}{2} M(f+f_c) \right\} H(f)$$

At the Receiver:



$$r(t) = x(t) \cdot \cos(2\pi f_c t)$$

$$R(f) = \frac{1}{2} X(f-f_c) + \frac{1}{2} X(f+f_c)$$

$$= \frac{1}{2} \left\{ \left(\frac{1}{2} M(f-2f_c) + \frac{1}{2} M(f) \right) H(f-f_c) \right\}$$

$$+ \frac{1}{2} \left\{ \left(\frac{1}{2} M(f) + \frac{1}{2} M(f+2f_c) \right) H(f+f_c) \right\}$$

$$= \frac{1}{4} M(f-2f_c) \cdot H(f-f_c) + \frac{1}{4} M(f) H(f-f_c)$$

$$+ \frac{1}{4} M(f) \cdot H(f+f_c) + \frac{1}{4} M(f+2f_c) \cdot H(f+f_c)$$

$M(F-2F_c)$ & $M(F+2F_c)$ can be eliminated by LPF

Pass $rc(t)$ through an LPF

Up of LPF

$$\tilde{R}(F) = \frac{1}{4} M(F) \cdot H(F-F_c) + \frac{1}{4} M(F) H(F+F_c)$$

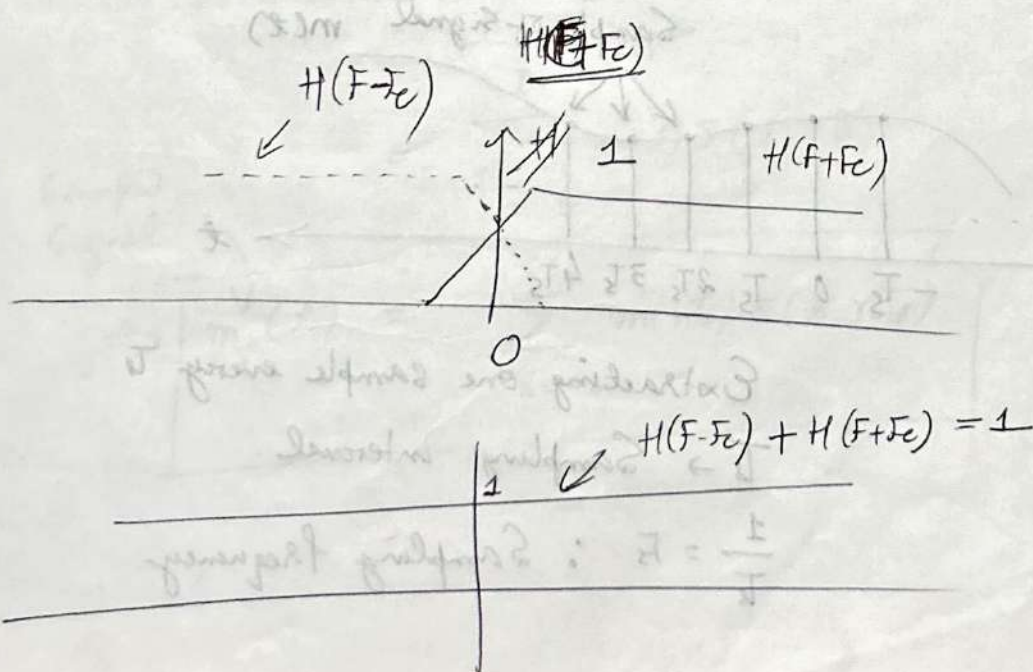
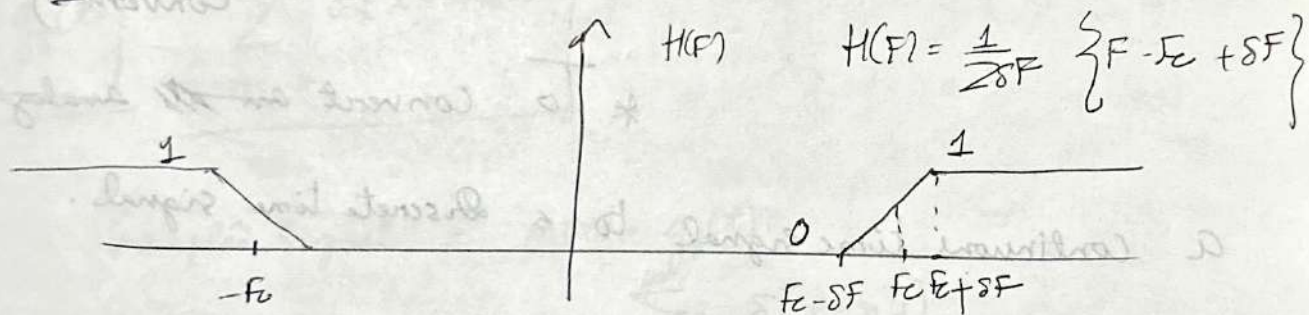
$$= \frac{M(F)}{4} \left[\underbrace{H(F-F_c) + H(F+F_c)}_{= 1 \text{ (if)}} \right]$$

$$\tilde{R}(F) = \frac{1}{4} M(F) \Rightarrow \tilde{r}(t) = \frac{1}{4} m(t)$$

\Rightarrow We have recovered our

original signal $m(t)$.
Non-ideal VSB filters must satisfy the property

$$H(F-F_c) + H(F+F_c) = 1$$



If the VSB filter is symmetric about F_c

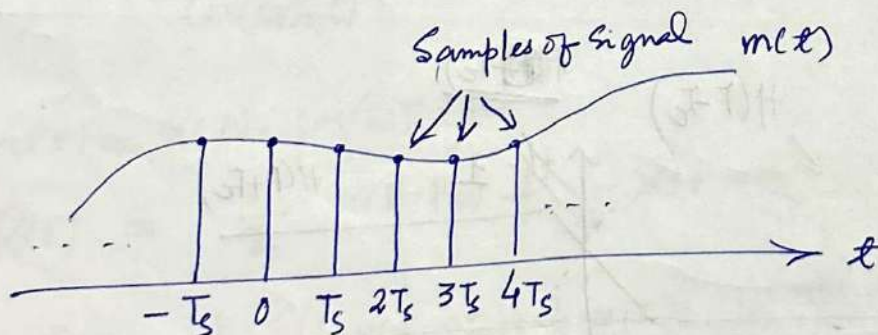
A particular non-ideal HPF which satisfies VSB property

$$H(F) = \begin{cases} \frac{1}{2\delta F} (F - F_c + \delta F) & , F_c - \delta F \leq F \leq F_c + \delta F \\ 1 & , F \geq F_c + \delta F \end{cases}$$

Analog to Digital Conversion

1. Sampling (1st step of Analog to Digital Conversion)

* To convert an ~~analog~~ analog a continuous time signal to a discrete time signal.

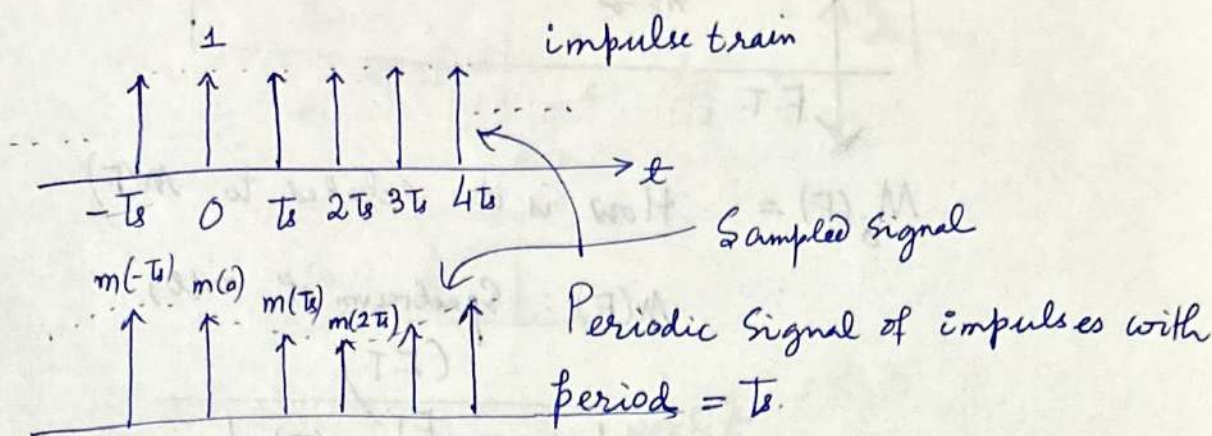
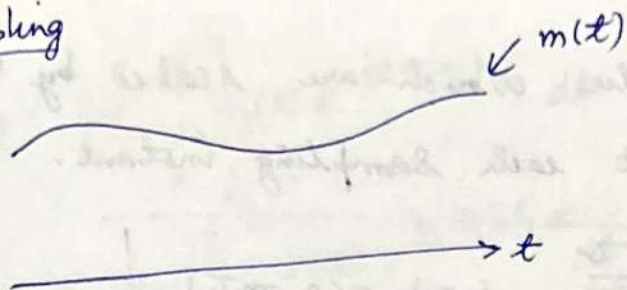


Extracting one sample every T_s

$T_s \rightarrow$ Sampling interval.

$\frac{1}{T_s} = F_s$; Sampling frequency

Ideal Sampling



Impulse train : impulses at $0, \pm T_s, \pm 2T_s, \pm 3T_s, \dots$

$$\dots + \delta(t+T_s) + \delta(t) + \delta(t-T_s) + \delta(t-2T_s) + \dots$$

$$g_s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

← impulse train

$$\text{Sampled Signal} = m(t) \cdot g_s(t)$$

$$= m(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$= \sum_{n=-\infty}^{\infty} m(t) \delta(t - nT_s)$$

Sampled Signal

$$\Rightarrow m_s(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \delta(t - nT_s)$$

Sequence of impulses which are scaled by the value of message signal at each sampling instant.

$$m_s(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \cdot \delta(t - nT_s)$$

↑
F.T.

$M_s(F)$ = How is it related to $M(F)$

$M(F)$: Spectrum of $m(t)$
(F.T.)

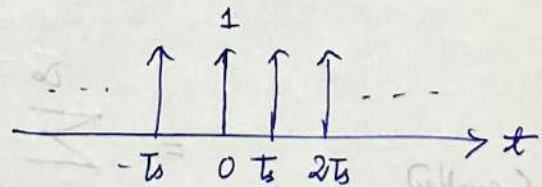
$$\left| \begin{array}{c} m(t) \xleftrightarrow{\text{FT}} M(F) \end{array} \right|$$

By sampling we lose information \rightarrow This may lead to

How to fix the parameters of sampling to minimize or if possible avoid distortion?

$$g_s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

↑
F.T.
 $G_s(F)$



Periodic signal
with period = T_s .

$$g_s(t) = \sum_{k=-\infty}^{\infty} C_k e^{j2\pi k F_s t}$$

$$(F_s = \frac{1}{T_s})$$

↓
fundamental frequency
= Sampling frequency

$$C_k = \frac{1}{T_s} \int_0^{T_s} g_s(t) e^{-j2\pi k F_s t} dt$$

$$= \frac{1}{T_s} \int_{-T_s/2}^{T_s/2} \delta(t) e^{-j2\pi k F_s t} dt = \frac{1}{T_s} \int dt = \frac{1}{T_s} \times T_s = 1$$

$$= \frac{1}{T_s} e^{-j2\pi k F_s t} \Big|_{t=0} = \frac{1}{T_s}$$

$$\therefore \boxed{C_k = \frac{1}{T_s}}$$

$$g_s(t) = \sum_{k=-\infty}^{\infty} \frac{1}{T_s} e^{j2\pi k F_s t}$$

$$\Rightarrow \boxed{g_s(t) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} e^{j2\pi k F_s t}}$$

$$\boxed{G_s(F) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \delta(F - k F_s)}$$

Impulse train in frequency domain.

Spacing between impulses = $F_s = \frac{1}{T_s}$

Spacing in time = T_s
 Spacing in frequency = $\frac{1}{T_s} = F_s$

As spacing in time domain increases
 spacing in frequency domain decreases.

Fourier Transform of Sampled Signal

Original Analog Signal

$$m_s(t) = m(t) \cdot g_s(t)$$

Sampled Analog Signal

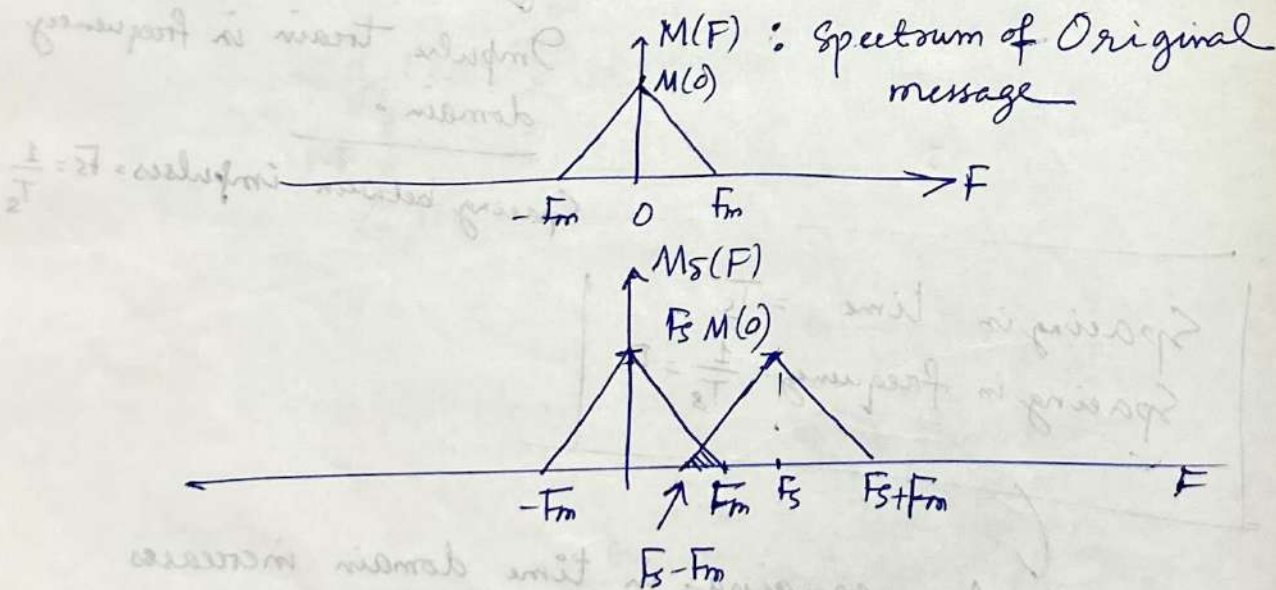
$$M_s(F) = M(F) * G_s(F)$$

$$= M(F) * \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \delta(F - kF_s)$$

$$M_s(F) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} M(F - kF_s)$$

Spectrum of Sampled signal = sum of

all copies of the original message spectrum $M(F)$ shifted to every kF_s x^{th} multiple of F_s



The overlap lead to distortion.
This distortion arises when,

$$F_s - F_m < F_m$$

$$\Rightarrow F_s < 2F_m$$

$$f_s < 2f_m$$

This distortion which occurs because of copies of spectrum shifted by multiples of f_s (kf_s) is termed as aliasing.

Aliasing occurs if

$$f_s < 2f_m$$

Sampling frequency < 2 (Max. message frequency $m(t)$)

To avoid aliasing distortion,

$$f_s \geq 2f_m$$

Nyquist criterion ~~for~~

(Or) " Sampling Theorem.

Sampling & Reconstruction

$m(t) \rightarrow$ Original signal

$$m_s(t) = m(t) \times g_s(t) = m(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

↑
impulse train

$F_s = \frac{1}{T_s}$: Sampling frequency.

$$m_s(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \delta(t - nT_s)$$

↑
Sum of impulses at nT_s scaled by $m(nT_s)$

$$M_s(F) = M(F) * G_s(F)$$
$$= M(F) * F_s \sum_{k=-\infty}^{\infty} \delta(F - kF_s)$$

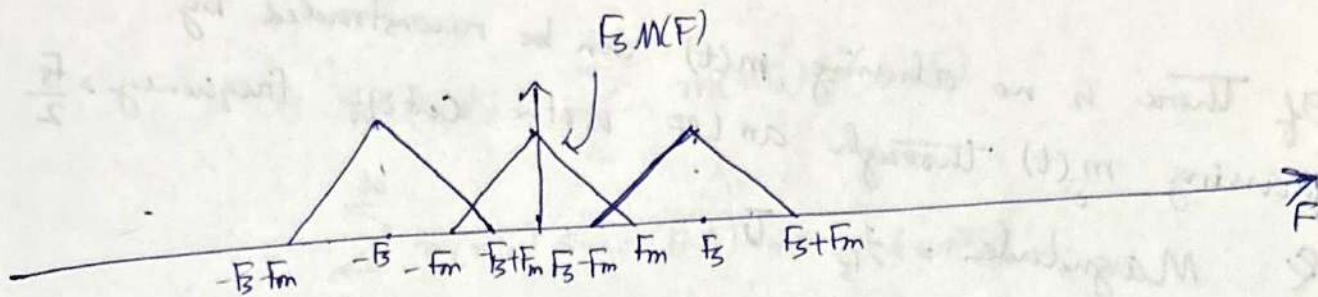
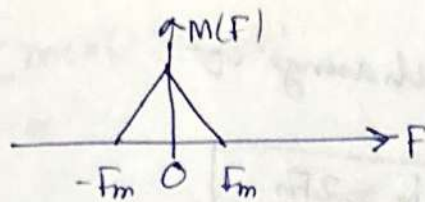
$$M_s(F) = F_s \sum_{k=-\infty}^{\infty} M(F - kF_s)$$

↑
(F.T. of sampled function)

↓

$$F_s M(F) + F_s M(F \pm F_s) + F_s M(F \pm 2F_s) + \dots$$

Sum of spectral copies of $M(F)$
sfc. shifted to each kF_s .



Overlap of spectral copies leads to distortion.

Spectrum of δ ... Sampled spectrum is a distorted version of original spectrum.

signal

ALIASING

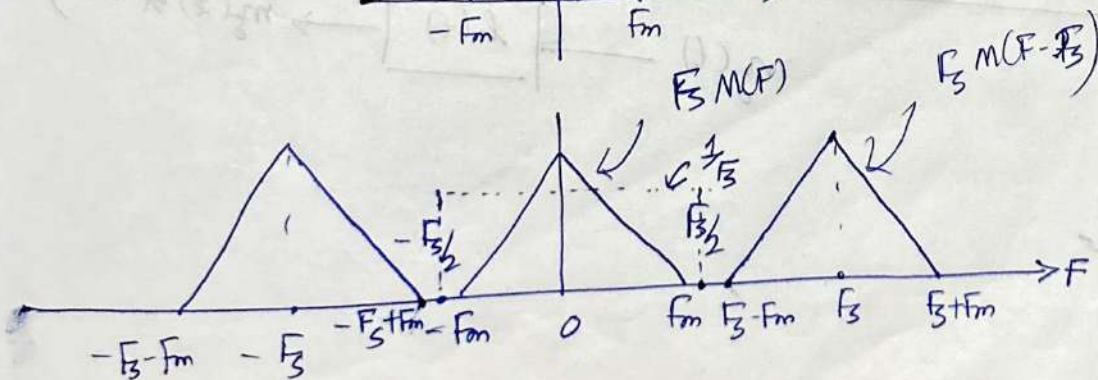
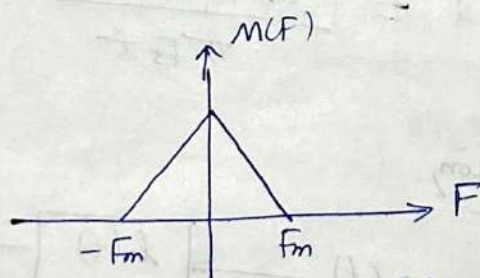
Aliasing occurs if,

$$F_s - F_m < F_m$$

$$\Rightarrow F_s < 2F_m$$

To avoid aliasing,

$$F_s \geq 2F_m \quad \text{: Nyquist criterion}$$

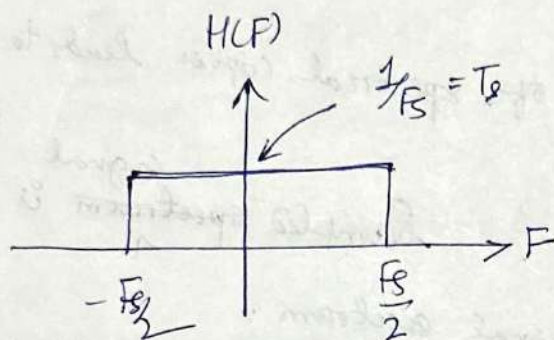


No overlap or aliasing is

$$\boxed{F_s \geq 2F_m}$$

If there is no aliasing, $m(t)$ can be reconstructed by passing $m_s(t)$ through an LPF with cutoff frequency $= \frac{F_s}{2}$

& Magnitude $= \frac{1}{F_s} = T_s$



Low pass filter for reconstruction

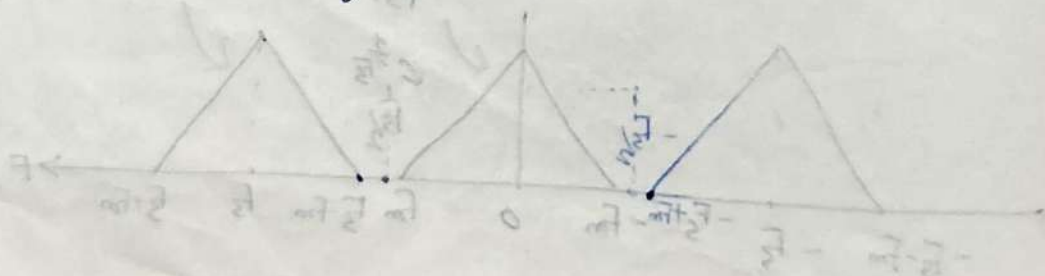
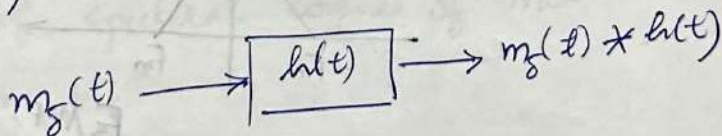
This can be derived by Duality

$$HCF = \begin{cases} T_s, & |F| \leq \frac{F_s}{2} \\ 0, & \text{otherwise} \end{cases}$$

$$\boxed{\text{FT}[HCF] \quad h(t) = \text{sinc}(F_s t)}$$

$$= \frac{\sin \pi F_s t}{\pi F_s t}$$

For reconstruction,



$$m_s(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \delta(t - nT_s)$$

$$\begin{aligned} c_m(t) &= m_s(t) * \text{sinc}(F_s t) \\ &= \text{sinc}(F_s t) * \sum_{n=-\infty}^{\infty} m(nT_s) \delta(t - nT_s) \\ &= \sum_{n=-\infty}^{\infty} m(nT_s) \text{sinc}(F_s t) * \delta(t - nT_s) \\ &= \sum_{n=-\infty}^{\infty} m(nT_s) \text{sinc}[F_s (t - nT_s)] \end{aligned}$$

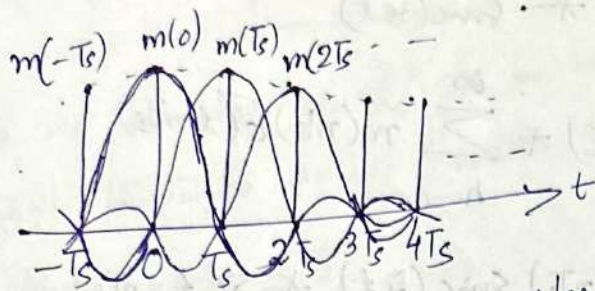
$$\Rightarrow m(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \text{sinc}(F_s t - n)$$

Shifting $\text{sinc}(F_s t)$ to each nT_s & scaling by $m(nT_s)$ followed by sum.

$$\text{sinc}(F_s t) = \frac{\sin(\pi F_s t)}{(\pi F_s t)}$$

Zeros are at $\textcircled{kT_s}$

$$\frac{\sin(\pi F_s kT_s)}{\pi F_s kT_s} = \frac{\sin k\pi}{k\pi} = 0$$



interpolating samples using sinc filters.

$$m(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \text{sinc}[F_s(t-nT_s)]$$

Shift $\text{sinc}(F_s t)$ to each nT_s scaled by

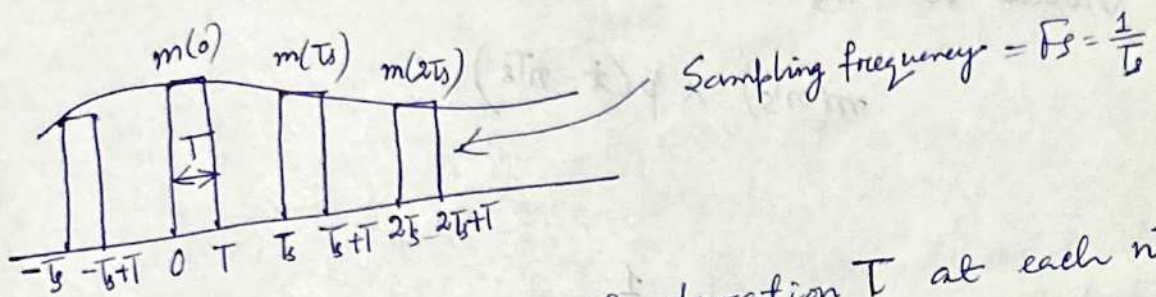
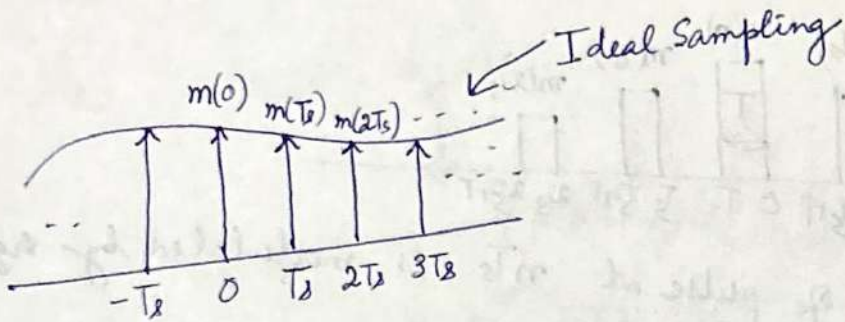
$\frac{m(nT_s)}{\text{sum of all shifted copies of}}$

$\text{sinc}(F_s t)$ ✓

sinc response : interpolation filter

$$D = \frac{\pi \sin^2}{\pi} = \frac{\sin(\pi F_s t)}{\pi F_s t}$$

PAM (Pulse Amplitude Modulation)



Sampling using pulses of duration T at each nT_s .

The n th pulse is from nT_s to $nT_s + T$ & amplitude of the pulse = $m(nT_s)$ { value of signal at nT_s }

Sampling at each nT_s & holding the sample value constant for a duration T
 → Sample & Hold Operation.

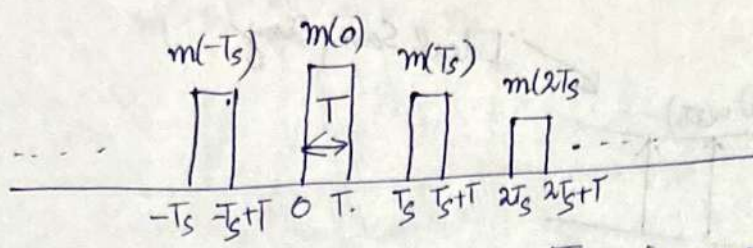
$T \ll T_s$
 Pulse Duration Sampling Interval.

~~Sample Small~~

Employs Flat-top pulses, hence also known as flat-top sampling.

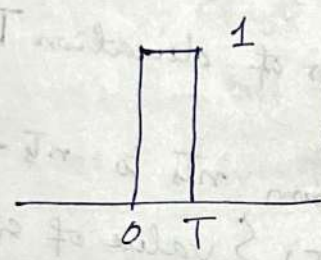
At

Pulse Amplitude Modulation (PAM)



Amplitude of pulse at nT_s is modulated by signal value at nT_s .

$$m(nT_s) \times p(t - nT_s)$$



$$\text{pulse } p(t) = \begin{cases} 1, & 0 \leq t \leq T \\ 0, & \text{otherwise} \end{cases}$$

At n^{th} sample,

$$m(nT_s) \cdot p(t - nT_s)$$

$$m_p(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \cdot p(t - nT_s)$$

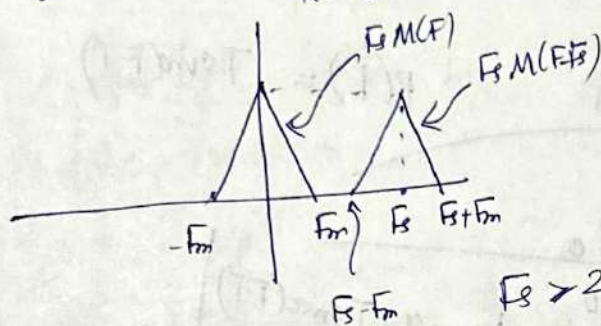
Shifting energy pulse to nT_s
& scaling by $m(nT_s)$

$$\sum_{n=-\infty}^{\infty} m(nT_s) \delta(t - nT_s) * p(t) = \sum_{n=-\infty}^{\infty} m(nT_s) p(t - nT_s)$$

So, $m_p(t) = m_s(t) * p(t)$

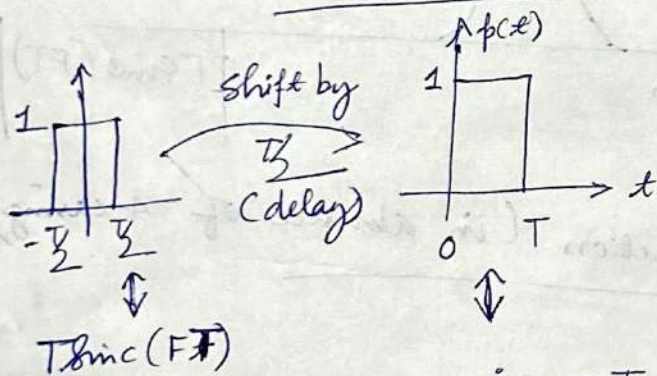
$$M_p(F) = M_s(F) \cdot P(F)$$

$$M_s(F) = F_s \sum_{k=-\infty}^{\infty} \delta(F - kF_s)$$



$F_s > 2F_m$ to avoid aliasing distortion.

$P(F)$: F.T. of $p(t)$



$$e^{-j2\pi F \frac{T}{2}} \times T \text{sinc}(FT)$$

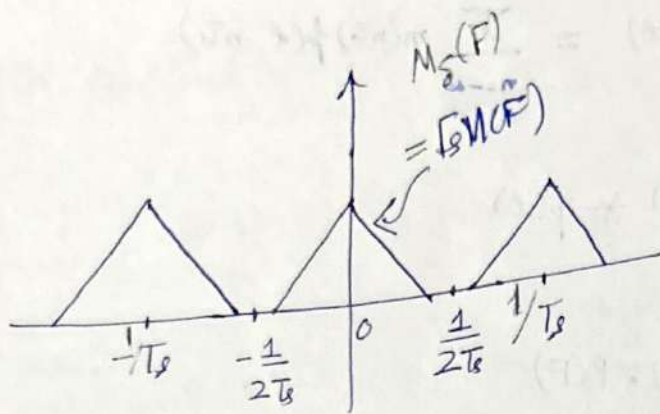
$$P(F) = T e^{-j\pi FT} \text{sinc}(FT)$$

$$|P(F)| = T \text{sinc}(FT)$$

in frequency domain
 Zeros are at $F = \frac{k}{T}$ & $k \neq 0$

$$\begin{aligned} \pi FT &= k\pi \\ \Rightarrow F &= \frac{k}{T}, \quad k \neq 0 \end{aligned}$$

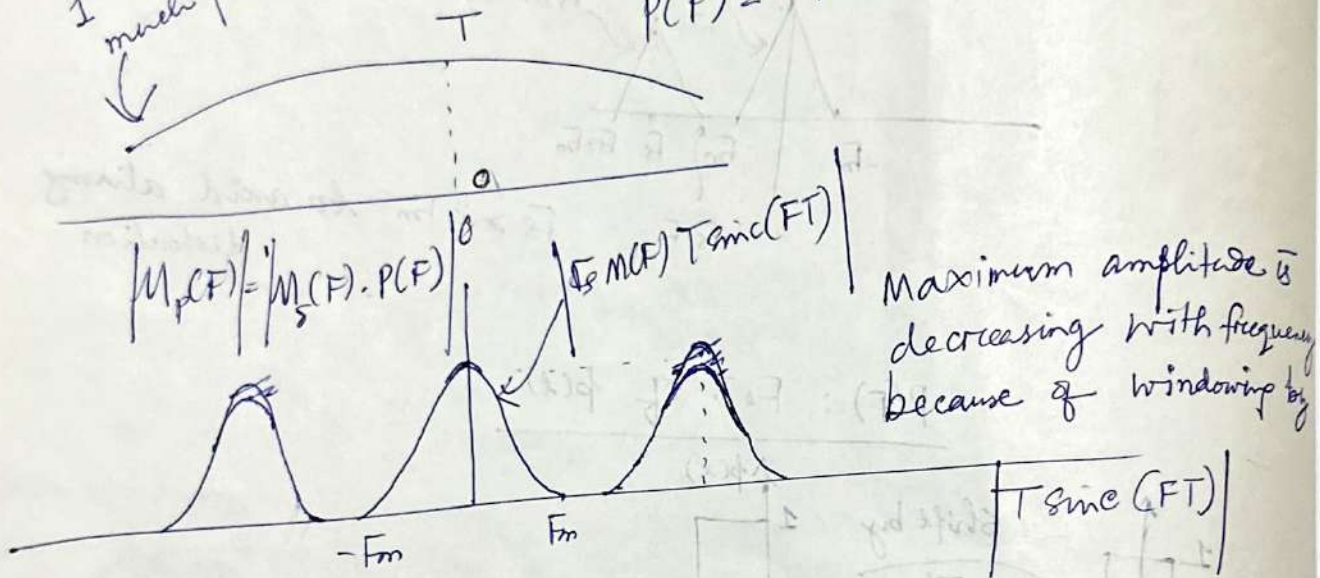
& $k \neq 0$



(4) 1st zero lies much further $\approx \frac{1}{2T_s}$

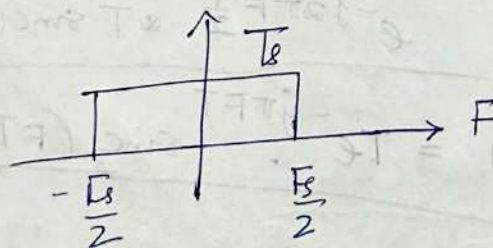
$$T < T_s \Rightarrow \frac{1}{T} > \frac{1}{T_s}$$

$$P(F) = T \sin(\pi F T)$$



For reconstruction (in absence of aliasing)

Step-1



Cut off freq = $\frac{F_s}{2}$
Amplitude = T_s

UNIT-5 SIGNALS

$$M_S'(F) = \sum_{k=-\infty}^{\infty} F_S M(F - kF_S)$$

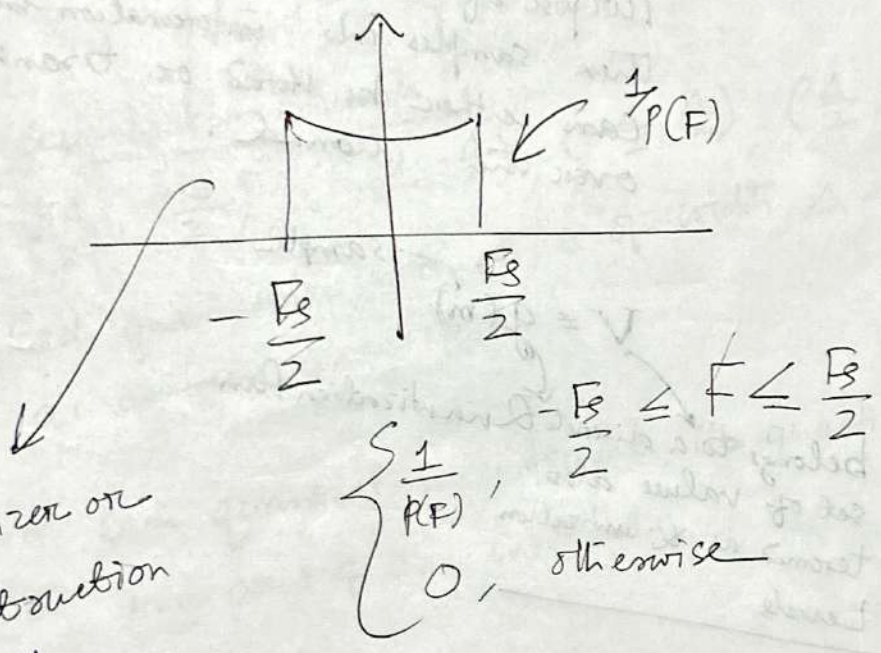
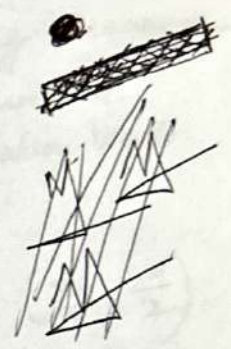
$$P(F) = T \text{sinc}(FT) e^{-j\pi FT}$$

$$M_P(F) = M_S(F) \cdot P(F)$$

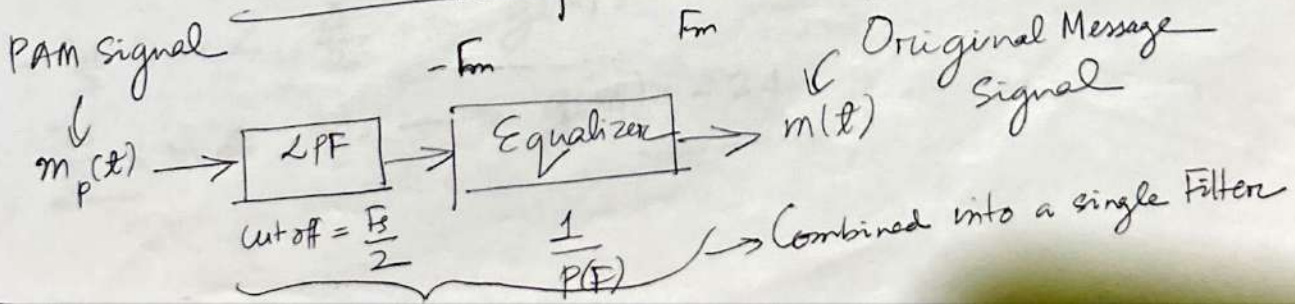
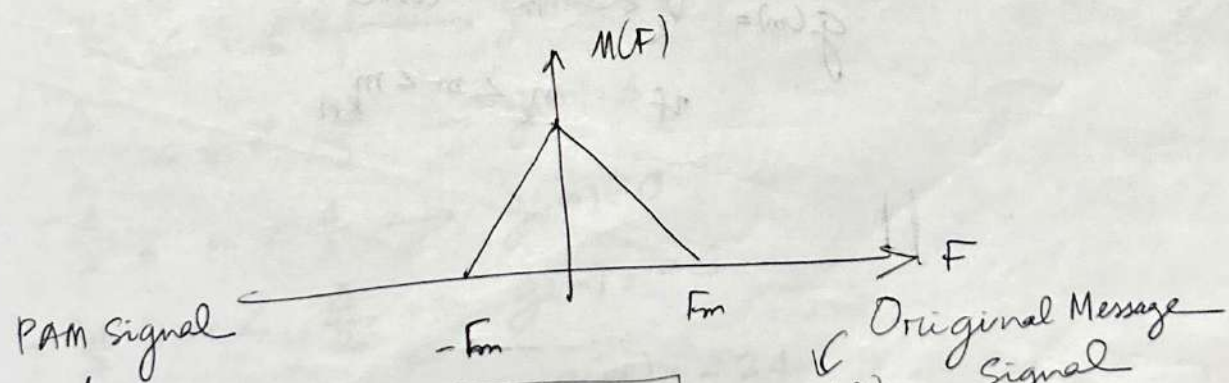
$$= \left(\sum_{k=-\infty}^{\infty} F_S M(F - kF_S) \right) \cdot e^{-j\pi FT} \cdot T \text{sinc}(FT)$$

Step 2

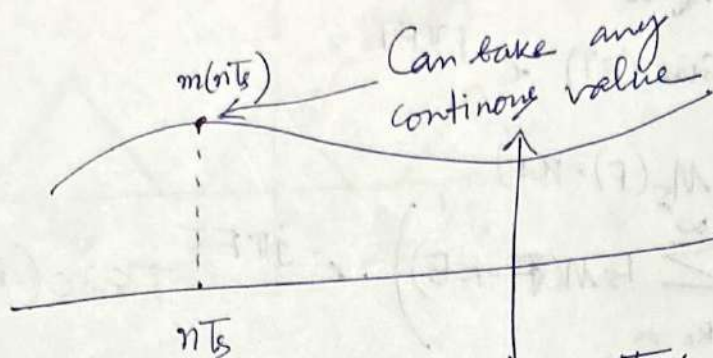
Reverse distortion caused by windowing with the sinc function.



Equalizer or Reconstruction Filter



QUANTIZATION



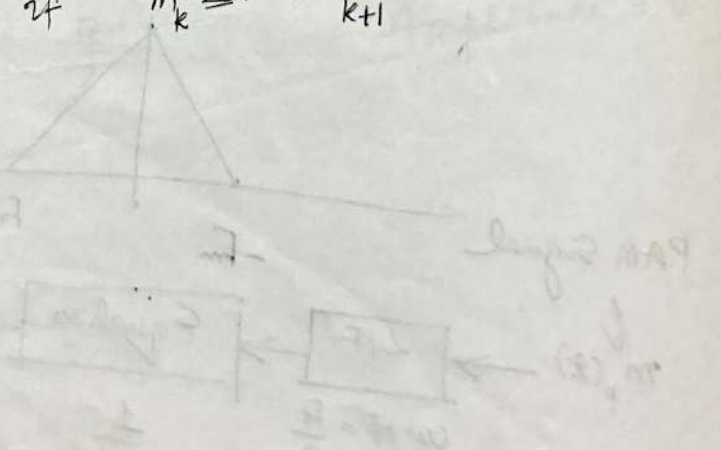
Mapping these samples to a discrete set of values is termed as Quantization

Purpose of Quantization is to convert these samples into information bits. Which can either be stored or transmitted over the channel.

$V = g(m)$ ← sample
 belongs to a discrete Quantization fun.
 set of values also
 termed as Quantization
Levels

$$g(m) = V_k \leftarrow k^{\text{th}} \text{ level}$$

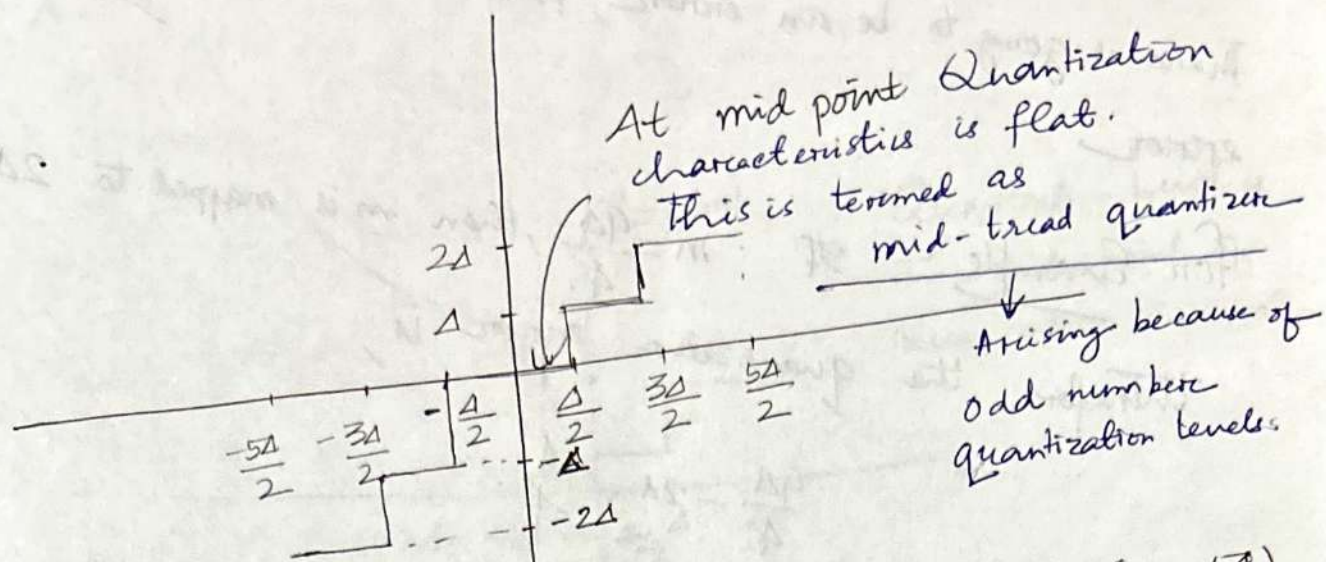
$$\text{if } m_k \leq m \leq m_{k+1}$$



Uniform Quantizer

Quantization Levels are uniformly spaced

Ex:- Let us consider a 5 level Quantizer



5 Quantization intervals

$(-\frac{5\Delta}{2}, -\frac{3\Delta}{2})$, $(-\frac{3\Delta}{2}, -\frac{\Delta}{2})$, $(-\frac{\Delta}{2}, \frac{\Delta}{2})$, $(\frac{\Delta}{2}, \frac{3\Delta}{2})$, $(\frac{3\Delta}{2}, \frac{5\Delta}{2})$

Each quantization interval is of width Δ . Therefore it is a uniform quantizer.

In each quantization interval, the quantization level is the mid point of the interval.

$$\frac{3\Delta}{2} \leq m < \frac{5\Delta}{2} \rightarrow g(m) = 2\Delta$$

$$\frac{\Delta}{2} \leq m < \frac{3\Delta}{2} \rightarrow g(m) = \Delta$$

$$-\frac{\Delta}{2} \leq m < \frac{\Delta}{2} \rightarrow g(m) = 0$$

$$-\frac{3\Delta}{2} \leq m < -\frac{\Delta}{2} \rightarrow g(m) = -\Delta$$

$$-\frac{5\Delta}{2} \leq m < -\frac{3\Delta}{2} \rightarrow g(m) = -2\Delta$$

For example,

All values in $(\frac{3\Delta}{2}, \frac{5\Delta}{2})$ are mapped to 2Δ .

Therefore, this is a many to one mapping.

There is going to be an error, this is known as quantization error.

For Example: If $m = \frac{9\Delta}{4}$, then m is mapped to 2Δ

therefore the quantization error is,

$$\frac{9\Delta}{4} - 2\Delta = \frac{\Delta}{4}$$

So, depending on where it lies in the quantization interval, the quantization error lies between

$$-\frac{\Delta}{2} \text{ to } \frac{\Delta}{2}$$

Minimum sample value = $-\frac{\Delta}{2}$

the maximum sample value = $+\frac{\Delta}{2}$

Quantization Level = midpoint of the interval.

When

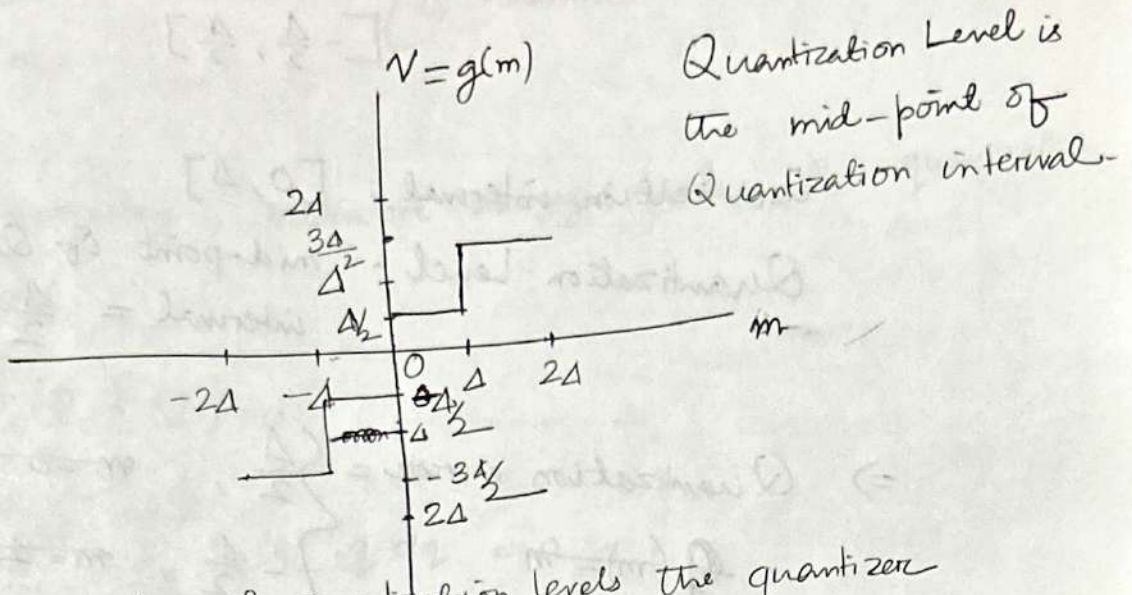
Odd number of Quantization levels \Rightarrow Mid tread quantizer

Smaller the quantization level, smaller will be the quantization error.

Uniform Quantization

Even number of quantization levels.

Consider 4 quantization levels, Quantization interval of width Δ .



With an even number of quantization levels the quantizer characteristics rises from $-\frac{\Delta}{2}$ to $\frac{\Delta}{2}$ at $m=0$. This is termed as a mid-rise quantizer.

Δ : Quantization interval (or) step size

$m \in [-m_{\max}, m_{\max}]$ Peak +ve sample value

Total quantization interval or Dynamic signal range = $2m_{\max}$.

$$\text{No of quantization levels} = \left\lfloor L = \frac{2m_{\max}}{\Delta} \right\rfloor$$

$$\Delta = \frac{2m_{\max}}{L}$$

Quantization error:

Quantization is a many-to-one mapping in which all sample values in a particular interval are mapped to a quantization level. \Rightarrow Quantization error.

In a uniform quantizer, the quantization error lies in

$$\left[-\frac{\Delta}{2}, \frac{\Delta}{2}\right]$$

Quantization interval: $[0, \Delta]$

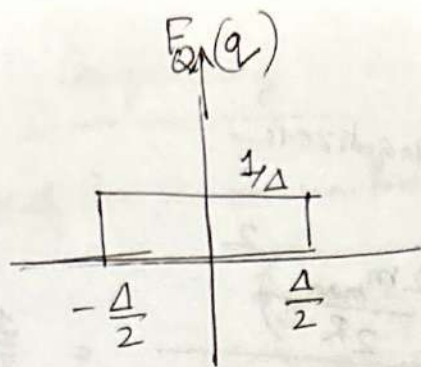
Quantization Level: mid-point of Quantization interval = $\frac{\Delta}{2}$

$$\Rightarrow \text{Quantization error} = \begin{cases} \frac{\Delta}{2}, & m=0 \\ -\frac{\Delta}{2}, & m=1 \end{cases}$$

~~$Q(m) = m$~~

$$q = |Q(m) - m|$$

Quantized	True
Sample	Sample
Value	value



Quantization error is uniformly distributed in the interval: $[-\frac{\Delta}{2}, \frac{\Delta}{2}]$

Prob. density fn of Quantization error

$$F_Q(q) = \begin{cases} \frac{1}{\Delta}, & |q| \leq \frac{\Delta}{2} \\ 0, & \text{otherwise} \end{cases}$$

By symmetry, mean or average value of quantization error,

$$E\{Q\} = 0$$

$$\Rightarrow \int_{-\frac{\Delta}{2}}^{\frac{\Delta}{2}} F_Q(q) \cdot q \, dq = 0$$

$$E\{Q^2\}$$

Variance or power of Quantization error
Also termed as quantization noise.

$$= \int_{-\frac{\Delta}{2}}^{\frac{\Delta}{2}} q^2 F_Q(q) \, dq = \int_{-\frac{\Delta}{2}}^{\frac{\Delta}{2}} \frac{1}{\Delta} q^2 \, dq = \frac{1}{\Delta} \left[\frac{q^3}{3} \right]_{-\frac{\Delta}{2}}^{\frac{\Delta}{2}}$$

$$= \frac{1}{\Delta} \times \frac{1}{3} \left[\frac{\Delta^3}{8} + \frac{\Delta^3}{8} \right] = \frac{1}{3\Delta} \times \frac{2\Delta^3}{8} = \frac{\Delta^2}{12}$$

$$\boxed{\text{Quantization noise power} = \frac{\Delta^2}{12}}$$

$$\Delta = \frac{2m_{\max}}{L} = \frac{2m_{\max}}{2^R}$$

$R = \log_2 L$ → no of bits required to represent L levels in binary

R : Resolution of Quantizer

$$\sigma_q^2 = \frac{\Delta^2}{12} = \frac{\left(\frac{2m_{\max}}{2^R}\right)^2}{12} = \frac{1}{3} \frac{m_{\max}^2}{2^{2R}}$$

Quantization noise variance in dB.

$$\downarrow$$

$$10 \log_{10} \sigma_q^2 = -10 \log_{10} 3 + 20 \log_{10} m_{\max} - 20R \log_{10} 2$$

$$\boxed{10 \log_{10} \sigma_q^2 = -10 \log_{10} 3 + 20 \log_{10} m_{\max} - 6.02R}$$

dB noise power decreases by 6dB for each additional bit

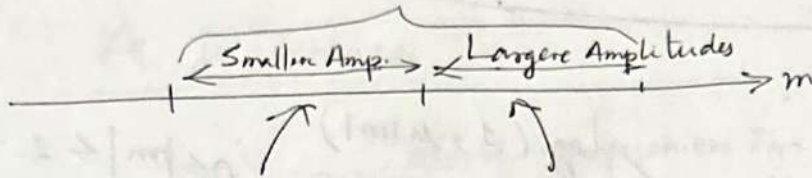
SNR : Signal to Quantization noise power ratio

Improves by 6dB for each additional bit.

Companing

used for non-uniform quantization.

Dynamic Range

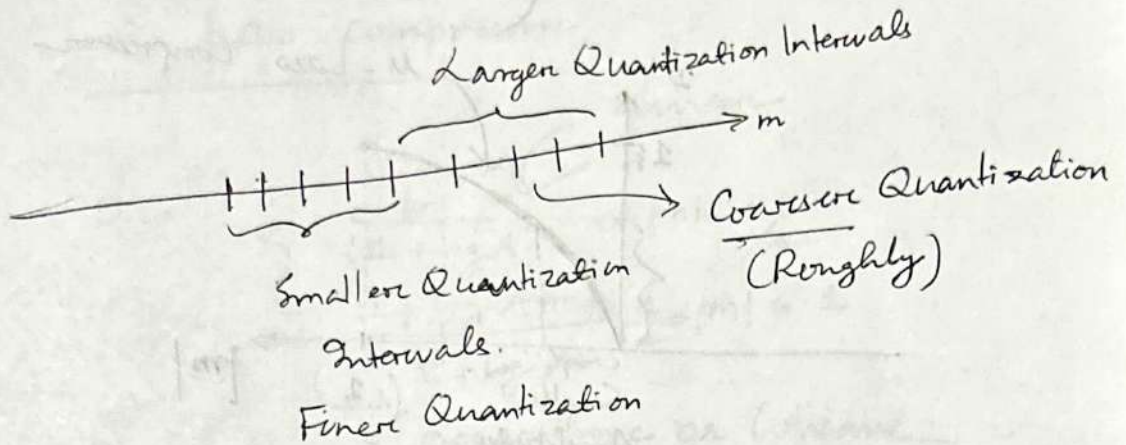


We need
Higher Accuracy

Lower Accuracy
(can be afforded)

⇒ Lower Quantization
Error

⇒ Higher Quantization
Error



Summary:

① At lower amplitudes, we need lower Quantization error ⇒ Smaller Quantization Intervals ⇒ Higher Accuracy of Reconstruction.

② At larger amplitudes, we can tolerate Large Quantization error ⇒ Larger Quantization Interval ⇒ Lower Accuracy of Reconstruction.

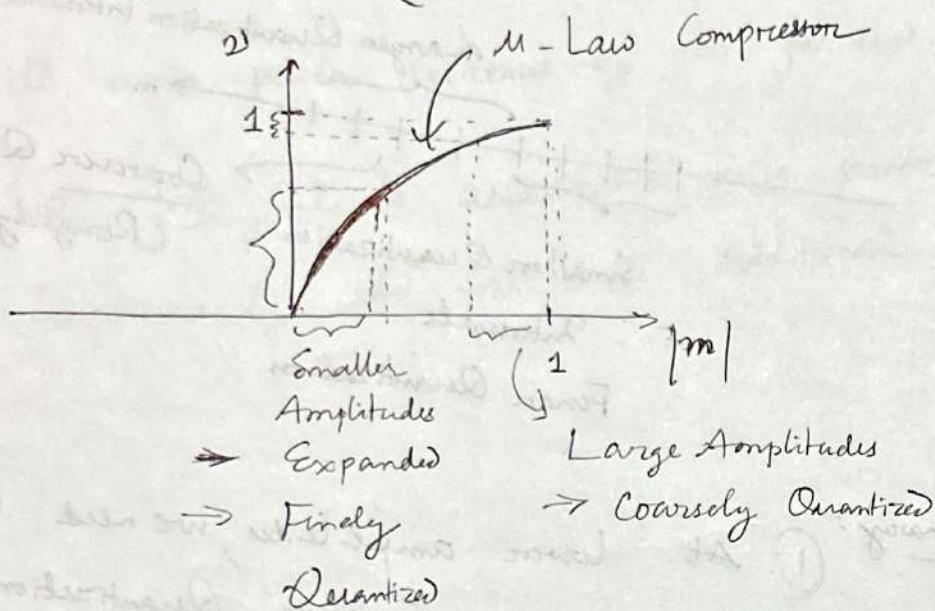
* Width of Quantization intervals are not same ⇒ Non-uniform Quantization.

COMPANDING Achieves NON-UNIFORM Quantization.

M-LAW COMPRESSOR FOR COMPANDING

$$D = \frac{\log(1 + \mu|m|)}{\log(1 + \mu)}, \quad 0 \leq |m| \leq 1$$

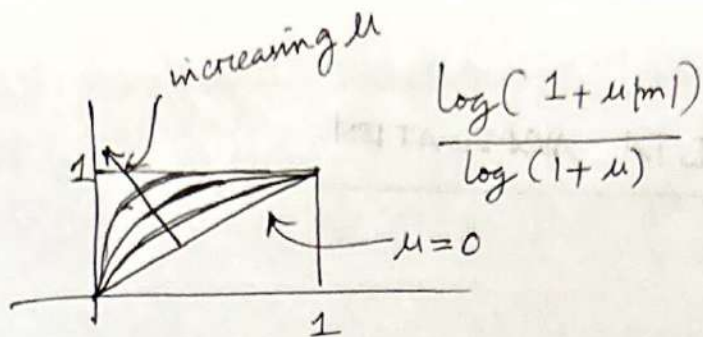
$m \rightarrow$ Normalized Sample value



$$\lim_{\mu \rightarrow 0} \frac{\log(1 + \mu|m|)}{\log(1 + \mu)} \quad \left\{ \lim_{x \rightarrow 0} \log(1+x) \approx x \right\}$$

$$= \frac{\mu|m|}{\mu} = |m|$$

$D(|m|) = |m|$
Linear Char.



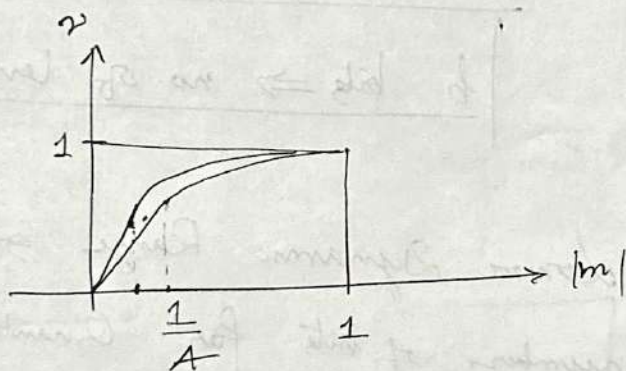
As μ increases

more compression of larger amplitudes
 more expansion of smaller "

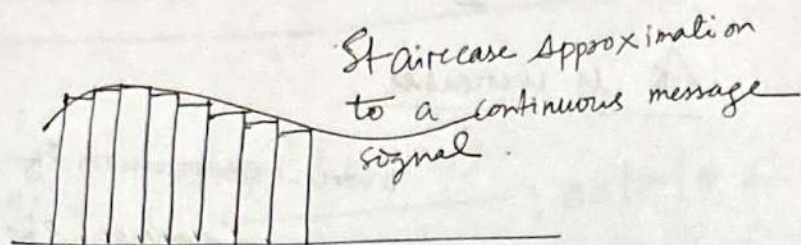
μ -Law compression is used in North
 American Standards.

A-Law compressor

$$v = \begin{cases} \frac{A|m|}{1 + \log A} & \text{linear} \\ \frac{1 + \log A|m|}{1 + \log A} & \text{logarithmic or concave} \end{cases} \quad \begin{matrix} |m| \leq \frac{1}{A} \\ \frac{1}{A} \leq |m| \leq 1 \end{matrix}$$



DELTA MODULATION



Instead of Quantizing samples, Quantize the difference between successive samples.

Typically, we have smooth continuous waveform

⇒ Difference of signal samples is small

⇒ Dynamic range of difference between successive samples is very small.

⇒ Finer Resolution { Quantization Interval small }
& Less Quantization Error

⇒ $b \text{ bits} \Rightarrow \text{no. of levels} = 2^b$

⇒ Lower Dynamic Range ⇒ We need lower number of bits for Quantization.

⇒ Bit Rate can be reduced.

In Delta Modulation, resolution of Quantizer is drastically reduced

In fact we employ only a single bit for quantization.

$m(n)$ ← Sample at time instant n .

$m_q(n-1)$ ← Approximation to $m(n)$

Error,
$$e(n) = m(n) - m_q(n-1) \quad \text{--- (1)}$$

Quantize $e(n)$:

$$e_q(n) = \Delta \operatorname{sgn}(e(n)) \quad \text{--- (2)}$$

Quantized Error

$$\operatorname{sgn}(x) = \begin{cases} +1, & x > 0 \\ -1, & x < 0 \\ 0, & x = 0 \end{cases}$$

If $e(n) > 0$, $e_q(n) = +\Delta$

If $e(n) < 0$, $e_q(n) = -\Delta$

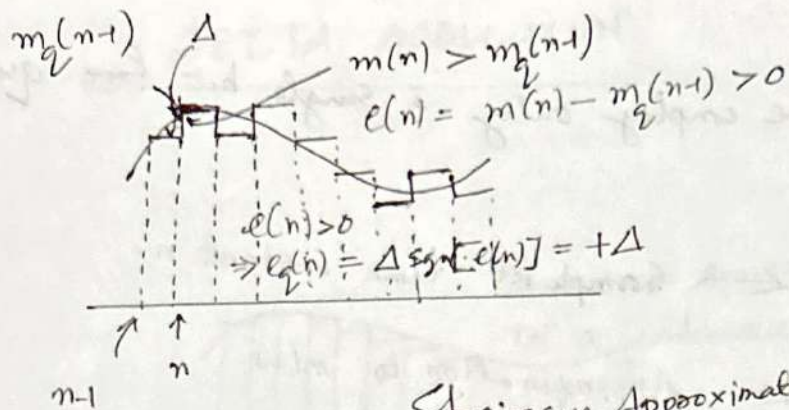
$e_q(n)$ can take only 2 values $\{-\Delta$ or $+\Delta\}$

Hence, only 2 levels

Therefore only 1 bit is required for quantization.

$$m_q(n) = m_q(n-1) + e_q(n) \quad \text{--- (3)}$$

Reconstruct Prediction or
approximation for next time instant

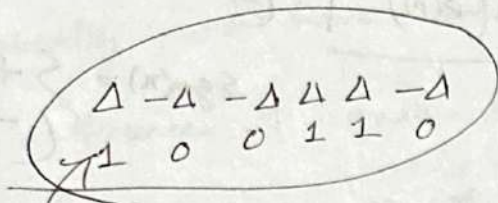


Staircase Approximation
of signal

$$e_q(n) = \begin{cases} +\Delta \\ -\Delta \end{cases}$$



Encoded using 1 bit



Encoded signal

Can be used for signal compression

- Speech Compression
- Image Compression

Delta Modulation

Differential Modulation

Encodes the difference of signal samples.

Each sample is encoded using a single bit only

Hence it is a very efficient modulation.

↓
Results in a low bit rate

Can also be used for compression.

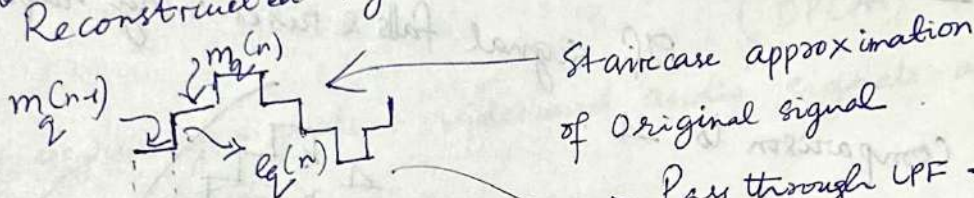
$m_q(n)$: Quantized approximation of signal at time instant n . (Also, reconstruction at n)

$e_q(n)$: Quantized error at time n . Either $+\Delta$ or $-\Delta$

$$m_q(n) = m_q(n-1) + e_q(n)$$

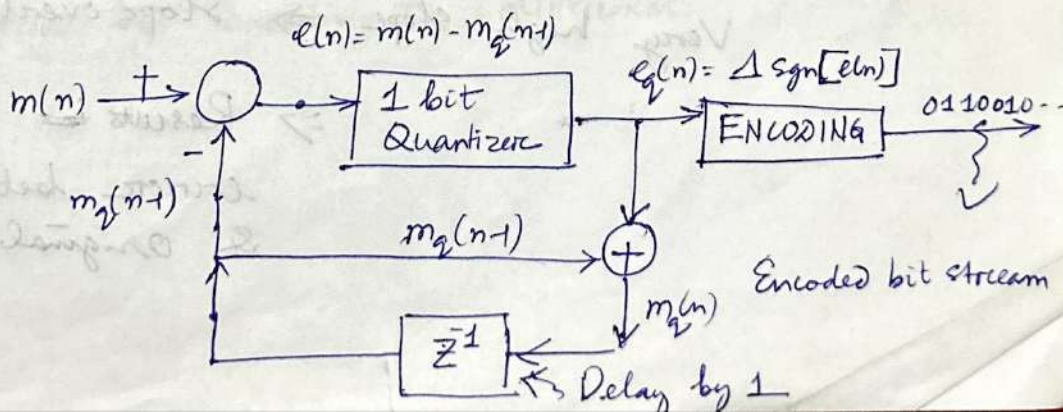
← $e_q(n)$ for signal reconstruction at n .

↓
Reconstructed signal at time n



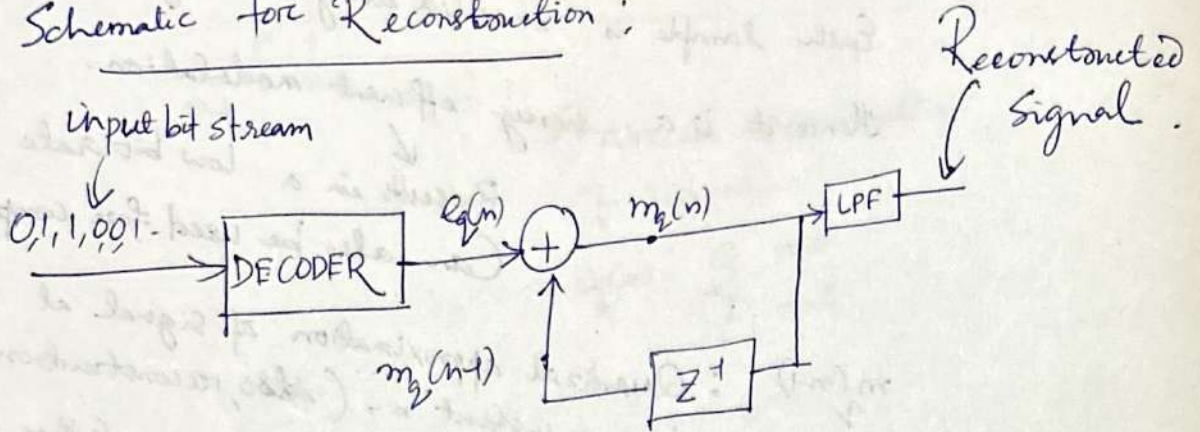
Pass through LPF → After passing through an LPF, smoothed version of signal is obtained.

Schematic Diagram of Delta Modulation



Encoded bit stream can be digitally modulated & transmitted over comm. channel.

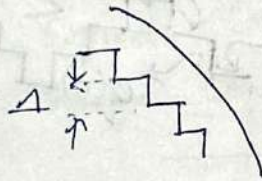
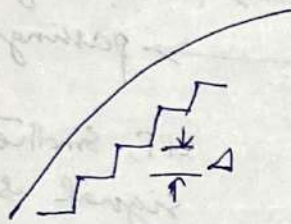
Schematic for Reconstruction:



Distortion in Delta Modulation:

Too small size Δ (step size)

If signal falls & rises very rapidly in comparison to Δ .

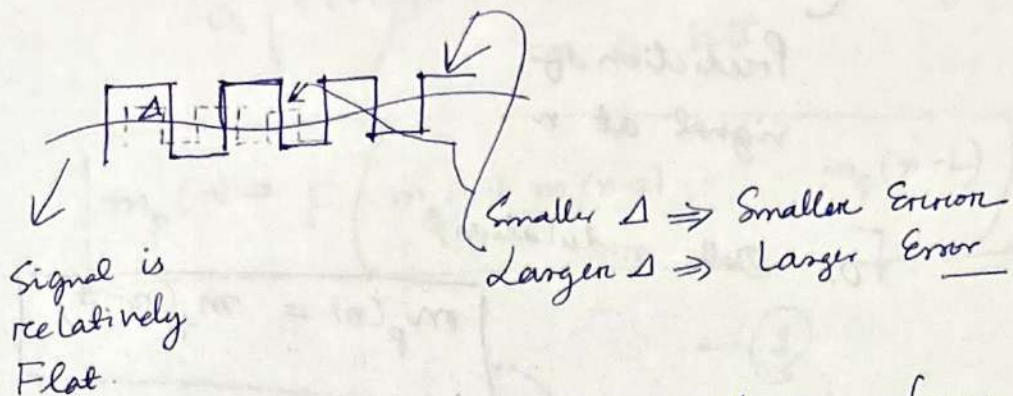


staircase approximation falls short of signal (is not able to catch up the signal).

Very rapid rise or fall in the signal \Rightarrow
 Very high slope \Rightarrow Slope overload Distortion.

\Rightarrow Results in a high error between reconstructed & original signal.

Too Large Step Size :-



Granular noise \rightarrow Arising from large value of step size Δ .
When the signal is relatively flat.

Different Pulse Modulation Schemes

DPCM (Differential Pulse Coded Modulation)
(DPCM)

Naturally occurring signals :- video and audio signals are very high correlation \Rightarrow High Redundancy

Bit rate can be significantly reduced by reducing the redundancy of the signal.

DPCM achieves this by predicting the signal $m(n)$ & followed by encoding the difference.

L past quantized samples

$$m_p(n) = F(m_q^{(n-1)}, m_q^{(n-2)}, \dots, m_q^{(n-L)})$$

Prediction of signal at n

For Delta modulation,

$$m_p(n) = m_q^{(n-1)}$$

Prediction function for Delta Modulation

$$m_q^{(n-1)}, m_q^{(n-2)}, \dots, m_q^{(n-L)}$$

L-past quantized samples.

F(.) Prediction function.

↳ It has to be appropriately

designed. Better prediction \Rightarrow Higher efficiency

DPCM

$$e(n) = m(n) - m_p(n) \quad \text{--- (2)}$$

Prediction error

$$e_q(n) = Q(e(n)) \quad \text{--- (3)}$$

Quantized prediction error

If Prediction is good $\Rightarrow e(n)$ is lower \Rightarrow quantization is efficient.

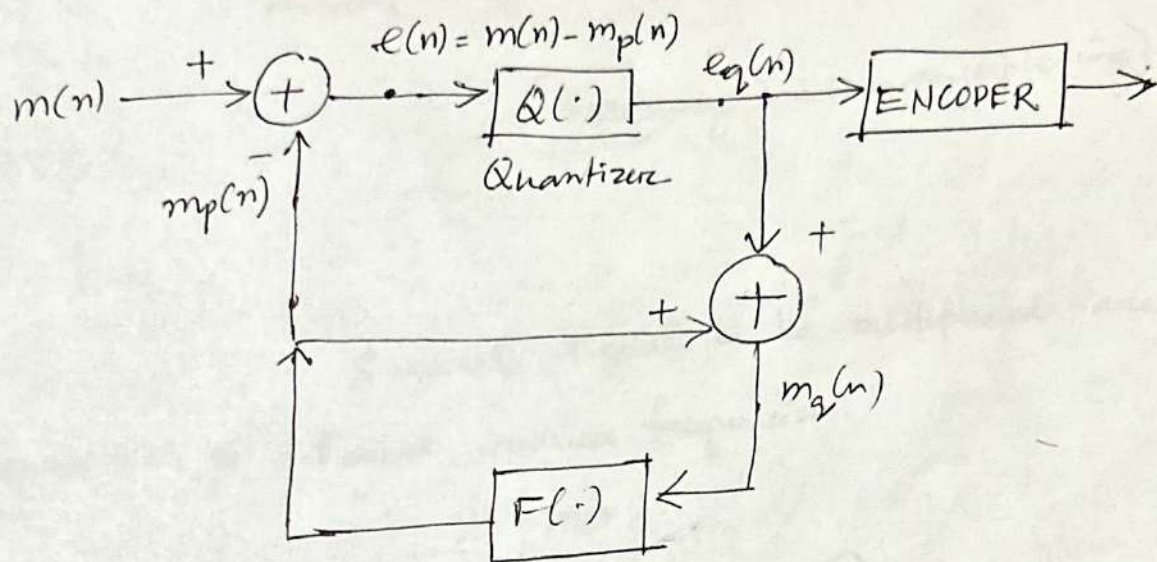
$$m_q(n) = m_p(n) + e_q(n) \rightarrow \text{Reconstruction.}$$

$Q(e(n)) \rightarrow$ can have arbitrary no. of bits.

$$m_p(n) = F(m_q(n-1), m_q(n-2), \dots, m_q(n-L))$$

①

Schematic Diagram



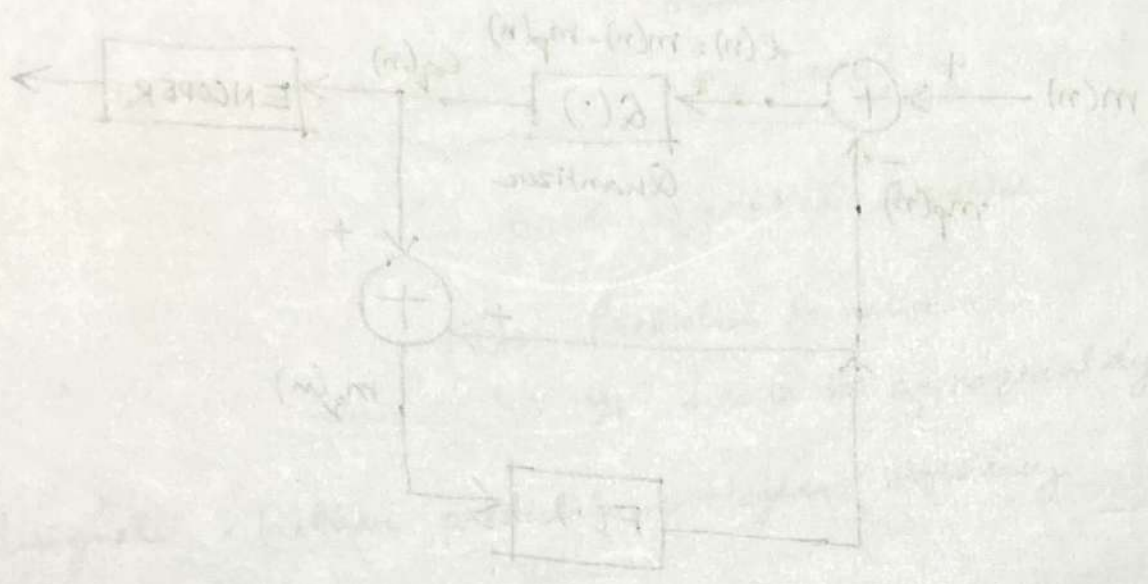
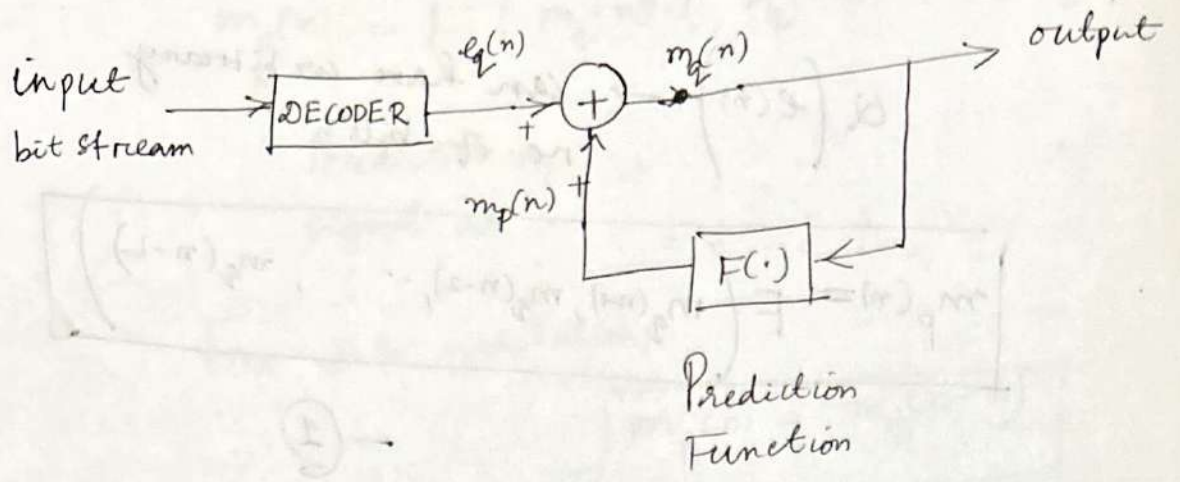
Prediction Function.

← For Delta Modulation, simply z^+

DPCM Reconstruction

$$m_p(n) = F(m_q(n-1), m_q(n-2), \dots, m_q(n-L))$$

$$m_q(n) = m_p(n) + e_q(n)$$



For bits
 Modulation
 apply 51

$$m_q(n) = F(m_p(n)) + e_q(n)$$

$$m_p(n) = F(m_q(n))$$

Frequency Division Multiplexing

Multiplexing :- Multiple signals are combined into a single composite signal for transmission over a channel.

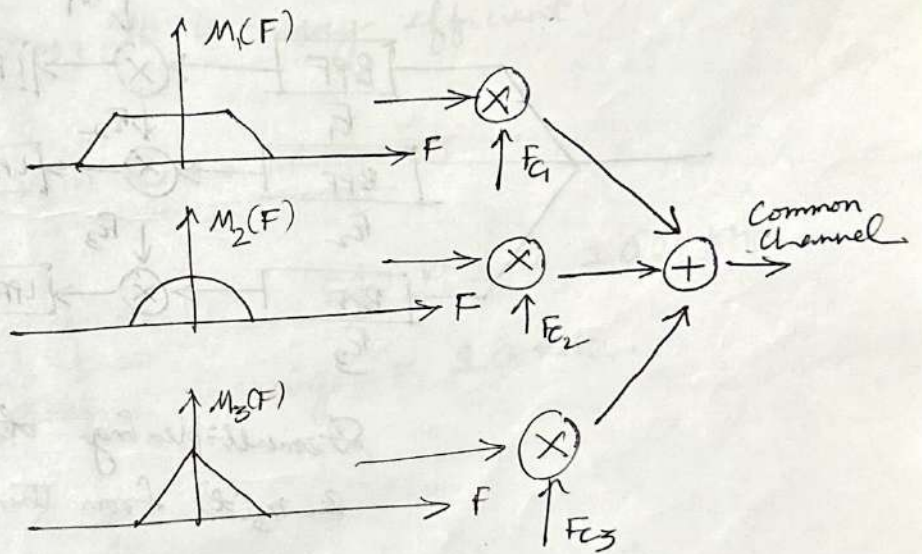
Same channel is used for the transmission of multiple signals.

Multiplexing is done in the frequency domain

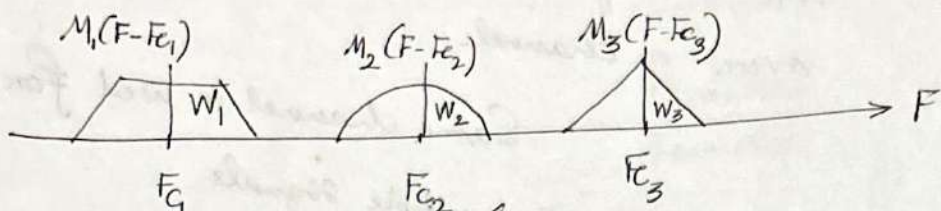
↓
(Frequency Division Multiplexing)

How?

Several signals to be multiplexed are translated to different carrier frequencies.

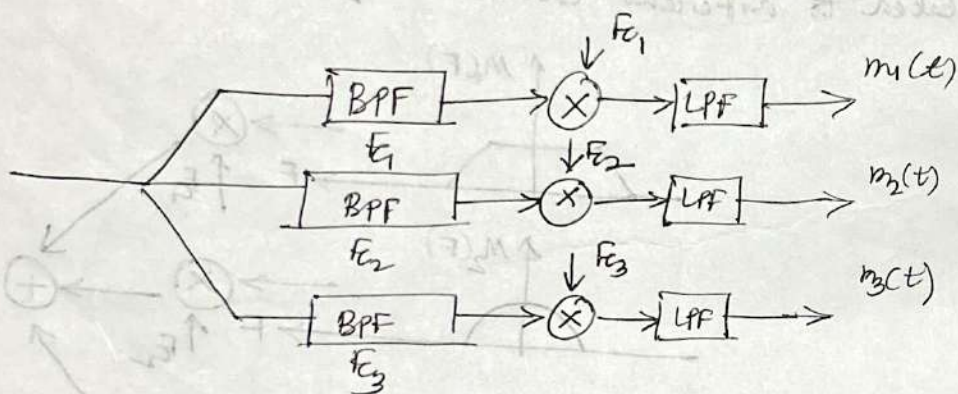


Spectrum of Composite Signal



↓
Transmitted over common channel.

$\{ m_1(t), m_2(t), m_3(t) \}$ are multiplexed in frequency domain for transmission over channel.
 (FDM)



Demultiplexing also extract $m_1(t)$, $m_2(t)$ & $m_3(t)$ from the composite signals.

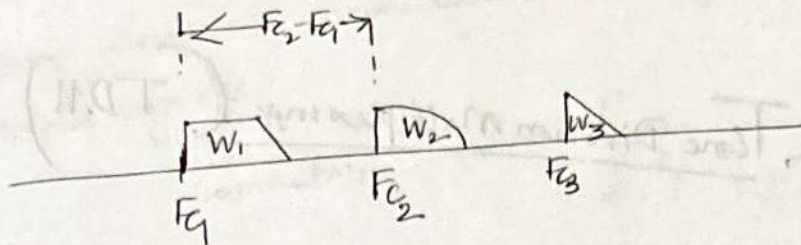
To avoid overlap:

$$F_2 - W_2 \geq F_1 + W_1$$

$$\Rightarrow \boxed{F_2 - F_1 \geq W_1 + W_2}$$

Carrier Frequency Separation \geq Sum of bandwidth

For SSB Modulation



For no overlap, $F_{c2} \geq F_{c1} + W_1$

$$\Rightarrow \boxed{F_{c2} - F_{c1} \geq W_1}$$

$$\boxed{F_{c3} - F_{c2} \geq W_2}$$

Spacing \geq Bandwidth

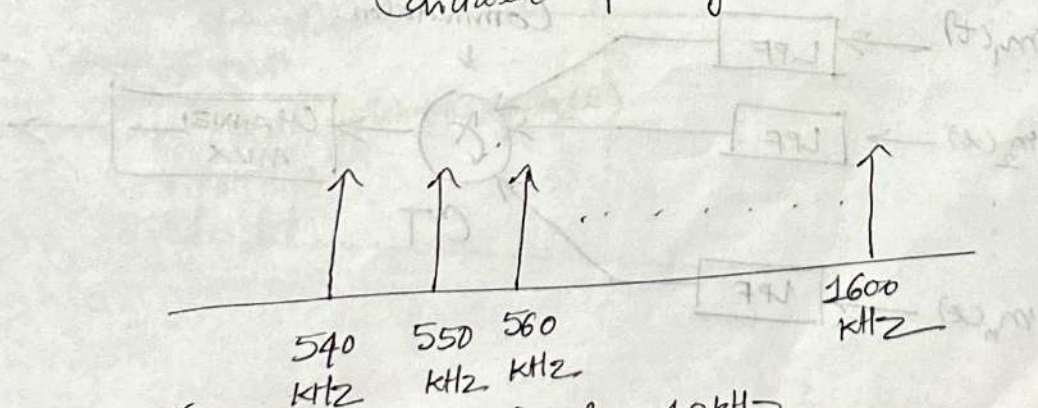
\Rightarrow Total Bandwidth required for
FDM + SSB \ll FDM + DSB.

\Rightarrow FDM + SSB is very efficient.

Example = AM Radio BROADCAST

Carrier in 540 kHz to 1600 kHz

Carrier spacing = 10 kHz



Carrier spacing is only 10 kHz

$W \approx 15\text{kHz} > \text{Carrier Spacing}$

Adjacent Carriers are not used in same geographic location in AM radio broadcast.

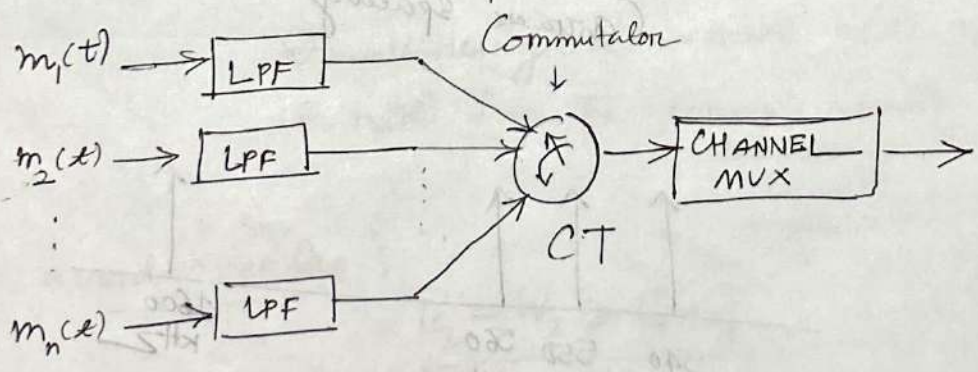
Time Division Multiplexing (TDM)

Application of Sampling.

Several signals are multiplexed in the time domain to form a composite signal for transmission over a channel.

TDM Operation

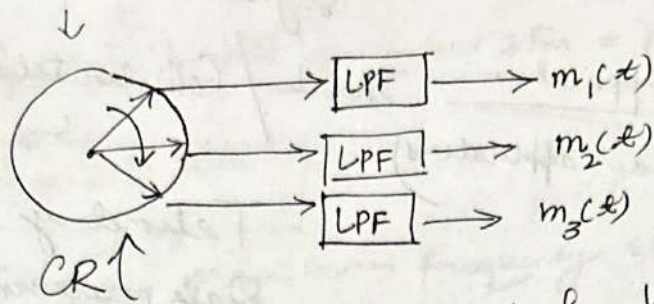
- Each signal is low pass filtered to first remove the undesired frequencies.
 - These signals are applied to a commutator which alternatively samples the signals to be multiplexed.
 - This commutator is implemented using high speed ^{electronic} switching circuit.
- $\{ m_1(t), m_2(t), \dots, m_n(t) \}$ are n signals to be multiplexed



Samples are multiplexed to form a composite signal which is transmitted over a channel.

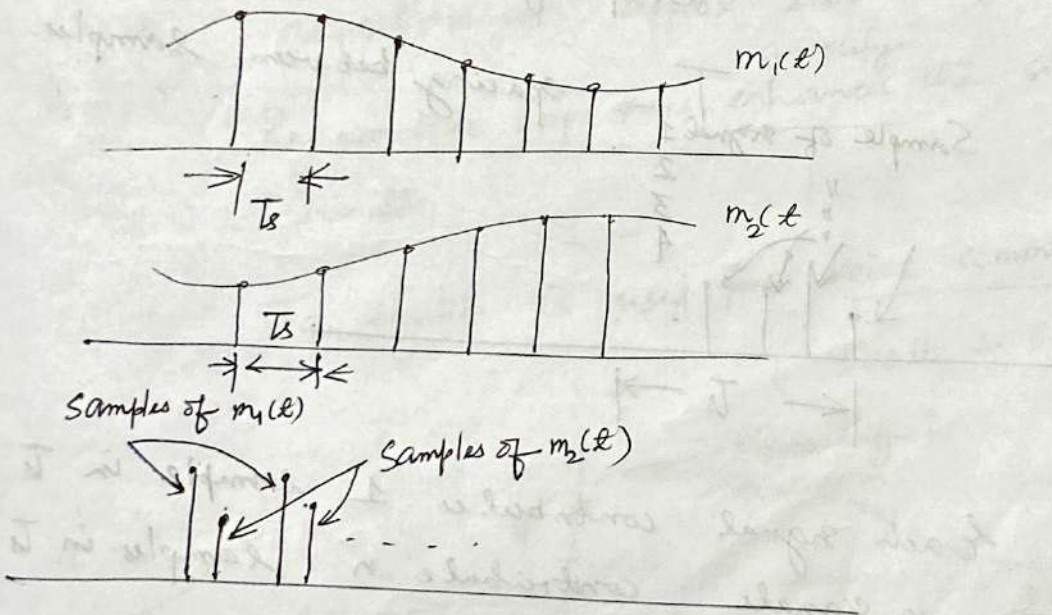
At the receiver the composite signal is demultiplexed using another commutator followed by low pass filtering of output signals.

Commutator



Demultiplexes samples from the composite signal.

CT & CR have to be synchronised for error free operation.



Duration between samples in TDM signals is,

$$T = \frac{T_s}{n}$$

n : Number of samples to be multiplexed.

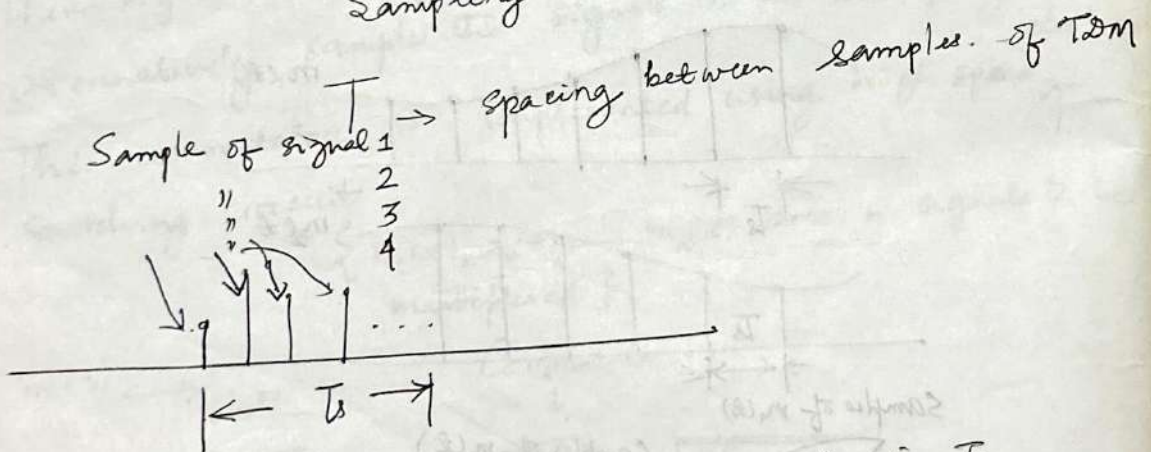
T_s : Sampling interval for each of the constituent signals of the TDM signals.

Application: Mobile / Cellular telephony (wide applications) \rightarrow (T1 System)
 \rightarrow (GSM, \rightarrow 2G Wireless Standard)
 Telemetry
 Data processing

Bandwidth required for TDM

$n \rightarrow$ no of signals to be multiplexed.

Sampling interval for each signal = T_s



Each signal contributes 1 sample in T_s
 \Rightarrow n signals contribute n samples in T_s

So,
$$T = \frac{T_s}{n}$$

Bandwidth required for transmission

$$F_{TDM} = \frac{1}{2T} = \frac{1 \times n}{2 \times T_s} = \frac{n}{2} F_s = \frac{1}{2} n F_s$$

F_s → Sampling frequency

From Nyquist criterion, we need

$$F_s \geq 2F_m$$

$$F_{TDM} = \frac{1}{2} n F_s \geq \frac{1}{2} n \times 2F_m = n F_m$$

$$\Rightarrow \boxed{F_{TDM} \geq n F_m}$$

F_m : maximum frequency component

Case study for TDM System

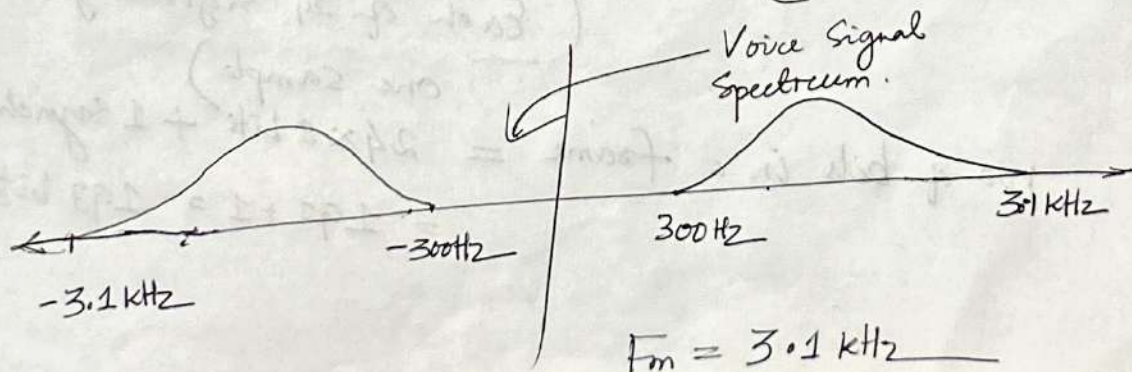
T₁ System (Voice Telephony)

It comprises of 24 voice channels over separate pairs of wires with regenerative repeaters at approx. 2km intervals.

Regenerative repeaters amplify the signal (TDM) strength.

T₁ system is used for voice communication.

$$(300\text{Hz} \div 3.1\text{kHz})$$



From Nyquist criterion to avoid distortion.
(Aliasing)

$$f_s \geq 2 f_m = 2 \times 3.1 \text{ kHz} = 6.2 \text{ kHz}$$

$$\Rightarrow \boxed{f_s \geq 6.2 \text{ kHz}}$$

→ Nyquist Sampling rate to avoid aliasing

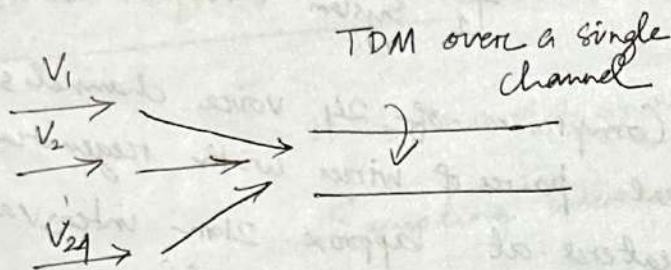
Typical sampled at

$$\boxed{f_s = 8 \text{ kHz}}$$

↓
8000 samples/sec

Each sample is quantized using 8 bits. $\left. \begin{matrix} 2^8 = 256 \\ \text{Levels} \end{matrix} \right\}$
↓
(μ -Law Quantizer)

8 bits/samples from each of $n=24$ voice signals.



Sampling rate = 8 kHz

$$\Rightarrow \text{Sampling duration, } T_s = \frac{1}{8 \text{ kHz}} = \underline{125 \mu\text{s}}$$

Frame Duration

(Each of 24 signals generate one sample)

$$\begin{aligned} \text{no of bits in a frame} &= 24 \times 8 \text{ bits} + 1 \text{ synch pulse} \\ &= 192 + 1 = 193 \text{ bits} \end{aligned}$$

of T₁ system, no. of bits/frame = 193

⇒ Time duration between bits = $\frac{125 \mu s}{193 \text{ bits}}$

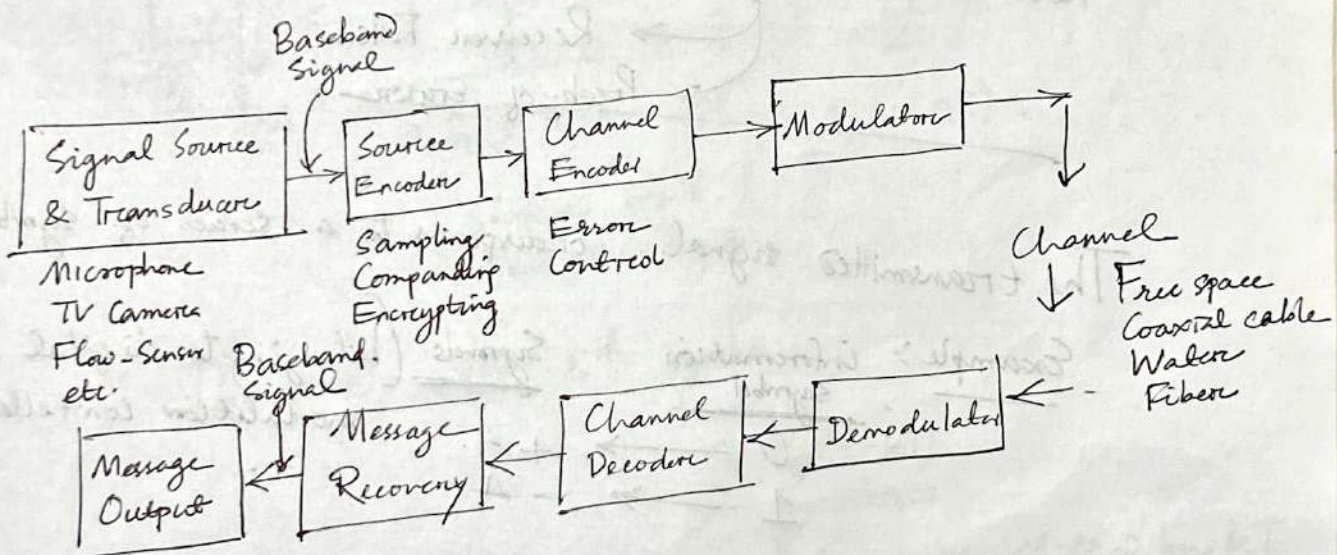
= 0.647 μs /bit

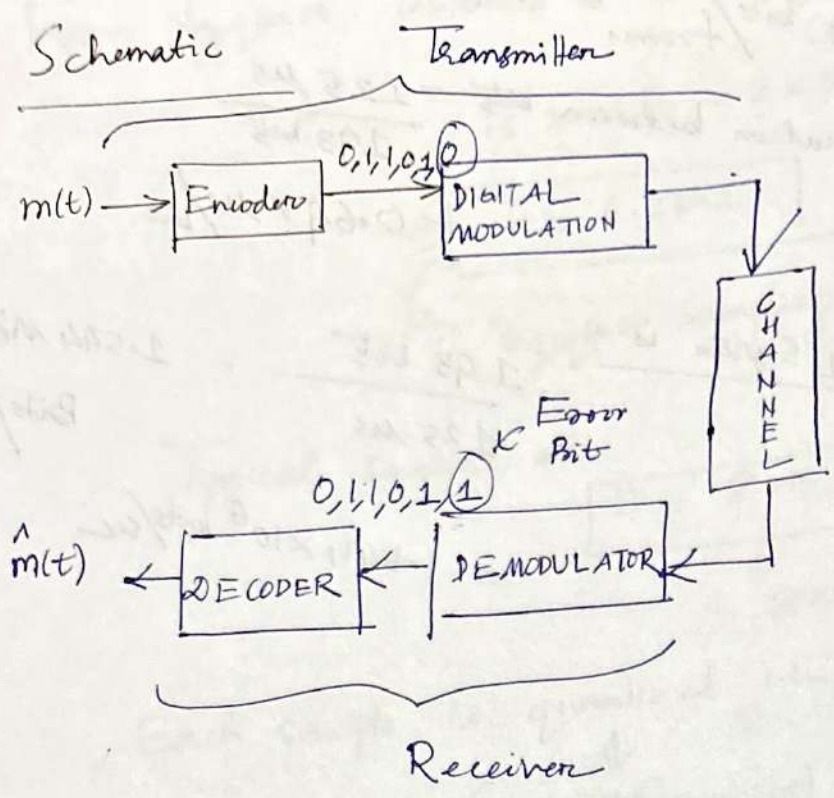
Bit rate of T₁ system is : $\frac{193 \text{ bits}}{125 \mu s} = 1.544 \text{ Mega Bits/sec}$

= $1.544 \times 10^6 \text{ bits/sec}$

Part-2

DIGITAL COMM. SYSTEM





How to design various modules?
 How to transmit? \leftarrow Transmit Power Modulation
 How to receive? \leftarrow Receiver Filter
 \leftarrow Prob. of Error

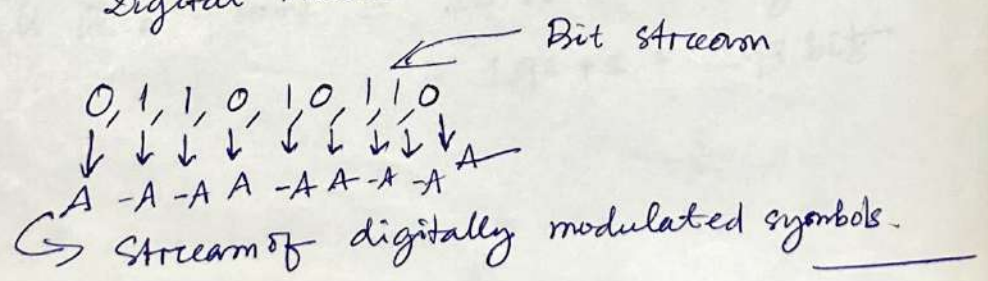
The transmitted signal corresponds to a series of symbols.

Example:

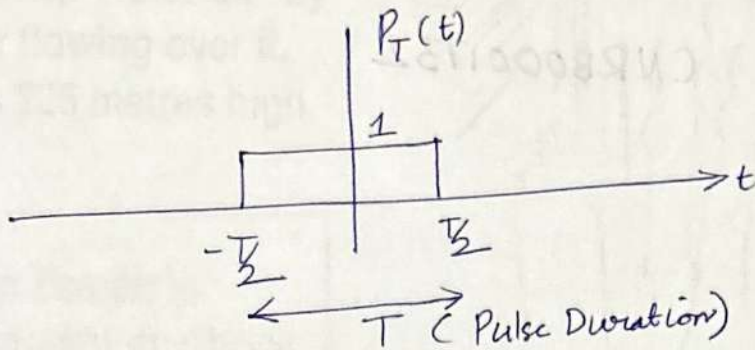
<u>Information Symbol</u>	\rightarrow	<u>Symbols</u> (belonging to digital modulation constellation)
0	\rightarrow	+A
1	\rightarrow	-A

BPSK (Binary Phase Shift Keying)

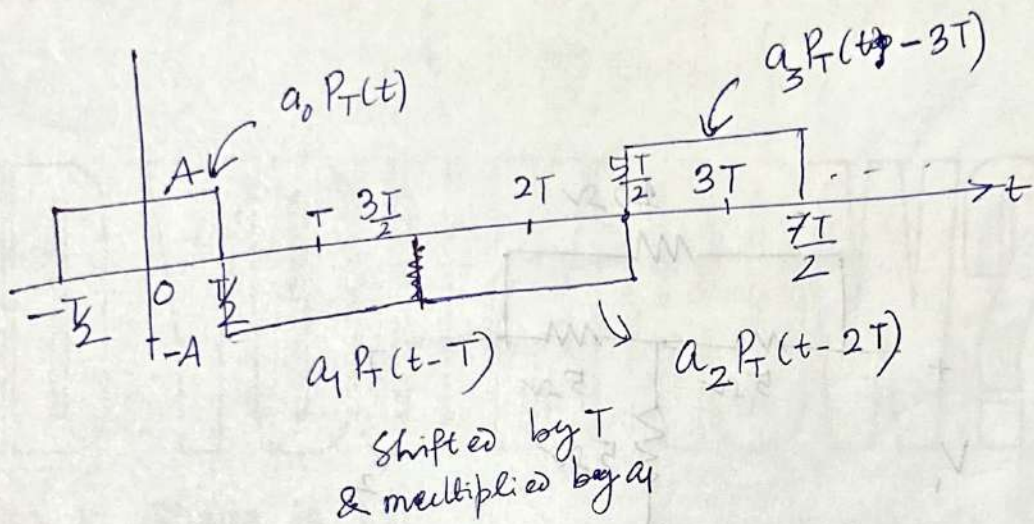
This mapping operation is termed as Digital Modulation.



Transmit the digitally modulated symbols using a pulse.



$$P_T(t) = \begin{cases} 1, & |t| \leq \frac{T}{2} \\ 0, & \text{otherwise} \end{cases}$$



Therefore, for k th symbol,

$$a_k P_T(t - kT)$$

a_k is the k th symbol.
Any pulse shifted by kT .

Net transmitted digital comm. signal is

$$x(t) = \sum_{k=-\infty}^{\infty} a_k P(t - kT)$$

Structure of a typical transmitted signal in a digital comm. system.

Spectrum of the transmitted signal

$$x(t) = \sum_{k=-\infty}^{\infty} a_k \underbrace{P_T(t-kT)}_{\substack{\text{Pulse shifted} \\ \text{by } kT}} \\ \downarrow \\ \text{k}^{\text{th}} \text{ symbol}$$

$$\text{k}^{\text{th}} \text{ bit} = \underbrace{0 \text{ or } 1}_{\text{Random}}$$

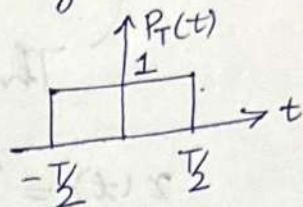
$$a_k = \underbrace{A \text{ or } -A}_{\text{Random}}$$

Aim: To characterise spectrum of transmitted signal $x(t)$

$$P_T(t) = \begin{cases} 1, & |t| \leq \frac{T}{2} \\ 0, & \text{otherwise} \end{cases}$$

↓ F.T.

$$T \text{ sinc } fT = \frac{T \sin(\pi fT)}{\pi fT}$$



Since a_k is random

$$P(a_k = A) = \frac{1}{2}$$

$$P(a_k = -A) = \frac{1}{2}$$

$$E \{ a_k \} = A P(a_k = A) + (-A) P(a_k = -A) \\ = A \times \frac{1}{2} - A \times \frac{1}{2} = 0$$

$$\Rightarrow \boxed{E \{ a_k \} = 0}$$

Assume that the symbols a_k are iid

(Independent Identically Distributed)

$$E \{ a_k a_m \} = E \{ a_k \} E \{ a_m \} = 0$$

↖ $\forall k \neq m$

uncorrelated.

$$x(t) = \sum_{k=-\infty}^{\infty} a_k P_T(t-kT)$$

↖ Average value?

$$E \{ x(t) \} = E \left\{ \sum_{k=-\infty}^{\infty} a_k P_T(t-kT) \right\} = \sum_{k=-\infty}^{\infty} E \{ a_k \} P_T(t-kT)$$

$$\Rightarrow \boxed{E \{ x(t) \} = 0}$$

Average value of transmitted signal $x(t)$ is zero.

$$\rightarrow \text{FT} \{ x(t) \} = X(F) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi Ft} dt$$

$$E \{ X(F) \} = E \left\{ \int_{-\infty}^{\infty} x(t) e^{-j2\pi Ft} dt \right\} = \int_{-\infty}^{\infty} E \{ x(t) \} e^{-j2\pi Ft} dt = 0$$

$$\Rightarrow \boxed{E \{ X(F) \} = 0}$$

Average value of spectrum transmitted is zero.

This does not mean spectrum = 0

$$x(t) = \sum_{k=-\infty}^{\infty} a_k P_T(t-kT)$$

\uparrow random \uparrow random

How to measure the spectral content of a random signal?

→ PSD (Power Spectral Density)

Gives spectral distribution of power of a random signal

To compute PSD

Step-1

Auto-Correlation Function

$$R_{xx}(\tau) = E \{ x(t) \cdot x(t+\tau) \}$$

for a WSS (Wide Sense Stationary Process)

Step-2 :-

$$\text{ACF} \xleftrightarrow{\text{F.T.}} \text{PSD}$$

$$\begin{aligned}
 & E \{ x(t) \cdot x(t+\tau) \} \\
 &= E \left\{ \left(\sum_{k=-\infty}^{\infty} a_k p_T(t-kT) \right) \times \left(\sum_{m=-\infty}^{\infty} a_m p_T(t+\tau-mT) \right) \right\} \\
 &= E \left\{ \sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} a_k a_m p_T(t-kT) p_T(t+\tau-mT) \right\} \\
 &= \sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} E \{ a_k a_m \} p_T(t-kT) p_T(t+\tau-mT)
 \end{aligned}$$

$$E \{ a_k a_m \} = E \{ a_k \} E \{ a_m \} = 0$$

if $k \neq m$

(\therefore Symbols are zero mean iid)

$$= \sum_{k=-\infty}^{\infty} E \{ a_k^2 \} p_T(t-kT) p_T(t+\tau-kT)$$

(for $k=m$)

$$P(a_k = A) = \frac{1}{2}$$

$$P(a_k = -A) = \frac{1}{2}$$

$$E \{ a_k^2 \} = \frac{1}{2} A^2 + \frac{1}{2} (-A)^2 = A^2 = P_d$$

Data Symbol Power

$$= P_d \sum_{k=-\infty}^{\infty} p_T(t-kT) p_T(t+\tau-kT)$$

depends on t

Hence NOT WSS

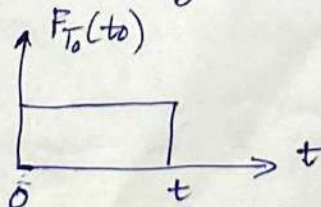
(Wide Sense Stationary)

$$x(t) = \sum_{k=-\infty}^{\infty} a_k p_T(t-kT-t_0)$$

Random Delay

uniformly distributed in $[0, T]$

uniform prob.
Density Function.



$$E \{ x(t) \cdot x(t+\tau) \} = P_d \sum_{k=-\infty}^{\infty} E \{ P_T(x-kT-t_0) P_T(x+\tau-kT-t_0) \}$$

Average / Expected value w.r.t. t_0

$$= P_d \sum_{k=-\infty}^{\infty} \int_{-\infty}^{\infty} F_{T_0}(t_0) P_T(x-kT-t_0) P_T(x+\tau-kT-t_0) dt_0$$

Averaging w.r.t. t_0
(random delay)

$$F_{T_0}(t_0) = \begin{cases} \frac{1}{T}, & 0 < t_0 \leq T \\ 0, & \text{otherwise} \end{cases}$$

$$= \frac{P_d}{T} \sum_{k=-\infty}^{\infty} \int_0^T P_T(x-kT-t_0) P_T(x+\tau-kT-t_0) dt_0$$

$$x_0 + kT = \tilde{t}_0$$

$$dt_0 = d\tilde{t}_0$$

$$= \frac{P_d}{T} \sum_{k=-\infty}^{\infty} \int_{kT}^{(k+1)T} P_T(x-\tilde{t}_0) P_T(x+\tau-\tilde{t}_0) d\tilde{t}_0$$

Each integral is from kT to $(k+1)T$

$$= \frac{P_d}{T} \int_{-\infty}^{\infty} P_T(x-\tilde{t}_0) P_T(x+\tau-\tilde{t}_0) d\tilde{t}_0$$

$$-\tilde{t}_0 + x + \tau = t'_0$$

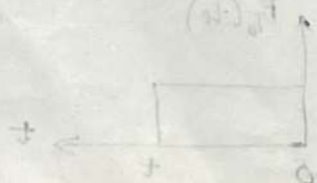
$$\Rightarrow -d\tilde{t}_0 = dt'_0$$

$$= \frac{P_d}{T} \int_{-\infty}^{\infty} P_T(t'_0 - \tau) P_T(t'_0) (-dt'_0)$$

$$= \frac{P_d}{T} \int_{-\infty}^{\infty} P_T(t'_0) P_T(t'_0 - \tau) dt'_0$$

independent of t
only depends on τ

Hence, $x(t)$ is WSS



$$E \{ x(t) \cdot x(t+\tau) \} = R_{xx}(\tau)$$

$$\int_{-\infty}^{\infty} P_T(t_0 - \tau) \cdot P(t_0) dt_0$$

ACF

$R_{P_T P_T} \leftarrow$ ACF of pulse P_T

$$R_{xx}(\tau) = E \{ x(t) x(t+\tau) \} = \frac{P_d}{T} R_{P_T P_T}(\tau)$$

ACF of signal depends on
ACF of pulse $P_T(t)$

F.T.

$$S_{xx}(F) = \frac{P_d}{T} S_{P_T P_T}(F)$$

Energy Spectral Density of $P_T(t)$

PSD of transmitted
signal $x(t)$

$$\begin{aligned} \text{F.T.} \left\{ \begin{aligned} R_{pp}(\tau) &= \int_{-\infty}^{\infty} p(t) p(t-\tau) dt \\ S_{pp}(F) &= \int_{-\infty}^{\infty} R_{pp}(\tau) e^{-j2\pi F\tau} d\tau \end{aligned} \right. \end{aligned}$$

$$\Rightarrow \boxed{S_{pp}(F) = |P(F)|^2} \quad P(F) : \text{F.T. of pulse } p(t)$$

ESD of $p(t)$

$$P(F) = \int_{-\infty}^{\infty} p(t) e^{-j2\pi Ft} dt$$

$$R_{xx}(\tau) = \frac{P_d}{T} R_{pp}(\tau)$$

$$S_{xx}(F) = \int_{-\infty}^{\infty} R_{xx}(\tau) e^{-j2\pi F\tau} d\tau$$

For a WSS process, PSD is given by F.T. of ACF.

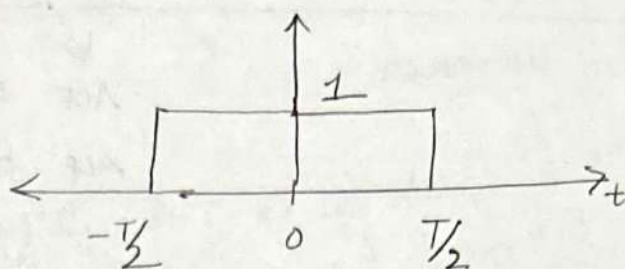
$$S_{xx}(F) = \frac{P_d}{T} S_{pp}(F) = \frac{P_d}{T} |P(F)|^2$$

PSD of transmitted

signal is proportional to Energy Spectral Density of pulse

Example :

Consider $p(t) = P_T(t)$



$$P_T(F) = T \operatorname{sinc}(FT) = T \frac{\sin(\pi FT)}{(\pi FT)}$$

$$|P_T(F)|^2 = T^2 \operatorname{sinc}^2(FT)$$

$$\text{PSD} = \frac{P_d}{T} \times T^2 \operatorname{sinc}^2(FT) = P_d T \operatorname{sinc}^2(FT)$$

$$\Rightarrow \boxed{S_{xx}(F) = P_d T \operatorname{sinc}^2(FT)}$$

PSD of transmitted signal

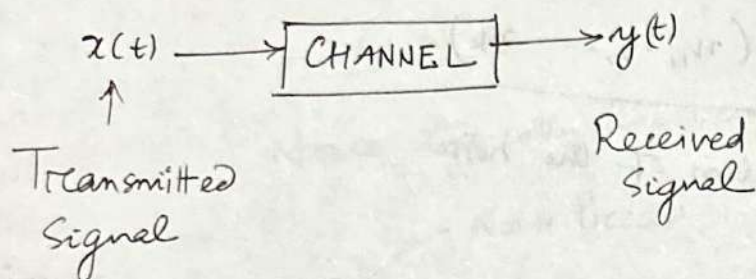
DIGITAL COMMUNICATION CHANNEL

Channel := Medium through which signal travels from transmitter to receiver in a communication system.

Example :- Telephone lines, Coaxial cables, Wireless Channel.

Ex :- AM, FM, Cellular, WiFi, Bluetooth.

$$x(t) = \sum_{k=-\infty}^{\infty} a_k p(t-kT)$$



Simple Channel model := (AWGN) channel
(Additive White Gaussian Noise)

$$y(t) = x(t) + n(t)$$

Received Signal $y(t)$ = Transmitted Signal $x(t)$ + Noise $n(t)$
Additive (Noise adds to the signal)
(Noise is termed as additive noise)

$N(t)$

↳ Random Process

Popular Noise Model → Gaussian Noise

⇒ Noise is a Gaussian Random Process.

Gaussian Random Process

$N(t)$ is a Gaussian random process if statistics of all orders are jointly Gaussian.

This means:

Consider noise samples

$$\underbrace{N(t_1), N(t_2), \dots, N(t_k)}$$

k - noise samples at time t_1, t_2, \dots, t_k .

$$F_{N(t_1), N(t_2), \dots, N(t_k)}(n_1, n_2, \dots, n_k)$$

Joint distribution of the noise samples.

If this is jointly Gaussian; i.e. follows a multivariate

Gaussian Density

For all t_1, t_2, \dots, t_k & for all k .

Then termed as a Gaussian Random Process.

$$\rightarrow \text{Noise} + \text{Gaussian Random Process} = \text{Gaussian Noise}$$

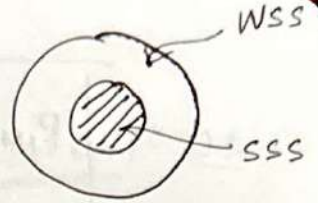
Gaussian Noise Process

→ of WSS (Wide Sense Stationary)

Also SSS (Strict Sense Stationary)

All SSS are WSS, converse is not true.

Only for a Gaussian random process, $WSS \Rightarrow SSS$



$N(t)$ is WSS if

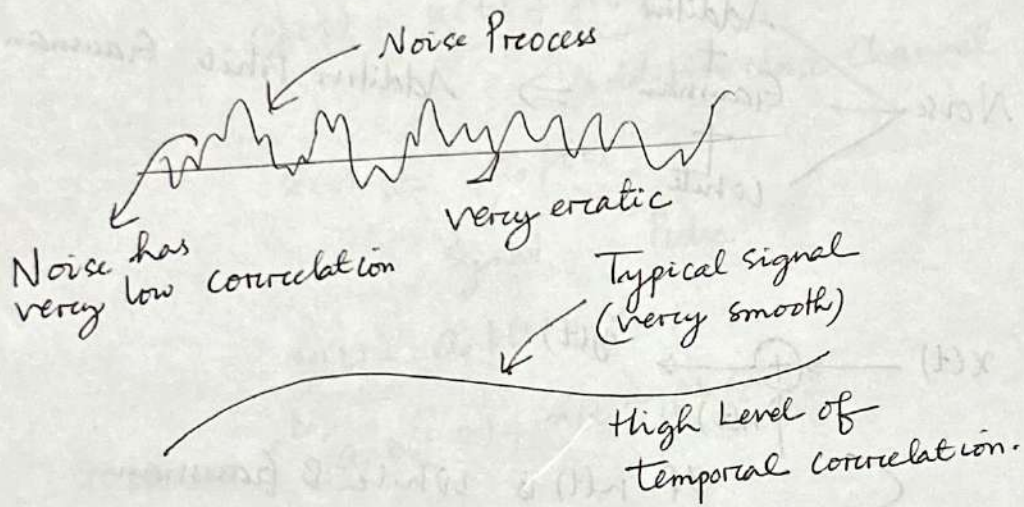
i) $E \{ N(t) \} = \mu \quad \forall t$

ii) $E \{ N(t) N(t+\tau) \} = R_{NN}(\tau) \quad \forall t, \tau$

↳ depends only on τ (time difference)

White Noise

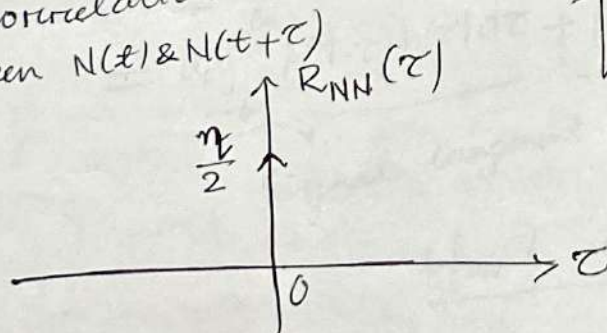
Noise typically has very low correlation.



$$E \{ N(t) \cdot N(t+\tau) \} = \frac{\eta}{2} \delta(\tau) = R_{NN}(\tau)$$

Correlation between $N(t)$ & $N(t+\tau)$
 $R_{NN}(\tau)$

Correlation = 0, if $\tau \neq 0$

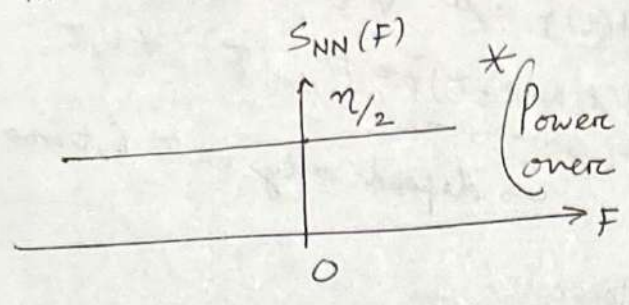


ACF: $R_{NN}(\tau) = \frac{\eta}{2} \delta(\tau)$

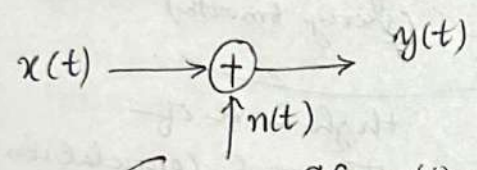
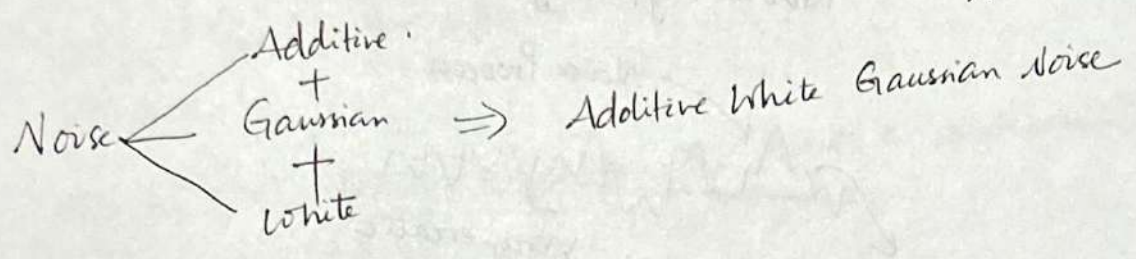
White Noise

Noise samples at any two different time instants t & $t+\tau$ are uncorrelated.

PSD: $S_{NN}(F) = FT[R_{NN}(\tau)] = \frac{\eta}{2}$



* (Power is spread uniformly over all frequencies) → (similar to white light)
 ↓
 'PSD is Flat'
 Hence termed as White Noise.

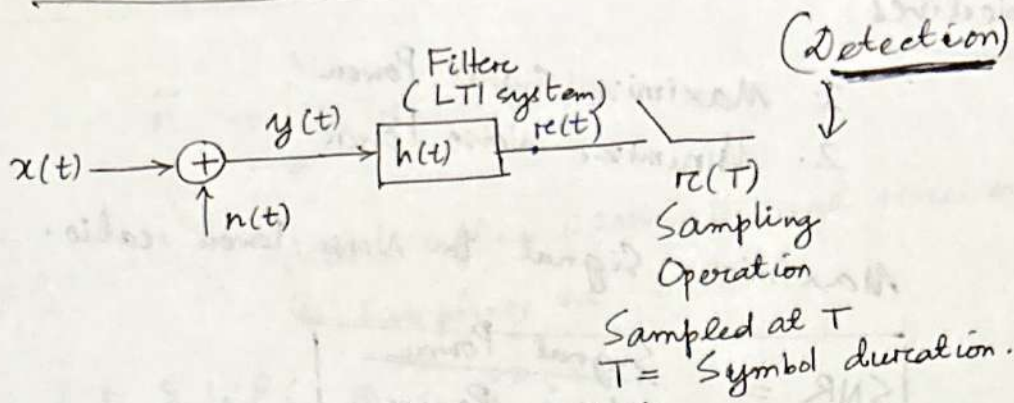


if $n(t)$ is White & Gaussian

\Rightarrow AWGN Channel

Most popular & practically applicable for Digital Communication system.

Digital Communication Receiver



$$r(t) = y(t) * h(t) \quad \rightarrow \text{Impulse response of LTI sys (or) Receiver Filter.}$$

$$= \int_{-\infty}^{\infty} y(t-\tau) \cdot h(\tau) d\tau$$

$$y(t) = \underbrace{x(t) + n(t)}_{\text{Additive Noise Channel}}$$

$$x(t) = a_0 p(t)$$

Symbol Pulse

$$y(t) = a_0 p(t) + n(t)$$

$$r(t) = \int_{-\infty}^{\infty} \{ a_0 p(t-\tau) + n(t-\tau) \} h(\tau) d\tau$$

Sampled at T.

$$r(T) = \int_{-\infty}^{\infty} [a_0 p(T-\tau) + n(T-\tau)] h(\tau) d\tau$$

$$= \underbrace{a_0 \int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau}_{\text{Signal component}} + \underbrace{\int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau}_{\text{Noise component}}$$

How to design, $h(\tau)$?

Objectives

1. Maximize Signal Power
2. Minimize Noise Power

Maximize Signal-to-Noise Power ratio.

$$\boxed{\text{SNR} = \frac{\text{Signal Power}}{\text{Noise Power}}}$$

Fundamental quantity for analysis of performance of a communication system.

Signal:

$$a_0 \int_{-\infty}^{\infty} p(T-\tau) \cdot h(\tau) d\tau$$

$$\begin{aligned} \text{Signal Power} &= E \left\{ \left| a_0 \int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau \right|^2 \right\} \\ &= E \left\{ |a_0|^2 \right\} E \left\{ \left| \int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau \right|^2 \right\} \\ &= E \left\{ a_0^2 \right\} E \left\{ \left(\int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau \right)^2 \right\} \end{aligned}$$

Symbols are random

P_d = Power of Data Symbols

$$P_d = E \left\{ |a_0|^2 \right\}$$

$\therefore p(t)$ & $h(t)$ are deterministic

$$= P_d \left(\int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau \right)^2$$

Signal Power

Noise Power

$$\tilde{n} = \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau$$

↳ Noise after passing through receiver filter & sampling at $t=T$.

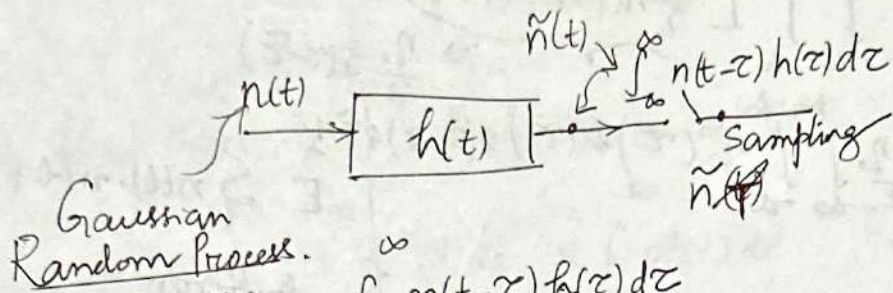
$$E \{ |\tilde{n}|^2 \} = E \{ \tilde{n}^2 \}$$

↳ (Assuming all quantities are real)

$n(t)$ ← White + Gaussian

$$E \{ n(t) \} = 0 \quad (\text{Zero mean})$$

$$E \{ n(t) \cdot n(t+\tau) \} = \frac{\eta_0}{2} \delta(\tau) = R_{NN}(\tau)$$



Gaussian Random Process.

$$\tilde{n}(t) = \int_{-\infty}^{\infty} n(t-\tau) h(\tau) d\tau$$

↳ Gaussian Random process, since the filter is a linear system.

$$\tilde{n} = \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau$$

$$E \{ \tilde{n} \} = E \left\{ \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau \right\}$$

$$= \int_{-\infty}^{\infty} E \{ n(T-\tau) \} h(\tau) d\tau$$

Deterministic quantity.

$$\therefore \boxed{E \{ \tilde{n} \} = 0}$$

= 0 since $n(t) = 0$

$$E \{ \tilde{n}^2 \} = ?$$

↪ Variance or Noise Power

$$= E \{ \tilde{n} \cdot \tilde{n} \}$$

$$= E \left\{ \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau \times \int_{-\infty}^{\infty} n(T-\tilde{\tau}) h(\tilde{\tau}) d\tilde{\tau} \right\}$$

$$= E \left\{ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} n(T-\tau) n(T-\tilde{\tau}) h(\tau) h(\tilde{\tau}) d\tau d\tilde{\tau} \right\}$$

(Putting the integrals together)

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E \{ n(T-\tau) \cdot n(T-\tilde{\tau}) \} \cdot h(\tau) \cdot h(\tilde{\tau}) d\tau d\tilde{\tau}$$

$$= \frac{\eta_0}{2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau) h(\tilde{\tau}) \delta(\tilde{\tau}-\tau) d\tilde{\tau} d\tau$$

$E \{ n(t) \cdot n(t+\tau) \} = \frac{\eta_0}{2} \delta(\tau)$

$$= \frac{\eta_0}{2} \int_{-\infty}^{\infty} h(\tau) d\tau \left(\int_{-\infty}^{\infty} h(\tilde{\tau}) \delta(\tilde{\tau}-\tau) d\tilde{\tau} \right) d\tau$$

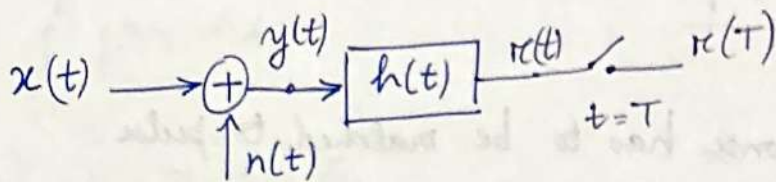
~~different~~ depends on time difference τ .

$$= \frac{\eta_0}{2} \int_{-\infty}^{\infty} h(\tau) \cdot h(\tau) d\tau$$

$$= \frac{\eta_0}{2} \int_{-\infty}^{\infty} |h(\tau)|^2 d\tau = \frac{\eta_0}{2} E_h \left\{ E_h = \text{Energy of Filter} \right\}$$

$$E \{ \tilde{n}^2 \} = \frac{\eta_0}{2} E_h = \frac{\eta_0}{2} \int_{-\infty}^{\infty} |h(\tau)|^2 d\tau$$

↪ Noise Power at op of sampler.
or Variance of \tilde{n}



$$\text{Signal} \rightarrow \int_{-\infty}^{\infty} a_0 p(T-\tau) h(\tau) d\tau$$

$$\text{Noise} \rightarrow \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau$$

$$\text{SNR} = \frac{\text{Signal Power}}{\text{Noise Power}}$$

$$\text{Signal-to-Noise Power Ratio} = \frac{P_d \left(\int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau \right)^2}{\frac{\eta_0}{2} \int_{-\infty}^{\infty} |h(\tau)|^2 d\tau}$$

We have to find filter $h(t)$ which maximizes SNR

$$\int_{-\infty}^{\infty} (u(t)v(t))^2 dt \leq \int_{-\infty}^{\infty} u^2(t) dt \times \int_{-\infty}^{\infty} v^2(t) dt$$

Cauchy-Schwarz inequality

Using Cauchy-Schwarz inequality,

Equality holds when

$$\Rightarrow u(t) = kv(t)$$

$$\text{SNR} \leq \frac{P_d \int_{-\infty}^{\infty} p^2(T-\tau) d\tau \times \int_{-\infty}^{\infty} h^2(\tau) d\tau}{\frac{\eta_0}{2} \int_{-\infty}^{\infty} h^2(\tau) d\tau}$$

$$\Rightarrow \text{SNR} \leq \frac{P_d \int_{-\infty}^{\infty} p^2(T-\tau) d\tau}{\left(\frac{\eta_0}{2}\right)}$$

SNR is maximized when Equality holds when &

$$p(T-\tau) \propto h(\tau)$$

$$\Rightarrow p(T-\tau) = kh(\tau)$$

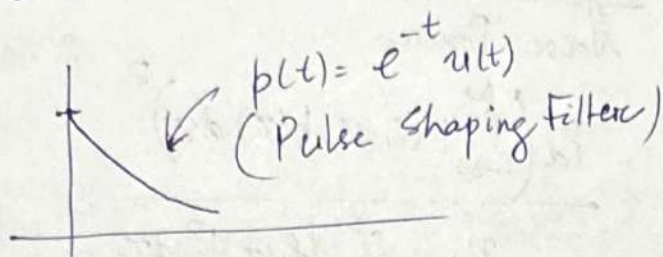
without loss of generality $k=1$

$$h(\tau) = p(T-\tau)$$

Principle
of
Matched
Filters

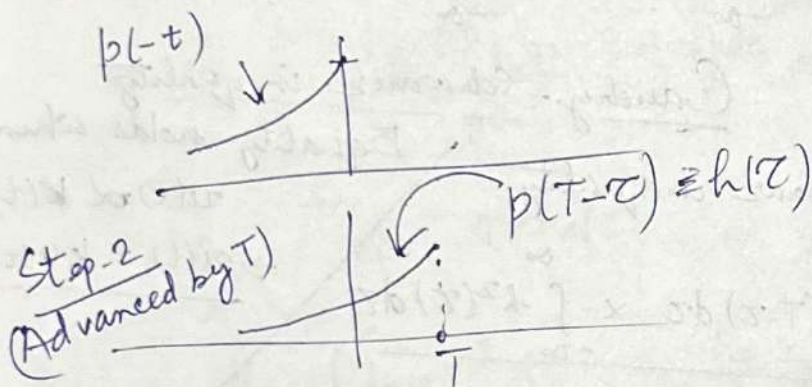
impulse response has to be matched to pulse shaping filter. Hence it is termed as a matched filter.

To maximize SNR at receiver, one has to employ a matched filter. ^{output}



$$h(\tau) = p(T-\tau)$$

Step-1 (Flip)



Maximum SNR for the matched Filter is:-

$$\text{SNR} = \frac{P_d \int_{-\infty}^{\infty} p^2(T-\tau) d\tau}{\left(\frac{\eta_0}{2}\right)}$$

$$= \frac{P_d \int_{-\infty}^{\infty} |h(\tau)|^2 d\tau}{\frac{\eta_0}{2}}$$

$$\int_{-T}^0 p^2(z) dz$$

$$T - z = z' \\ \Rightarrow -dz = dz'$$

$$= \int_{-\infty}^{\infty} p^2(z') (-dz') \\ = \int_{-\infty}^{\infty} p^2(z) dz$$



Energy of pulse shaping filter

$$\boxed{\begin{aligned} \text{SNR} &= \frac{P_d}{\left(\frac{\eta_0}{2}\right)} \int_{-\infty}^{\infty} h^2(z) dz \\ &= \frac{P_d}{\left(\frac{\eta_0}{2}\right)} \int_{-\infty}^{\infty} p^2(z) dz \end{aligned}}$$

Maximum SNR for matched Filter

$$\boxed{\text{SNR} = \frac{P_d}{\left(\frac{\eta_0}{2}\right)} \int_{-\infty}^{\infty} p^2(z) dz}$$

Matched Filter

$$h(z) = p^*(T-z)$$

$$h(z) = p^*(T-z)$$

Energy of pulse shaping filter

Probability of Error in Digital Comm. System

→ Transmit several symbols

→ The Prob. of error is an important metric to characterize the performance of a digital communication system.

→ Aim is to minimize the Prob of Error

$$(\sim 10^{-6} - 10^{-8})$$

Typical values of Prob. of Error

For a given scheme, how to characterize the prob. of error?

← After filtering with $h(t)$ & sampling at $t=T$

$$r(T) = a_0 \int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau + \int_{-\infty}^{\infty} n(T-\tau) h(\tau) d\tau$$

$$= a_0 \int_{-\infty}^{\infty} p(T-\tau) h(\tau) d\tau + \tilde{n}$$

↑
Gaussian

To maximize SNR

$$\boxed{p(T-\tau) = h(\tau)}$$

"Matched Filter"

$$r(T) = a_0 \int_{-\infty}^{\infty} p^2(T-\tau) d\tau + \tilde{n} = a_0 E_p + \tilde{n}$$

$$= \int_{-\infty}^{\infty} p^2(\tau) d\tau = E_p$$

↑
Energy of pulse shaping filter

$$r(T) = a_0 E_p + \tilde{n}$$

$a_0 E_p$ → Transmitted Symbol
 \tilde{n} → Pulse Energy, Gaussian Noise

$$E \{ \tilde{n} \} = 0 \quad (\text{Zero mean})$$

$$E \{ \tilde{n}^2 \} = \frac{\eta_0}{2} \int_{-b}^b |h(\tau)|^2 d\tau$$

$$= \frac{\eta_0}{2} \int_{-b}^b p^v(\tau) d\tau = \frac{\eta_0}{2} E_p$$

$$\tilde{n} \sim \mathcal{N} \left(0, \frac{\eta_0}{2} E_p \right)$$

(Noise after Sampling) → Gaussian
 Mean → 0
 Variance → $\frac{\eta_0}{2} E_p$

$$\mathcal{N}(\mu, \sigma^2)$$

↳ Gaussian of

Noise mean = μ

Variance = σ^2

$$\mathcal{N}(0, 1)$$

Mean

Variance = 1 (unity)

Standard Gaussian

(or) Standard Normal

$$r(t) = a_0 E_p + \tilde{n}$$

↳ Symbols must belong to a digital constellation in a digital comm. system.

$$a_0 = -A \text{ or } +A$$

$$\begin{array}{cccccc} 0 & 1 & 1 & 0 & 1 & 0 & \dots \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \\ A, & -A, & -A, & A, & -A, & A & \end{array}$$
 Information bits

$$\begin{array}{l} 0 \rightarrow A \\ 1 \rightarrow -A \end{array} \left. \vphantom{\begin{array}{l} 0 \rightarrow A \\ 1 \rightarrow -A \end{array}} \right\} \text{Mapping}$$

$$r(t) = \pm A E_p + \tilde{n}$$

$$\left[\begin{array}{l} r(t) = A E_p + \tilde{n} \\ r(t) = -A E_p + \tilde{n} \end{array} \right. \begin{array}{l} a_0 = A \\ a_0 = -A \end{array}$$

$\rightarrow \sigma_p$ after sampling

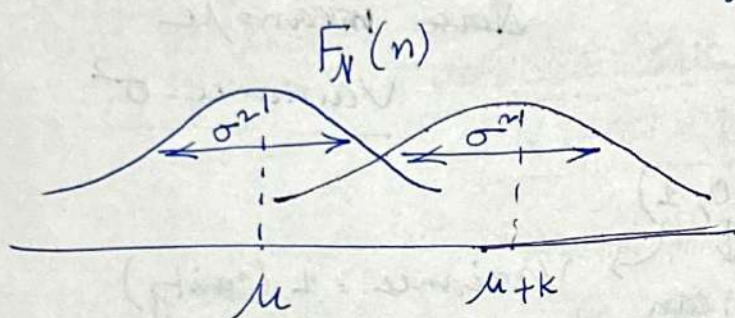
Property :

if $n \sim \mathcal{N}(\mu, \sigma^2)$

Then $n+k \sim \mathcal{N}(\mu+k, \sigma^2)$

constant

Variance is unchanged.

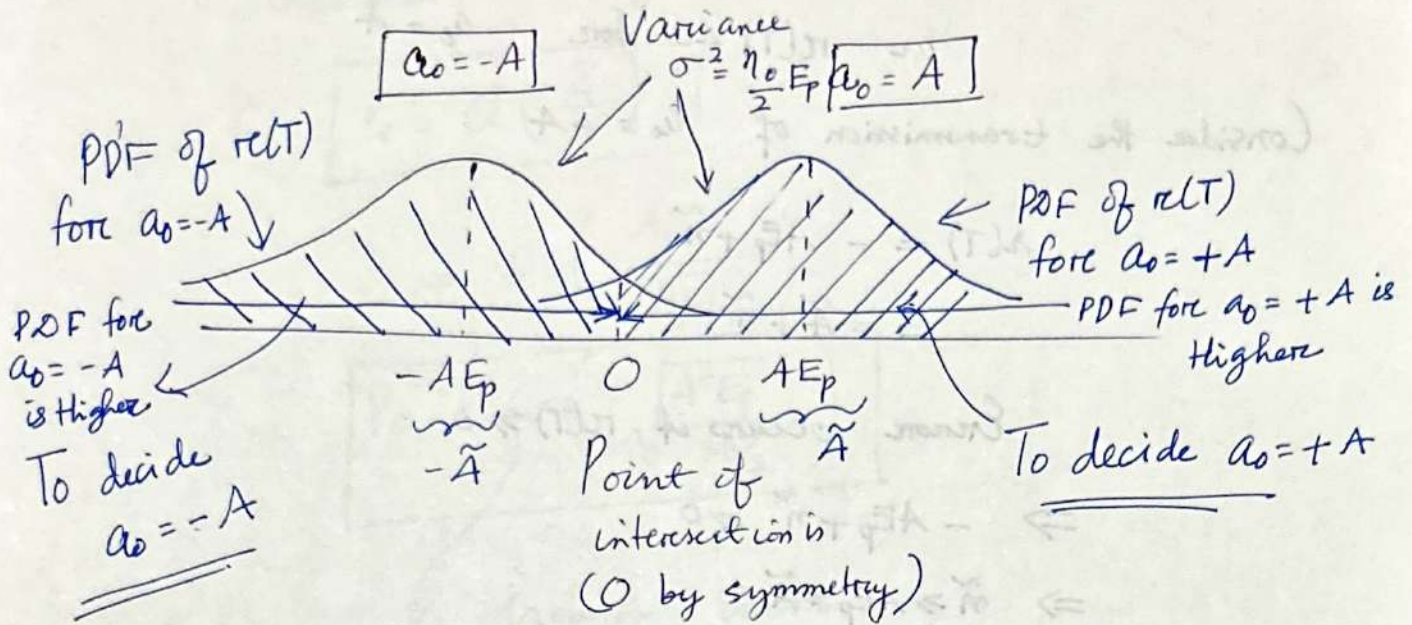


$$r(t) = \begin{cases} A E_p + \tilde{n} & \sim \mathcal{N}(A E_p, \sigma^2) \\ -A E_p + \tilde{n} & \sim \mathcal{N}(-A E_p, \sigma^2) \end{cases}$$

$r(T)$ is Gaussian
Mean = AE_p

$r(t)$ is Gaussian
Mean = $-AE_p$

For Both cases variance is same, $\sigma^2 = \frac{\eta_0}{2} E_p$



Both have same variance

$$r(T) = \begin{cases} AE_p + \tilde{n} \\ -AE_p + \tilde{n} \end{cases} \quad \begin{matrix} \tilde{n} \rightarrow \mathcal{N}(0, E_p) \\ \mathcal{N}(0, \frac{\eta_0}{2} E_p) \\ N_0 = \frac{\eta_0}{2} \end{matrix}$$

$$\mathcal{N}(AE_p, \frac{\eta_0}{2} E_p)$$

$$\mathcal{N}(-AE_p, \frac{\eta_0}{2} E_p)$$

$$r(T) = \begin{cases} \mathcal{N}(\tilde{A}, \sigma^2), & \text{for } a_0 = +A \\ \mathcal{N}(-\tilde{A}, \sigma^2), & \text{for } a_0 = -A \end{cases}$$

Detection rule / Decision rule

$$\begin{cases} r(T) \geq 0 \Rightarrow \text{decide } a_0 = +A \\ r(T) < 0 \Rightarrow \text{decide } a_0 = -A \end{cases}$$

Corresponds to information bit 0

Corresponds to information bit 1

Probability of Error

When does error occur?

Error occurs when

$$r(T) \geq 0 \text{ for } a_0 = -A$$

$$\text{or } r(T) < 0 \text{ for } a_0 = A$$

Consider the transmission of $a_0 = -A$

$$\begin{aligned} r(T) &= -AE_p + \tilde{n} \\ &= -\tilde{A} + \tilde{n} \end{aligned}$$

Error occurs if $r(T) \geq 0$

$$\Rightarrow -AE_p + \tilde{n} \geq 0$$

$$\Rightarrow \tilde{n} \geq AE_p = \tilde{A}$$

$$P_e = P_r(\tilde{n} \geq \tilde{A})$$

$$\begin{aligned} &= \int_{\tilde{A}}^{\infty} F_N(\tilde{n}) d\tilde{n} \\ &= \int_{\tilde{A}}^{\infty} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{\tilde{n}^2}{2\sigma^2}} d\tilde{n} \end{aligned}$$

$$\begin{aligned} &= \int_{\frac{\tilde{A}}{\sigma}}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{n'^2}{2}} \sigma dn' \\ &= \int_{\frac{\tilde{A}}{\sigma}}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{n'^2}{2}} dn' \end{aligned}$$

PDF of standard Gaussian with mean=0 & variance=1

$$Q(u) = \int_u^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$$

↓ Gaussian Q function denotes that standard Gaussian RV is greater than u .

$$\text{So, } \boxed{P_e = Q\left(\frac{\tilde{A}}{\sigma}\right)}$$

$$= Q\left(\frac{AE_p}{\sqrt{\frac{N_0}{2} E_p}}\right)$$

$$\boxed{P_e = Q\left(\sqrt{\frac{A^2 E_p}{N_0/2}}\right)}$$

↓ Prob. of Error
Gaussian Q function.

BINARY PHASE SHIFT KEYING (BPSK)

- A digital modulation scheme.

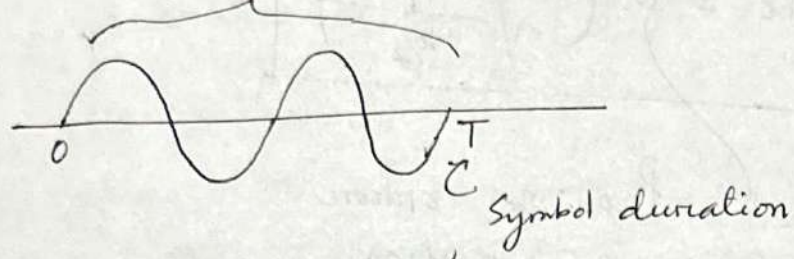
BPSK

Pulse, $p(t) = \sqrt{\frac{2}{T}} \cos(2\pi F_c t)$, $0 \leq t \leq T$
Symbol duration.

$T = \text{Integral multiple of } \frac{1}{F_c}$

$$\Rightarrow \boxed{T = \frac{K}{F_c}}$$

$$p(t) = \frac{\sqrt{2}}{\sqrt{T}} \cos(2\pi F_c t)$$



Contains 2 cycles of cosine waveform.

$$\Rightarrow \boxed{T = \frac{2}{F_c}}$$

$p(t)$ is normalized to unit energy

$$E_p = \int_{-\infty}^{\infty} p^2(t) dt = \int_0^T \frac{2}{T} \cos^2(2\pi F_c t) dt$$
$$= \frac{2}{T} \int_0^T \frac{1 + \cos 4\pi F_c t}{2} dt = \frac{2}{T} \times \frac{1}{2} T = 1$$

$$\Rightarrow \boxed{E_p = 1}$$

$$x(t) = a_0 p(t), \quad a_0 \in \left\{ \begin{array}{c} -A, +A \\ \uparrow \quad \uparrow \\ 1 \quad 0 \end{array} \right\}$$

Each a_0 carries 1 bit of information.

$E_b =$ Energy per bit
 ↖ Constant across schemes.

information bits $\begin{cases} 0 \rightarrow \text{occurs with prob } \frac{1}{2} \\ 1 \rightarrow \text{ " " " } \frac{1}{2} \end{cases}$

$$a_0 = \pm A \quad x(t) = a_0 p(t)$$

Average Energy per bit

$$\frac{1}{2} A^2 E_p + \frac{1}{2} A^2 E_p = A^2 E_p = A^2 \quad (\because E_p = 1)$$

$$\begin{aligned} A^2 &= E_b \\ \Rightarrow A &= \sqrt{E_b} \end{aligned}$$

This ensures average energy/bit = E_b

Therefore, the transmitted waveforms are

$$0 \rightarrow a_0 = +A = \sqrt{E_b}$$

$$\therefore x(t) = \sqrt{E_b} \sqrt{\frac{2}{T}} \cos(2\pi F_c t), \quad 0 \leq t \leq T$$

$$x(t) = \sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t), \quad 0 \leq t \leq T$$

Waveform corresponding to bit 0

$$1 \rightarrow a_0 = -A = -\sqrt{E_b}$$

$$x(t) = -\sqrt{E_b} \sqrt{\frac{2}{T}} \cos(2\pi F_c t), \quad 0 \leq t \leq T$$

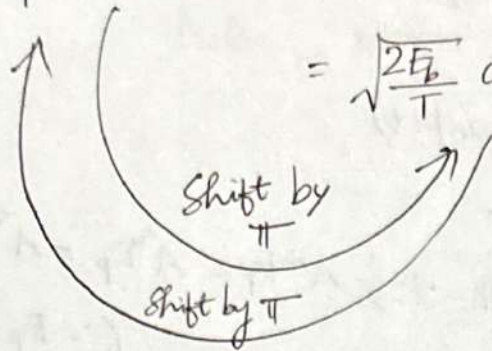
Waveform corresponding to bit 1

Waveforms



$$\sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t) \quad -\sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t)$$

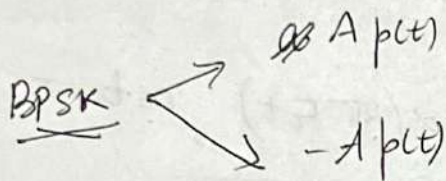
$$= \sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t + \pi)$$



$$\sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t + \pi + \pi) = \sqrt{\frac{2E_b}{T}} \cos(2\pi F_c t)$$

Two waveforms \Rightarrow Binary modulation scheme

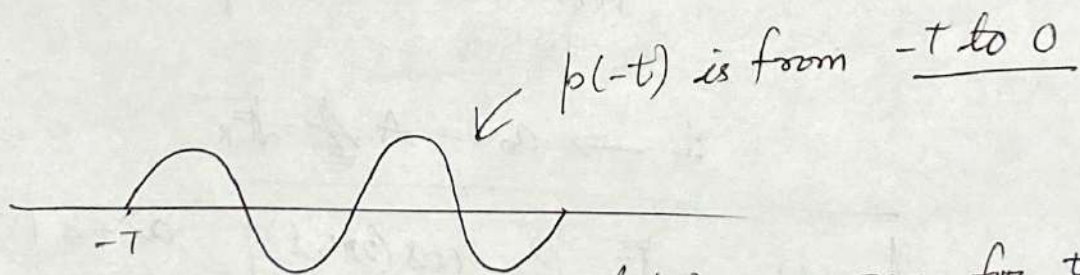
Waveforms are phase shifted w.r.t. each other.



$$p(t) = \sqrt{\frac{2}{T}} \cos(2\pi F_c t)$$

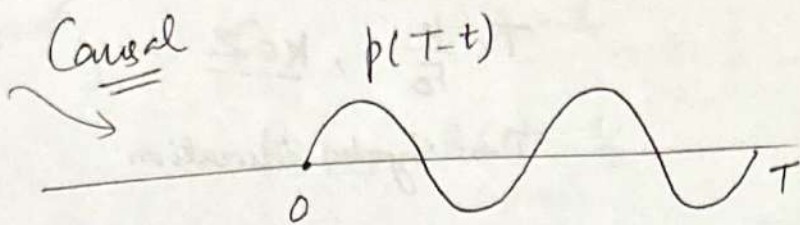
$$A = \sqrt{E_b}$$

At receiver, matched Filter is $h(t) = p(T-t)$



$h(t)$ is nonzero for $t \leq 0$
 \Downarrow
 Non-causal system.

Shifting by T , to make it causal.
 (Delaying)



$r(t) \geq 0 \Rightarrow$ decide $a_0 = A = \sqrt{E_b} \Rightarrow \text{bit} = 0$
 $r(t) < 0 \Rightarrow$ decide $a_0 = -A = -\sqrt{E_b} \Rightarrow \text{bit} = 1$
 \rightarrow optimal decision rule

$$P_e = Q\left(\sqrt{\frac{A^2 E_p}{N_0/2}}\right)$$

$$A = \sqrt{E_b}$$

$$E_p = 1$$

$$P_e = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

Prob. of error of
 BPSK
 with avg. energy per bit
 $= E_b$

$$Q(x) = \int_x^{\infty} \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt \rightarrow \text{Denotes the prob.}$$

that $N(0, 1) \Rightarrow x$

AMPLITUDE ~~SHIFT~~ SHIFT KEYING (ASK)

→ A digital modulation scheme.

$$p(t) = \sqrt{\frac{2}{T}} \cos(2\pi F_c t), 0 \leq t \leq T$$

$$T = \frac{k}{F_c}, k \in \mathbb{Z}$$

$T \rightarrow$ Symbol Duration

$$E_p = \int_0^T p^2(t) dt = 1$$

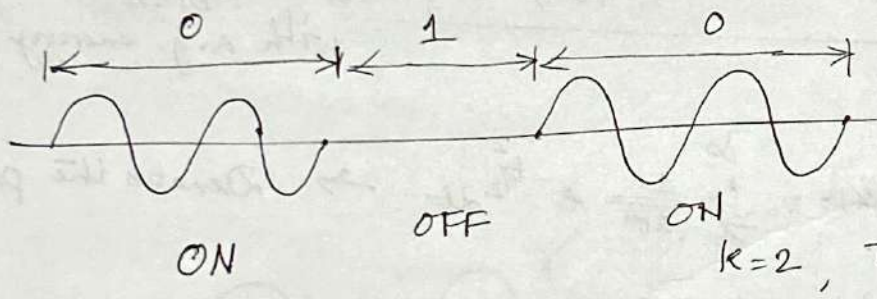
↪ Energy of pulse is unity

$$a_0 = \{0, 1\} \Rightarrow a_0 = A \text{ or } 0$$

Waveforms differ in amplitude.

information bits

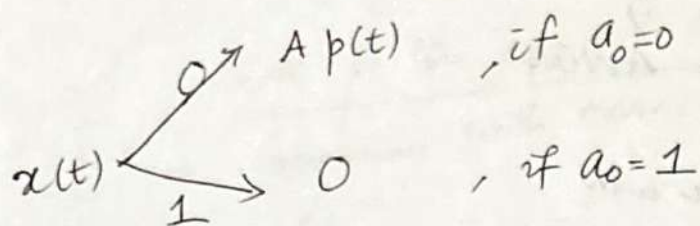
$$\left\{ \begin{array}{l} 0 \rightarrow A \sqrt{\frac{2}{T}} \cos(2\pi F_c t), 0 \leq t \leq T \\ 1 \rightarrow 0, p(t) = 0, 0 \leq t \leq T \end{array} \right.$$



ASK is also termed as ON-OFF Keying.

How to choose A?

Bit energy = E_b (constant)



$$Pr(0) = Pr(1) = \frac{1}{2}$$

Average energy per bit

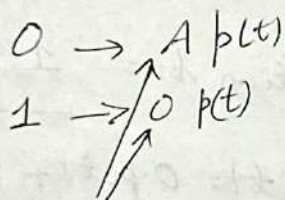
$$= \frac{1}{2} A^2 E_p + 0 = \frac{1}{2} A^2 E_p.$$

$$\frac{1}{2} A^2 E_p = E_b$$

$$\Rightarrow \frac{A^2}{2} = E_b \quad (\because E_p = 1)$$

$$\Rightarrow \boxed{A = \sqrt{2E_b}}$$

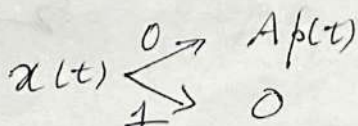
This ensures energy/bit is constant across the schemes.



both waveforms differ in amplitude

\Rightarrow This modulation scheme is termed as amplitude shift keying (ASK).

Prob. of error,



At the receiver

$$y(t) = x(t) + n(t)$$

AWGN.

Matched Filter with

$$h(t) = p(T-t)$$

Followed by sampling at $t=T$.

Consider, transmission bit = 0

$$x_y(t) = A p(t) + n(t)$$

After matched filtering followed by sampling at $t=T$,

$$z(T) = A E_p + \tilde{n}$$

Gaussian

mean = 0

$$\text{Variance} = \frac{N_0}{2} E_p = \frac{N_0}{2}$$

Consider, information bit = 1

$$y(t) = 0 \cdot p(t) + n(t) = n(t)$$

After matched filtering & sampling at $t=T$,

$$z(T) = \tilde{n}$$

Gaussian

Mean = 0

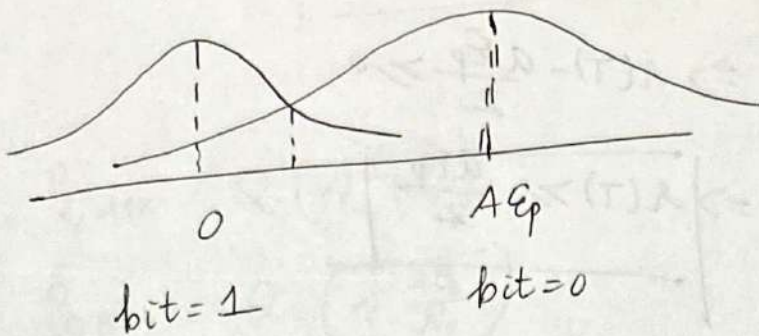
$$\text{Variance} = \frac{N_0}{2} E_p$$

$$r(T) = \begin{cases} A\epsilon_p + \tilde{n}, & \text{if } a_0 = A \\ 0 + \tilde{n}, & \text{if } a_0 = 0 \end{cases}$$

What is the optimal decision rule?

$r(T)$ is Gaussian with mean = $A\epsilon_p$

Gaussian with mean = 0



By Symmetry, midpoint = $\frac{A\epsilon_p}{2}$

Optimum decision rule:

$$\begin{array}{|l} r(T) \geq \frac{A\epsilon_p}{2} \Rightarrow a_0 = A \\ r(T) < \frac{A\epsilon_p}{2} \Rightarrow a_0 = 0 \end{array}$$

Optimum decision rule.

$$\tilde{r}(T) = r(T) - \frac{A\epsilon_p}{2} = \begin{cases} \frac{A\epsilon_p}{2} + \tilde{n}, & \text{if } a_0 = A \\ -\frac{A\epsilon_p}{2} + \tilde{n}, & \text{if } a_0 = 0 \end{cases}$$

Similar to BPSK with $A\epsilon_p$ replaced by $\frac{A\epsilon_p}{2}$

Decide

$$a_0 = A \quad \text{if } \tilde{r}(T) > 0 \Rightarrow r(T) \geq \frac{A\epsilon_p}{2}$$

$$a_0 = 0 \quad \text{if } \tilde{r}(T) < 0 \Rightarrow r(T) < \frac{A\epsilon_p}{2}$$

Decide

$$a_0 = A$$

$$\text{if } \tilde{r}(T) \geq 0$$

$$\Rightarrow r(T) - \frac{A\epsilon_p}{2} \geq 0$$

$$\Rightarrow \boxed{r(T) \geq \frac{A\epsilon_p}{2}}$$

$$r(T) \geq \frac{A\epsilon_p}{2} \Rightarrow \text{Decide } a_0 = A$$

$$r(T) < \frac{A\epsilon_p}{2} \Rightarrow \text{Decide } a_0 = 0$$

$$\tilde{r}(T) = \begin{cases} \frac{A\epsilon_p}{2} + \tilde{n} \\ -\frac{A\epsilon_p}{2} + \tilde{n} \end{cases}$$

Prob. of bit error, is similar to BPSK
with $A\epsilon_p$ replaced by $\frac{A\epsilon_p}{2}$

$$P_e = Q\left(\frac{\frac{A\epsilon_p}{2}}{\sqrt{\frac{N_0}{2}\epsilon_p}}\right) = Q\left(\frac{\sqrt{A^2\epsilon_p}}{2N_0}\right)$$

$$\epsilon_p = 1, \quad A^2 = 2\epsilon_b$$

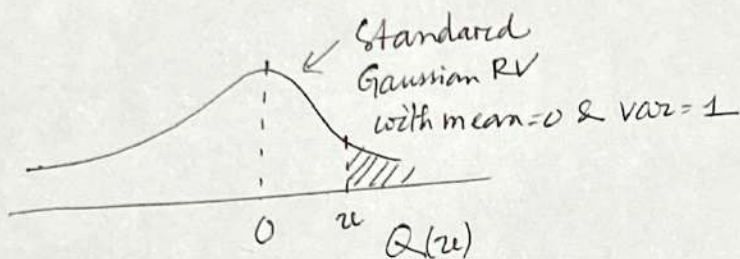
$$P_e = Q\left(\sqrt{\frac{2E_b}{N_0}}\right) = Q\left(\frac{E_b}{N_0}\right)$$

Probability of error for ASK

for BPSK

$$P_e = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

$$\begin{cases} P_{e, \text{ASK}} = Q\left(\sqrt{E_b/N_0}\right) \\ P_{e, \text{BPSK}} = Q\left(\sqrt{\frac{2E_b}{N_0}}\right) \end{cases}$$



Prob that
Standard Gaussian $> u$

$$= \int_u^{\infty} \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt$$

$$Q\left(\sqrt{\frac{2E_b}{N_0}}\right) < Q\left(\sqrt{E_b/N_0}\right)$$

$$\Rightarrow P_{e, \text{BPSK}} < P_{e, \text{ASK}}$$